Toshiba 3G49P/5949 is a hydrogen thyratron for switching service in radar modulator and other pulse applications. It is capable of switching a peak power of 6 MW at an average power of 6 kW.

3G49P/5949 has a hydrogen reservoir which assures freedom from failure due to gas clean-up. The reservoir compensates for the gas consumed during operation and permits the user to adjust the pressure within the tube to the most suitable volume for the particular application.

**GENERAL DATA**

**ELECTRICAL:**

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Minimum</th>
<th>Bogie</th>
<th>Maximum</th>
</tr>
</thead>
<tbody>
<tr>
<td>Cathode ; Indirectly Heated</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Tied to the Heater Midpoint</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Heater Voltage</td>
<td>6.0</td>
<td>6.3</td>
<td>6.6 V</td>
</tr>
<tr>
<td>Heater Current (E=6.3V)</td>
<td>15</td>
<td>18.5</td>
<td>22 A</td>
</tr>
<tr>
<td>Reservoir Heater Voltage (E)</td>
<td>3.0</td>
<td>-</td>
<td>5.5 V</td>
</tr>
<tr>
<td>Reservoir Heater Current (E_{res}=4.5V)</td>
<td>2</td>
<td>-</td>
<td>5 A</td>
</tr>
<tr>
<td>Cathode and Reservoir Heating Time</td>
<td>900</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>Anode Voltage Drop</td>
<td>-</td>
<td>150</td>
<td>250 V</td>
</tr>
<tr>
<td>Anode Delay Time</td>
<td>-</td>
<td>-</td>
<td>1.0 μs</td>
</tr>
<tr>
<td>Anode Current Time Jitter</td>
<td>-</td>
<td>0.005</td>
<td>0.01 μs</td>
</tr>
</tbody>
</table>

* The information contained herein is presented only as a guide for the applications of our products. No responsibility is assumed by TOSHIBA for any infringements of patents or other rights of the third parties which may result from its use. No license is granted by implication or otherwise under any patent or patent rights of TOSHIBA or others.

* The information contained herein may be changed without prior notice. It is therefore advisable to contact TOSHIBA before proceeding with the design of equipment incorporating this product.
MECHANICAL:

Dimensions:
- Overall Length
- Maximum Diameter

Base Number:
- Cap
- Base

Recommended Socket:
- Cap
- Base

Base Connections
Coning (2)

Mounting Position
See Outline Drawing

Net Weight (Approx.)
860 g

RATINGS

ABSOLUTE MAXIMUM:

Maximum Peak Anode Voltage (3):
- Inverse
- Forward 5% epy

Minimum Supply Voltage
5,000 V

Negative Grid Voltage (Before Conduction)
450 V

Maximum Anode Current:
- Peak
- Average
- RMS (4)

Averaging Time
1 cycle

Maximum Rate of Rise of Anode Current
2,500 A/ s

Pulse Repetiting Rate (prr)(5)
2,000 pps

Operation Factor (6)
6.25 × 10^9

Pulse Duration
6 μs

Ambient Temperature Limits
-55 °C to +75 °C

Altitude
3,000 m

GRID DRIVE(7):

Grid Trigger Voltage (Peak)
550 ~ 1,000 V

Maximum Rise Time
0.25 μs

Minimum Grid Pulse Duration
2 μs

Grid Drive Circuit Impedance
50 ~ 200 Ω
Notes (1) The optimum reservoir voltage for operation at maximum tube voltage, maximum peak and average tube currents, and at a repetition corresponding to the rated operation factor is inscribed on the base of the tube, and must be held within ±5 percent. Applications involving operation at other conditions will necessitate the redetermination of the optimum reservoir voltage.

(2) Cooling of anode lead by forced convection permissible, but there shall be no air blast directly on the bulb.

(3) Instantaneous starting is not recommended. However, in case where it is necessary to apply anode voltage instantaneously, the maximum permissible forward starting voltage is 18,000 volts peak. The power-supply filter should be designed to limit the rate of application of this voltage to 450,000 volts per second. The minimum inverse anode voltage permissible is 5 percent of the peak forward voltage and the maximum is 5000 volts during the first 25 microseconds following the anode pulse exclusive of a spike of 0.05 microsecond maximum duration.

(4) The root mean square anode current shall be computed as the square root of the product of peak current (ib) and the average current (Ib), i.e.

\[ I_{\text{rms}} = \sqrt{ib \times Ib} \]

(5) prr (pulse repetiting rate) depends on both peak forward anode voltage epy (V) and peak anode current ib (A). The figure given above is an example of epy and ib against maximum ratings. Actually, the design should be made within the limit of epy (V) \[ \times \text{prr (pps)} \times \text{ib (A)} \leq \text{Operation Factor} \]
Notes (6) Operation factor = epy (peak forward anode voltage) \times ib (peak anode current) \times prr (pulse repetition rate).

(7) Driver pulse measured at tube socket with the thyratron grid disconnected.

GENERAL OPERATIONAL RECOMMENDATION

1. High Voltage

Operating voltages for power tubes range from several hundred volts to higher than 50,000 volts. Since these voltages can be deadly, equipment must be designed so that one cannot come in contact with high voltage.

2. X-RAY Radiation

High-vacuum tubes operating at voltage higher than 10 kilovolts produce progressively more dangerous X-ray radiation as the voltage is increased. X-ray shielding must be provided on all sides of tubes which operate above 10 kilovolts, to provide adequate protection through the tube's life. If there is any doubt as to the adequacy of shielding, an expert in this field should be contacted to perform an X-ray survey of the equipment.

3. High Temperature

Don't come in contact with the vacuum tubes, not only the period of the operation but also immediately after the removal of all tubes voltages because the temperature of the tube during the operation often exceeds 200°C.
DIMENSIONAL OUTLINE
3G49P/5949

Unit: mm

P: Anode
G: Grid
K: Cathode
H: Heater
HCT: Center of Heater
R: Reservoir