

PHILIPS

Data handbook



Electronic
components
and materials

Electron tubes

Part 4 September 1980

Magnetrons



RATING SYSTEM

(in accordance with IEC Publication 134)

ABSOLUTE MAXIMUM RATING SYSTEM

Absolute maximum ratings are limiting values of operating and environmental conditions applicable to any electronic device of a specified type as defined by its published data, which should not be exceeded under the worst probable conditions.

These values are chosen by the device manufacturer to provide acceptable serviceability of the device, taking no responsibility for equipment variations, environmental variations, and the effects of changes in operating conditions due to variations in the characteristics of the device under consideration and of all other electronic devices in the equipment.

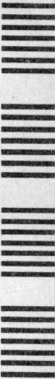
The equipment manufacturer should design so that, initially and throughout life, no absolute maximum value for the intended service is exceeded with any device under the worst probable operating conditions with respect to supply variation, equipment component variation, equipment control adjustment, load variations, signal variation, environmental conditions, and variations in characteristics of the device under consideration and of all other electronic devices in the equipment.

ELECTRON TUBES

PART 4 - SEPTEMBER 1980

MAGNETRONS

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DATA HANDBOOK SYSTEM

Our Data Handbook System is a comprehensive source of information on electronic components, sub-assemblies and materials; it is made up of four series of handbooks each comprising several parts.

ELECTRON TUBES	BLUE
SEMICONDUCTORS	RED
INTEGRATED CIRCUITS	PURPLE
COMPONENTS AND MATERIALS	GREEN

The several parts contain all pertinent data available at the time of publication, and each is revised and reissued periodically.

Where ratings or specifications differ from those published in the preceding edition they are pointed out by arrows. Where application information is given it is advisory and does not form part of the product specification.

If you need confirmation that the published data about any of our products are the latest available, please contact our representative. He is at your service and will be glad to answer your inquiries.

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ELECTRON TUBES (BLUE SERIES)

Starting in 1980, new part numbers and corresponding codes are being introduced. The former code of the preceding issue is given in brackets under the new code.

Part 1	February 1980	T1 02-80 (ET1a 12-75)	Tubes for r.f. heating
Part 2	April 1980	T2 04-80 (ET1b 08-77)	Transmitting tubes for communications
Part 2b	May 1978	ET2b 05-78	Microwave semiconductors and components Gunn, Impatt and noise diodes, mixer and detector diodes, backward diodes, varactor diodes, Gunn oscillators, sub-assemblies, circulators and isolators.
Part 3	June 1980	T3 06-80 (ET2a 11-77)	Klystrons, travelling-wave tubes, microwave diodes
Part 3	January 1975	ET3 01-75	Special Quality tubes, miscellaneous devices
Part 4	September 1980	T4 09-80 (ET2a 11-77)	Magnetrons
Part 5a	October 1979	ET5a 10-79	Cathode-ray tubes Instrument tubes, monitor and display tubes, C.R. tubes for special applications.
Part 5b	December 1978	ET5b 12-78	Camera tubes and accessories, image intensifiers
Part 6	July 1980	T6 07-80 (ET6 01-77)	Geiger-Müller tubes
Part 7a	March 1977	ET7a 03-77	Gas-filled tubes Thyratrons, industrial rectifying tubes, ignitrons, high-voltage rectifying tubes.
Part 7b	May 1979	ET7b 05-79	Gas-filled tubes Segment indicator tubes, indicator tubes, switching diodes, dry reed contact units.
Part 8	July 1979	ET8 07-79	Picture tubes and components Colour TV picture tubes, black and white TV picture tubes, monitor tubes, components for colour television, components for black and white television.
Part 9	June 1980	T9 06-80 (ET9 03-78)	Photo and electron multipliers Photomultiplier tubes, phototubes, single channel electron multipliers, channel electron multiplier plates.

SEMICONDUCTORS (RED SERIES)

Starting in 1980, new part numbers and corresponding codes are being introduced. The former code of the preceding issue is given in brackets under the new code.

Part 1	March 1980	S1 03-80 (SC1b 05-77)	Diodes Small-signal germanium diodes, small-signal silicon diodes, special diodes, voltage regulator diodes (< 1,5 W), voltage reference diodes, tuner diodes, rectifier diodes
Part 2	May 1980	S2 05-80 (SC1a 08-78)	Power diodes, thyristors, triacs Rectifier diodes, voltage regulator diodes (> 1,5 W), rectifier stacks, thyristors, triacs
Part 2	June 1979	SC2 06-79	Low-frequency power transistors
Part 3	January 1978	SC3 01-78	High-frequency, switching and field-effect transistors *
Part 3	April 1980	S3 04-80 (SC2 11-77, partly) (SC3 01-78, partly)	Small-signal transistors
Part 4a	December 1978	SC4a 12-78	Transmitting transistors and modules
Part 4b	September 1978	SC4b 09-78	Devices for optoelectronics Photosensitive diodes and transistors, light-emitting diodes, photocouplers, infrared sensitive devices, photoconductive devices
Part 4c	July 1978	SC4c 07-78	Discrete semiconductors for hybrid thick and thin-film circuits

* Field-effect transistors and wideband transistors will be transferred to S5 and SC3c respectively. The old book SC3 01-78 should be kept until then.

INTEGRATED CIRCUITS (PURPLE SERIES)

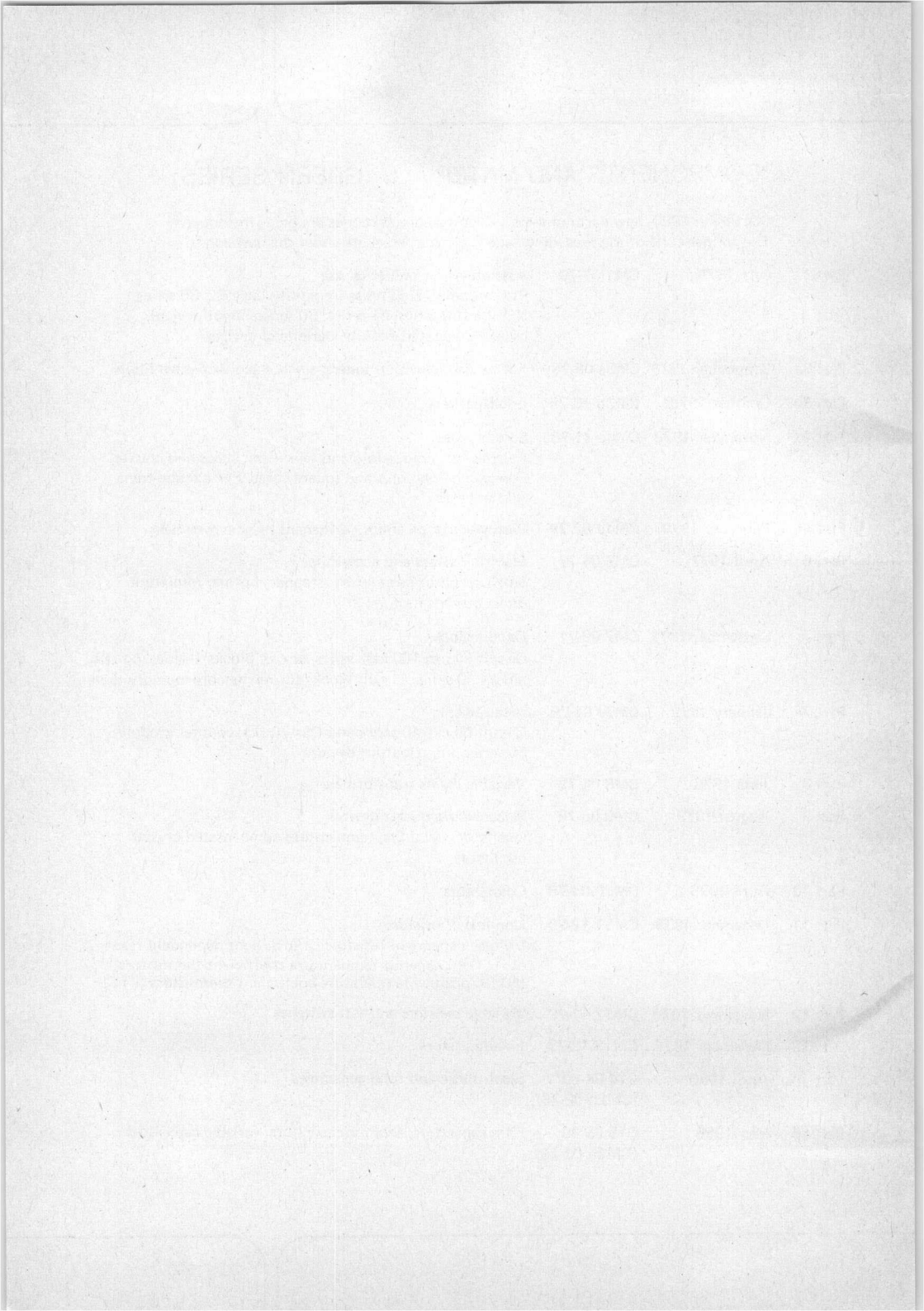
Starting in 1980, new part numbers and corresponding codes are being introduced. The former code of the preceding issue is given in brackets under the new code. Books with the purple cover will replace existing red covered editions as each is revised.

Part 1	May 1980	IC1 04-80 (SC5b 03-77)	Bipolar ICs for radio and audio equipment
Part 2	May 1980	IC2 04-80 (SC5b 03-77)	Bipolar ICs for video equipment
Part 5a	November 1976	SC5a 11-76	Professional analogue integrated circuits
Part 6	October 1977	SC6 10-77	Digital integrated circuits LOCMOS HE4000B family
Part 6b	August 1979	SC6b 08-79	ICs for digital systems in radio and television receivers
Signetics integrated circuits			Bipolar and MOS memories 1979 Bipolar and MOS microprocessors 1978 Analogue circuits 1979 Logic - TTL 1978

COMPONENTS AND MATERIALS (GREEN SERIES)

Starting in 1980, new part numbers and corresponding codes are being introduced. The former code of the preceding issue is given in brackets under the new code.

Part 1	July 1979	CM1 07-79	Assemblies for industrial use PLC modules, high noise immunity logic FZ/30 series, NORbits 60-series, 61-series, 90-series, input devices, hybrid integrated circuits, peripheral devices
Part 3a	September 1978	CM3a 09-78	FM tuners, television tuners, surface acoustic wave filters
Part 3b	October 1978	CM3b 10-78	Loudspeakers
Part 4a	November 1978	CM4a 11-78	Soft Ferrites Ferrites for radio, audio and television, beads and chokes, Ferroxcube potcores and square cores, Ferroxcube transformer cores
Part 4b	February 1979	CM4b 02-79	Piezoelectric ceramics, permanent magnet materials
Part 6	April 1977	CM6 04-77	Electric motors and accessories Small synchronous motors, stepper motors, miniature direct current motors
Part 7	September 1971	CM7 09-71	Circuit blocks Circuit blocks 100 kHz-series, circuit blocks 1-series, circuit blocks 10-series, circuit blocks for ferrite core memory drive
Part 7a	January 1979	CM7a 01-79	Assemblies Circuit blocks 40-series and CSA70 (L), counter modules 50-series, input/output devices
Part 8	June 1979	CM8 06-79	Variable mains transformers
Part 9	August 1979	CM9 08-79	Piezoelectric quartz devices Quartz crystal units, temperature compensated crystal oscillators
Part 10	April 1978	CM10 04-78	Connectors
Part 11	December 1979	CM11 12-79	Non-linear resistors Voltage dependent resistors (VDR), light dependent resistors (LDR), negative temperature coefficient thermistors (NTC), positive temperature coefficient thermistors (PTC)
Part 12	November 1979	CM12 11-79	Variable resistors and test switches
Part 13	December 1979	CM13 12-79	Fixed resistors
Part 14	April 1980	C14 04-80 (CM2b 02-78)	Electrolytic and solid capacitors
Part 15	May 1980	C15 05-80 (CM2b 02-78)	Film capacitors, ceramic capacitors, variable capacitors



GENERAL SECTION

A



List of symbols

Definitions

Waveguides

Flanges

General operational recommendations

Surveys

MAGNETRONS
LIST OF SYMBOLS

a	Anode
B	Bandwidth
C_{ak}	Capacitance between anode and cathode (all other elements being earthed)
d	Distance of voltage standing wave minimum
$\frac{dV_a}{dt}, \frac{\Delta V}{\Delta t_{rv}}$	Rate of rise voltage
f	Filament or heater or frequency
f_{imp}	Pulse repetition rate
H	Magnetic field strength
I_a	Anode current
I_{ap}	Peak anode current
I_f	Filament or heater current
I_{fo}	Filament or heater starting current
I_{fr}	Peak filament or heater starting current
p	Pressure
P_i	Pressure drop of cooling air or cooling water
q	Required air flow or water flow for cooling
T	Temperature
T_a	Temperature of anode or anode block
T_{amb}	Ambient temperature
T_i	Inlet temperature of cooling air or cooling water
t_{imp}	Pulse duration
T_o	Outlet temperature of cooling air or cooling water
t_w	Cathode preheating time
V_a	Anode voltage
V_{ap}	Peak anode voltage
V_f	Filament or heater voltage
V_{fo}	Filament or heater starting voltage
VSWR	Voltage standing-wave ratio
W_{ia}	D.C. anode supply power
W_{ip}	Peak input power
W_o	Output power
W_{op}	Peak output power
δ	Duty factor

LIST
OF
SYMBOLS

$$\frac{\Delta f}{\Delta I_a}$$

$$\frac{\Delta f}{\Delta T}$$

$$\Delta f_p$$

η

λ

Pushing figure of a magnetron

Frequency temperature coefficient

Pulling figure of a magnetron

Efficiency

Wavelength

MAGNETRONS DEFINITIONS

- f The frequency f is measured at maximum instantaneous output power when the tube is coupled into a matched load ($VSWR \leq 1,05$).
- Δf_p The pulling figure Δf_p is the difference between the maximum and minimum frequencies, reached when the phase angle of the load with a VSWR of 1,5 is varied from 0° to 360° .
- I_a The mean anode current I_a is the average anode current through the magnetron as measured with a moving-coil instrument (or equivalent method).
- I_{ap} The peak anode current I_{ap} is the maximum instantaneous anode current value during the current pulse.
- t_{imp} The pulse duration t_{imp} is defined as the time interval between the two points on the current pulse at which the current is 50% of the smooth peak current (see Fig. 1).

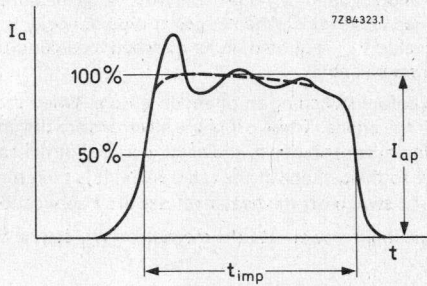


Fig. 1 Current pulse.

The smooth peak is the maximum value of a smooth curve through the average of the fluctuation over the top portion of the pulse.

- t_{rv} The time of rise of voltage t_{rv} is defined as the time interval between points of 20 and 85 per cent of the smooth peak value measured on the leading edge of the voltage pulse.
- t_w The cathode preheating time t_w , also called waiting time, is the minimum period of time during which the heater or filament voltage should be applied before the application of electrode voltages.

DEFINITIONS

dV_a/dt or $\Delta V_a/\Delta t_{rv}$ Unless otherwise stated the rate of rise of voltage dV_a/dt is defined by the steepest tangent to the leading edge of the voltage pulse above 80% of the smooth peak value (see Fig. 2).

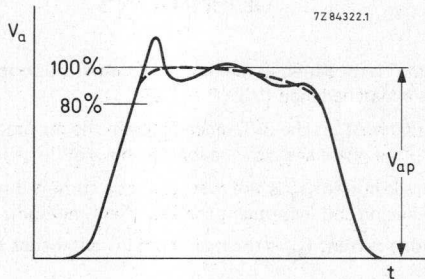


Fig. 2 Voltage pulse.

- V_a The published anode voltage V_a is generally the value measured under d.c. power supply and matched load conditions. When a special type of power is published, then the peak anode voltage value V_{ap} is quoted under matched load conditions (or other conditions of matching where applicable).
- V_{fo} Heater voltage before switching on of anode voltage. When the magnetron oscillates, not all electrons reach the anode. These off-phase electrons are driven back to the cathode. This back bombardment contributes to the heating power of the cathode. In order to maintain the total power to the cathode at the rated value, it is therefore necessary in some cases to reduce or even to switch off the heater voltage after application of high voltage.
- W_{ia} The mean anode input power into the magnetron W_{ia} can be computed approximately from:
- mains input power measurements and correcting for losses in transformer, capacitor, etc.
 - mean anode current times peak anode voltage.
- δ The duty factor δ is the ratio of the pulse duration to the time between corresponding points of two successive pulses.

$$\delta = t_{imp} \text{ (s)} \times f_{imp} \text{ (Hz)}.$$

RECTANGULAR WAVEGUIDE DATA AND DESIGNATIONS

WAVEGUIDE DATA

FREQUENCY RANGE TE ₁₀ -mode 153-IEC* GHz	WAVEGUIDE DESIGNATION				WAVEGUIDE 153-IEC*			WAVEGUIDE 153-IEC*			ATTENUATION in dB/m for copper waveguide		Theoretical C. W. power rating** lowest to highest frequency MW				
	153-IEC*	BRITISH STAND.	RETMA	IAN RG- IU alum.	BAND PREFIX	Width mm	Height mm	Tolerance on width and height ±	Width mm	Height mm	Tolerance on width and height ±	Frequency GHz		Theoretical value	Maximum value		
1.14 — 1.73	R 14	WG 6	WR 650	69	103	L	165.10	82.55	0.33	169.16	86.61	0.20	1.36	0.00522	0.007	12.0	-17.0
1.45 — 2.20	R 18	WG 7	WR 510	—	—	D	129.54	64.77	0.26	133.60	68.83	0.20	1.74	0.00749	0.010	7.5	-11.0
1.72 — 2.61	R 22	WG 8	WR 430	104	105	—	109.22	54.61	0.22	113.28	58.67	0.20	2.06	0.00970	0.013	5.2	-7.5
2.17 — 3.30	R 26	WG 9A	WR 340	112	113	—	86.36	43.18	0.17	90.42	47.24	0.17	2.61	0.0138	0.018	3.4	-4.8
2.60 — 3.95	R 32	WG 10	WR 284	48	75	S	72.14	34.04	0.14	76.20	38.10	0.14	3.12	0.0189	0.025	2.2	-3.2
3.22 — 4.90	R 40	WG 11A	WR 229	—	—	A	58.17	29.083	0.12	61.42	32.33	0.12	3.87	0.0249	0.032	1.6	-2.2
3.94 — 5.89	R 48	WG 12	WR 187	49	95	G	47.55	22.149	0.095	50.80	25.40	0.095	4.73	0.0355	0.046	0.94	-1.32
4.64 — 7.05	R 58	WG 13	WR 159	—	—	C	40.39	20.193	0.081	43.64	23.44	0.081	5.57	0.0431	0.056	0.79	-1.0
5.38 — 8.17	R 70	WG 14	WR 137	50	106	J	34.85	15.799	0.070	38.10	19.05	0.070	6.46	0.0576	0.075	0.56	-0.71
6.57 — 9.99	R 84	WG 15	WR 112	51	68	H	28.499	12.624	0.057	31.75	15.88	0.057	7.89	0.0794	0.103	0.35	-0.46
7.00 — 11.00	—	—	WR 102	—	320	T	25.90	12.95	0.125	29.16	16.21	0.125	—	—	—	0.33	-0.43
8.2 — 12.5	R 100	WG 16	WR 90	52	67	X	22.860	10.160	0.046	25.40	12.70	0.05	9.84	0.110	0.143	0.20	-0.29
9.84 — 15.0	R 120	WG 17	WR 75	—	—	M	19.050	9.525	0.038	21.59	12.06	0.05	11.8	0.133	—	0.17	-0.23
11.9 — 18.0	R 140	WG 18	WR 62	91	—	P	15.799	7.899	0.031	17.83	9.93	0.05	14.2	0.176	—	0.12	-0.16
14.5 — 22.0	R 180	WG 19	WR 51	—	—	—	12.954	6.477	0.026	14.99	8.51	0.05	17.4	0.238	—	0.080	-0.107
17.6 — 26.7	R 220	WG 20	WR 42	53	121	—	10.668	4.318	0.020	12.70	6.35	0.05	21.1	0.370	—	0.043	-0.058
21.7 — 33.0	R 260	WG 21	WR 34	—	—	—	8.636	4.318	0.020	10.67	6.35	0.05	26.1	0.435	—	0.034	-0.048
26.4 — 40.0	R 320	WG 22	WR 28	—	—	—	7.112	3.556	0.020	9.14	5.59	0.05	31.6	0.583	—	0.022	-0.031
32.9 — 50.1	R 400	WG 23	WR 22	—	—	—	5.690	2.845	0.020	7.72	4.88	0.05	39.5	0.815	—	0.014	-0.020
39.2 — 59.6	R 500	WG 24	WR 19	—	—	—	4.775	2.388	0.020	6.81	4.42	0.05	47.1	1.060	—	0.011	-0.015
48.8 — 75.8	R 620	WG 25	WR 15	—	—	—	3.759	1.880	0.020	5.79	3.91	0.05	59.9	1.52	—	0.0063	-0.0090
60.5 — 91.9	R 740	WG 26	WR 12	—	—	—	3.099	1.549	0.020	5.13	3.58	0.05	72.6	2.03	—	0.0042	-0.0060
73.8 — 112.0	R 900	WG 27	WR 10	—	—	—	2.540	1.270	0.020	4.57	3.30	0.05	88.6	2.74	—	0.0030	-0.0041
92.2 — 140.0	R 1200	WG 28	WR 8	—	—	—	2.032	1.016	0.020	4.06	3.05	0.05	111.0	3.82	—	0.0018	-0.0026
114.0 — 173.0	R 1400	WG 29	WR 7	—	—	—	1.651	0.826	—	—	—	—	136.3	5.21	—	0.0012	-0.0017

* IEC Recommendations are obtainable from:
 Central Office of the International Electrotechnical Commission
 1, rue de Varembe
 GENEVA, Switzerland

** based on breakdown of air of 15,000 volts per cm
 (safety factor of approx. 2 at sea level)



FLANGE DESIGNATIONS











FLANGE DESIGNATIONS

FOR WAVEGUIDE 153 - IEC*	FLANGE DESIGNATION					
	PLAIN FLANGE			CHOKE FLANGE		
	154 - IEC	JAN UG /U		154 - IEC	JAN UG /U	
		Brass	Aluminium		Brass	Aluminium
R 14	PDR 14		417A	418A		
R 18	PDR 18					
R 22	PDR 22		435A	437A		
R 26	PDR 26		553	554		
R 32	UER 32 PDR 32 PAR 32 UAR 32		53	584	CAR 32	54A 585A
R 40	UER 40 PDR 40					
R 48	PAR 48 PDR 48 UAR 48 UER 48		149A	407	CAR 48	148C 406B
R 58	PAR 58 PDR 58 UAR 58 UER 58				CAR 58	
R 70	PAR 70 PDR 70 UAR 70 UER 70		344	441	CAR 70	343B 440B
R 84	PBR 84 PDR 84 UBR 84 UER 84		51	138	CBR 84	52B 137B
R 100	PBR 100 PDR 100 UBR 100 UER 100		39	135	CBR 100	40B 136B
R 120						
R 140	PBR 140 UBR 140		419		CBR 140	541A
R 180						
R 220	PBR 220 UBR 220 PCR 220		595	597	CBR 220	596A 598A
R 260	PCR 260					
R 320	PBR 320 PCR 320 UBR 320		599		CBR 320	600A
R 400	PCR 400		383			
R 500	PCR 500 PAR 500					
R 620	PCR 620 PFR 620		385			
R 740	PCR 740 PFR 740		387			
R 900	PCR 900 PFR 900					
R 1200	PCR1200 PFR 1200					

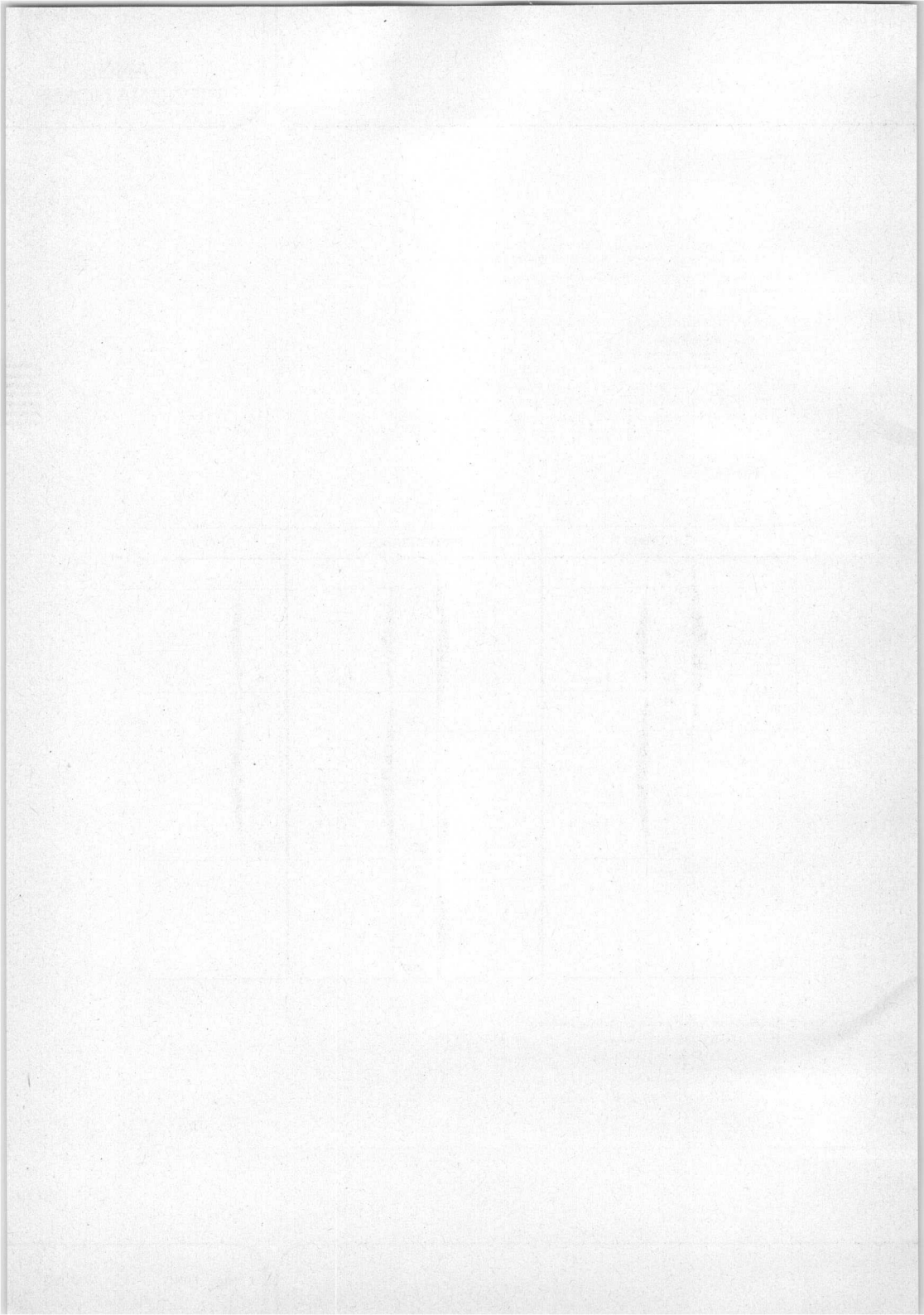
IEC

Waveguide flanges covered by IEC recommendation shall be indicated by a reference number comprising the following information:

- the number of the present IEC publication.
- the letters "IEC".
- a dash.
- a letter relating to the basic construction of the flange
 - P = pressurable
 - C = choke, pressurizable
 - U = unpressurizable
- a letter for the type according to the drawing. Flanges with the same letter and of the same waveguide size can be mated.
- the letter and number of the waveguide for which the flange is designed.

UNPRESSURABLE		PRESSURABLE		CHOKE		
 Type E	14	 Type A	 Type D	14	 Type A	 Type A
	32			32		
	70			70		
	84 100			84 100		
	120	 Type B	 Type C	220	 Type B	 Type B
	320			320		
				500		
				620		
		 Type F	1200			

* IEC Recommendations are obtainable from :
 Central Office of the
 International Electrotechnical Commission
 1, rue de Varembe
 GENEVA, Switzerland



GENERAL OPERATIONAL RECOMMENDATIONS MAGNETRONS

1. GENERAL

1.1 General note

The following directions apply in general to all types of magnetrons. Any deviations for a particular type has been indicated in the relevant data.

1.2 Magnetron definition

A magnetron is a cylindrical high-vacuum diode with a cavity resonator system embedded in the anode. In the presence of suitable crossed electric and magnetic fields the magnetron can be used for the generation of continuous-wave and pulsed signals in the higher frequency bands. The energy available within the cathode/anode zone is coupled out and launched in a coaxial line or waveguide by means of the output probe or antenna.

The magnetron should not be regarded as an independent device, but rather as an integral part of the complete circuit. It follows that the operation of the equipment depends on the degree the various components are matched to each other.

1.3 Magnetrons for communications

In practice the communication magnetrons comprise the pulsed type of magnetrons used as radar transmitters either at a fixed frequency or tunable over a frequency range.

1.4 Magnetrons for microwave heating

Magnetrons for microwave heating are designed for c.w. operation at a frequency of either 2,450 GHz or 2,375 GHz.

1.5 General design considerations

Equipment should be designed around the tube specifications given in the data and not around one particular tube since, due to normal production variations, the electrical and mechanical design parameters may vary around the nominal values.

2. OPERATING CONDITIONS

2.1 Operating characteristics

The values published for these characteristics must be considered as the outcome of measurements on an average magnetron. Individual magnetrons may show a certain spread around the published values, whereas during life the values may be subject to variation.

In the published data the spread and variation during life have in many cases be accounted for by mentioning maximum and/or minimum values of the characteristics.

As the performance of a magnetron is greatly influenced by its load and by the characteristics of the power supply, it is strongly recommended that the magnetron be operated at the published operating conditions only. Whenever it is considered to operate the magnetron at conditions substantially different from those indicated, the tube manufacturer should be consulted.

2.2 Typical characteristics

The characteristics tabulated under this heading give general information on the magnetron independent of any specific kind of operation. The data should be regarded as pertaining to an average magnetron representative of the particular type. When necessary maximum and/or minimum values of the characteristics have been given to include the spread shown by individual samples and the variation which may occur during life.

2.3 Typical operation (recommended operation)

As the performance and lifetime of a magnetron are greatly influenced by the operating conditions (kind of anode supply, load, cooling, etc.), it is recommended that the magnetron be operated under the conditions "Typical Operation". Designers can consult the manufacturer whenever they consider it necessary to operate a certain tube under conditions different from those stated under "Typical Operation".

3. LIMITING VALUES

3.1 Rating system

The limiting values should be used in accordance with the 'Absolute maximum rating system' as defined by IEC publication 134.

3.2 Absolute maximum rating system

Absolute maximum ratings are limiting values of operating and environmental conditions applicable to any electronic device of a specified type as defined by its published data, which should not be exceeded under the worst probable conditions.

These values are chosen by the device manufacturer to provide acceptable serviceability of the device, taking no responsibility for equipment variations, environmental variations, and the effects of changes in operating conditions due to variations in the characteristics of the device under consideration and of all other electronic devices in the equipment.

The equipment manufacturer should design so that, initially and throughout life, no absolute maximum value for the intended service is exceeded with any device under the worst probable operating conditions with respect to supply voltage variation, equipment component variation, equipment control adjustment, load variations, signal variation, environmental conditions, and variations in characteristics of the device under consideration and of all other electronic devices in the equipment.

3.3 Anode voltage, positive and negative

In some cases (e.g. when the filament is not energized) the anode voltage across the tube may be higher than the nominal operating condition, due to the type of power supply employed. The maximum voltage is specified for individual tubes. It is recommended that a suitable spark gap be connected between the filament connectors and the anode (earth) to prevent this maximum rating being exceeded.



4. CATHODE

4.1 A cathode temperature either too high or too low may lead to unsatisfactory operation such as moding and arcing, involving short life and loss of efficiency. During operation the heater voltage should, therefore, be set as near as possible at the prescribed value. Temporary fluctuations should not exceed the tolerances mentioned in the published data of the individual types. The heater voltage should be measured directly on the terminals of the tube.

4.2 Types of cathode

There are two types of cathode in use and each individual tube data specifies which cathode it uses.

(a) *Indirectly heated cathode*

A cathode heated by an element, the heater.

A special construction is the *dispenser cathode*, which is not coated but continuously supplied with suitable emission material from a separate element associated with it.

(b) *Directly heated cathode*, or filamentary cathode.

A hot cathode usually in the form of a thoriated tungsten wire which is heated by current flowing in it.

4.3 Heater supply

The heater should be operated from a.c. (50 Hz or 60 Hz); d.c. may be used when specified in the data of a particular type.

4.4 Heater transformer

It is usual that the magnetron will be operated with the anode at earth potential. Therefore, the heater will be at high potential with respect to earth. Care must be taken to ensure that the secondary winding of this transformer is sufficiently well insulated from the earth and the primary winding.

4.5 Heater/cathode connectors

The connectors specified in the individual data have been designed to give the required electrical and mechanical contact and should be used with the specified magnetron.

The heater voltage should be measured on these connectors.

A coating of high temperature resistant silicone grease is recommended to prevent oxidation. The electrical conductors to the heater/cathode connectors should be flexible to eliminate undue stress on their respective terminals.

4.6 Heater voltage, starting

This is the voltage that should be applied to the heater when the tube is switched on from cold and before the anode voltage is applied.

4.7 Waiting time, or HT delay time

This is the minimum time which must elapse after the heater starting voltage is switched on and before the anode voltage is applied. This is to enable the cathode to reach the operating temperature.

4.8 Heater voltage, operating

This is the voltage at which the heater should be set immediately after applying the anode voltage. For some types information is given of the heater operating voltage related to the mean anode current.

4.9 Heater current

The heater current mentioned in the data is the nominal (typical) value measured when only the starting voltage is applied to the tube and when (thermal) equilibrium is reached. In addition the maximum value of the heater current at the starting voltage is given to assist in transformer design.

4.10 Heater current, peak starting

During switch-on when the heater starting voltage is applied, the peak current through the heater shall not exceed (at any time) the specified value under any condition of supply voltage waveform. In order to assist in the design of the heater transformer, information is also given in the individual data about the cold filament resistance at room temperature.

4.11 Precautions

Filtering of r.f. interference

There are national and international regulations concerning r.f. interference emanating from equipment. Filtering of this interference by capacitive and inductive components associated with the heater connections may be necessary. For tubes having no integral filter these components can influence the proper operation of the magnetron and the tube manufacturer should be consulted for advice and approval.

Fluctuations in supply voltage

Care should be taken to ensure that fluctuations in the supply voltage to the heater do not exceed the published tolerances for the particular type since too high or too low cathode operating temperatures can result in unsatisfactory magnetron operation e.g. moding, arcing, short life, etc.

5. ANODE POWER SUPPLY AND MODULATORS

5.1 General

The dynamic impedance of magnetrons is in general low; thus small variations in the applied voltage can cause appreciable changes in operating current. In the equipment design it is necessary to ensure that such variations in operating current do not lead to operation outside the published limits.

Current changes result in variation of power, frequency and frequency spectrum quality and consequent deterioration of equipment performance. This factor should determine the maximum current change inherent in the equipment design under the worst operating conditions.

For some magnetrons, a special type of power supply is published which is recommended for that tube. Design information of these power supplies may be obtained from the tube manufacturer.

5.2 Pulse type magnetrons

5.2.1 General

To ensure a constant operating condition with a pulsed magnetron the modulator design must provide a pulse, the amplitude of which does not vary to any significant extent from pulse to pulse. Moreover, the energy per pulse delivered to the magnetron, if arcing occurs, should not considerably exceed the normal energy per pulse. Further design precautions depend on the type of modulator employed, and cannot be generalized.

The performance of a magnetron is often a sensitive function of the shape of the voltage pulse that it receives and it is necessary to control four distinct aspects: rate of rise, spike, flatness and rate of fall. In this connection it is important that any observation of the shape of the pulse, either of voltage or of current, supplied by the modulator should be made with a magnetron load and not with a dummy load, because a magnetron acts as a non-linear impedance. Furthermore, a magnetron is likely to be sensitive to a mismatched load.

5.2.2 Rate of rise of voltage

Both maximum and minimum rate of rise of voltage (and sometimes of current) may be specified. The most critical value is that just before and during the initiation of oscillation. Too high or low a rate of rise may accentuate the tendency to moding.

Too high a rate of rise may cause operation in the wrong mode or even failure to oscillate, and either of these conditions may lead to arcing resulting in overheating or to excessive voltages.

Operation at too low a rate of rise of voltage may also cause oscillation in the wrong mode or oscillation in the normal mode at less than full current for an appreciable period and this will cause frequency pushing leading to a broad frequency spectrum.

Generally the rate of rise of voltage between the 20% and 80% points of the peak voltage is nearly linear and provides a good impression of the rate of rise at the onset of oscillation. In other cases, however, it may be necessary to measure the rate of rise above the 80% point.

For accuracy it is advisable to measure the rate of rise by means of a differentiating circuit or an oscilloscope. The total capacitance of the removable measuring device should be small with respect to the total stray capacitance of the modulator output circuit and in most cases not exceed 6 pF.

5.2.3 Spike

It is important that the voltage pulse should not have a high spike on the leading edge. Such a spike may cause the magnetron to start in an undesired mode. Although this operation may not be sustained, the transient condition may lead to destructive arcing. Measures taken to reduce the spike must not also reduce the rate of rise below the specified minimum.

5.2.4 Flat

The top of the voltage pulse should be free from ripple or droop since small changes in voltage cause large current variations resulting in frequency pushing. This leads to frequency modulation of the r.f. pulse and consequent broadening of the spectrum or instability.

5.2.5 Rate of fall

The fall of voltage must be rapid at least to the point where oscillation ceases, to avoid appreciable periods of operation below full current, with the attendant frequency pushing. This point is normally reached when the voltage has fallen to about 80% of the peak value.

Beyond this point a lower rate of fall is generally permissible, but a significant amount of noise will be generated, which may be detrimental to radar systems with a very short minimum range. To prevent noise being generated especially in short-wave radars the voltage tail must decay to zero before the radar receiver recovers.

A fast rate of fall is also important where a magnetron is operated at a high pulse repetition frequency since any diode current which occurs after oscillations have ceased will add appreciably to the mean current and dissipation of the tube.

In certain applications it is desirable to return the cathode to a positive d.c. bias in order to speed up the rate of fall and to prevent diode current being passed during the inter-pulse period.

5.3 C.W. type magnetrons

5.3.1 General

For c.w. types the amount of smoothing required in the h.t. supply depends on the amount of modulation, resulting from operating current variation, that can be tolerated.

5.3.2 Power supplies

General information on power supply design and possibly component design, e.g. transformer design, capacitor, etc. may be supplied by the tube manufacturer. The following power supply types are in use for different tubes:

- (a) unfiltered three-phase
- (b) single-phase full-wave rectification
- (c) unfiltered three-phase half-wave rectification
- (d) unfiltered three-phase full-wave rectification
- (e) LC stabilized
- (f) half-wave doubler, LC stabilized.



6 MICROWAVE PERFORMANCE

6.1 General

The magnetron oscillates in the specified frequency range and the power is coupled out from the anode zone into a waveguide or coaxial line by means of the output probe or antenna. The coupling of the transmission line to the cavity in which the material is being treated has to be carefully designed to ensure that the magnetron operates correctly.

6.2 Load or Rieke diagram

In general the published data include a load diagram, a circle diagram in which, for fixed input conditions, the output power and the frequency change of the magnetron are plotted against the magnitude and the phase (varied over 180 electrical degrees) of the voltage standing-wave ratio representing the load as seen by the magnetron.

In some cases the magnitude of the voltage standing-wave ratio (VSWR) has been replaced by the magnitude of the reflection coefficient (γ) these magnitudes being related by the formulae:

$$\text{VSWR} = \frac{1 + \gamma}{1 - \gamma} \qquad \gamma = \frac{\text{VSWR} - 1}{\text{VSWR} + 1}$$

The load diagram provides information on the behaviour of the magnetron to load conditions.

With a load of bad mismatch and at a particular phase there is a region on the load diagram which is characterized by high power output and convergence of the frequency contours. This region is known as "the sink" and the phase of the load at which the magnetron behaves in this manner is known as "the phase of sink". It is recommended that a tube be operated in the direction of sink. A tube should not be operated in the direction of anti-sink.

6.3 Reference plane

This is the plane from which measurements on microwave phase of the VSWR are made. The reference plane corresponds with the zero λ line in the load diagram. The distance d of an operating point in the diagram gives the position of the minimum of the VSWR with respect to the reference plane. This distance is specified in terms of guide wavelength.

6.4 Voltage standing-wave ratio (VSWR)

6.4.1 VSWR for pulse magnetrons

The anode current range shown in the individual data is related to a VSWR of maximum 1,5 as seen by the magnetron. Operation of the magnetron with a VSWR in excess of 1,5 is not recommended as this may reduce the current range for stable operation and can cause arcing and moding. A ratio near unity will benefit tube life and reliability.

When the length of the transmission line between the magnetron and the load is large compared with the wavelength the maximum permissible value of the VSWR may be reduced due to the occurrence of so-called long line effects. When a long transmission line can not be avoided a load isolator must be inserted between the magnetron and the line.

6.4.2 VSWR for c.w. magnetrons

Under typical operating conditions the tube is operated under specified VSWR and phase conditions. It is most unlikely that these VSWR and phase conditions will be constant and therefore there are two types of VSWR conditions:

(a) *Maximum continuous voltage standing-wave ratio*

This value shall not be exceeded under any conditions of loading, except those specified in para. 6.4.2(b) The value for a certain equipment may be measured with standard cold measuring techniques (perhaps using a specified measuring probe). In some instances this VSWR value may be limited to particular phase regions of operation and outside these regions a lower VSWR value may be specified. This value shall not be exceeded. Incorrect loading of the tube may cause unstable operation.

(b) *Instantaneous maximum voltage standing-wave ratio*

Some equipments use a device for varying the field pattern to produce a more uniform energy distribution in the applicator. This introduces instantaneous VSWR conditions which may exceed the continuous value. With those tubes where it is permissible to exceed the continuous value, the instantaneous value may be up to the specified value for a time of 0,02 s and maximum 20% of the time. It must be followed by a period four times as long during which the VSWR is less than the continuous maximum value.

Under no circumstances should the magnetron be permitted to mode. Amongst other conditions, the moding stability of a magnetron depends on the r.f. loading conditions such as VSWR, phase of reflection and coupling section. It also depends on peak anode current, mean anode current waveform. See para. 7.2.5.

6.5 Fixed reflection elements

Fixed reflection elements are used to alter the operating position of a magnetron concerning magnitude of VSWR and phase. It may be that an equipment is set up for optimum operation at matched load. A fixed reflection element such as described in the data of tube type YJ1160 (VSWR 1,5; phase change 0) alters the operating position to the more efficient position of the phase of sink.

6.6 Microwave accessories

6.6.1 Antenna

In some cases the tube manufacturer can supply data on antennae which can be attached to the output of the tube in order to facilitate coupling into a specific waveguide type. In addition, drawings may be available on specific waveguide coupling assemblies.

6.6.2 R.F. gasket or soft copper washer

Gaskets and washers are provided to ensure adequate and proper electrical and r.f. contact between the tube output structure and the coupling section. When a new tube is installed in an equipment new gaskets and washers must be installed at the same time.

6.6.2 Microwave coupling or launching section

In some instances the coupling section for a certain tube is published. It is recommended that that coupling section be used with that tube. In other cases no specific publication of coupling section is given and the tube manufacturer should be consulted, since drawings of a particular coupling section for a particular waveguide may be available. In some instances a transition to approximately 53,4 Ω coaxial line is published.

7 MEASUREMENTS

7.1 Cold measurements

Cold measurements are carried out to determine the VSWR and phase offered to the magnetron. These measurements should already have been carried out during the development of the applicator.

A measuring probe is available for those magnetrons having an antenna output. This probe replaces the tube in cold measurements. For tubes with a coaxial output structure VSWR measurements can be done with available standard equipment.

The coaxial input of either the measuring probe or applicator can be directly connected to a network analyser to observe VSWR and phase. The reference plane for the load diagram is fixed to the input of the measuring probe or to the coaxial output structure of the tube (see drawings in the respective data publications). Design information for a network analyser for the microwave-heating band is available from the tube manufacturer.

7.2 Hot measurements

Hot measurements are carried out during development, production and servicing of microwave equipment.

7.2.1 Power output in a load

An output power measurement can be made using a defined quantity of water which is heated during a defined time. This check can also be done during production line control and servicing. The power into a cavity is given by the following equation:

$$P_o = q \frac{\Delta T}{14,4} \text{ W}$$

in which q is the quantity of water being heated (cm^3) and ΔT is the temperature rise per minute of the water (K).

7.2.2 Peak heater current

This value must be checked. A suggested method is shown in the following diagram.

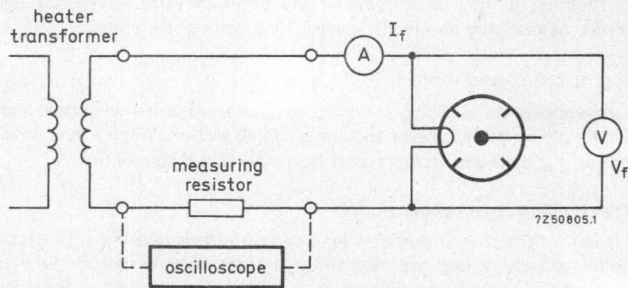


Fig. 1.

7.2.3 Heater voltage

The heater voltage – both starting and stand-by – shall be checked under all possible conditions of mains voltage fluctuations. The values shall remain within the published limits.

7.2.4 Anode current/anode voltage

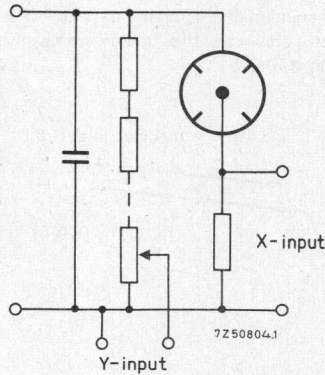


Fig. 2.

The circuit shown above enables the peak anode current I_a , the peak anode voltage V_a and the V_a to I_a characteristic to be displayed on an oscilloscope. The waveforms show whether the peak values are in accordance with the published data and whether under certain load conditions, the magnetron can mode.

In addition the X-input signal can be read on a moving-coil voltmeter and calibrated in mean current.

For measurement of peak anode voltage the following circuit is recommended.

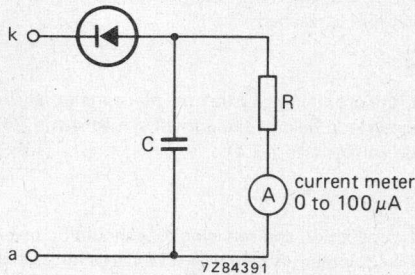


Fig. 3 For 50 Hz operation the RC time is fixed to 1 s.

7.2.5 V_a to I_a characteristic

Excessive VSWR and/or current values may lead to moding of the magnetron which can be detected by displaying the V_a to I_a characteristic on an oscilloscope for the various load conditions. This should be part of production line inspection but should also be checked during field inspection and after tube replacement. The normal V_a to I_a characteristic should be similar to the normal magnetron characteristic as drawn below. The appearance of a second line or parts thereof distinctly above the first line indicates undesired modes of oscillation that can rapidly lead to failure of the tube.

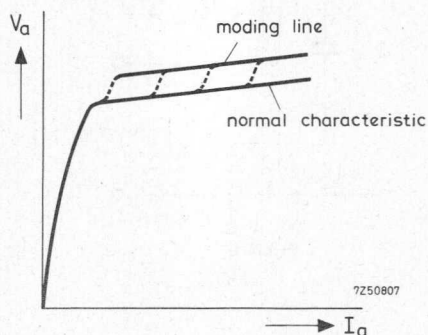


Fig. 4 X-Y display of magnetron characteristic (unfiltered supply).

In such cases the operating conditions, including the VSWR, must be checked and the tube replaced if, under correct operating conditions, moding still occurs.

7.2.6 Seal temperature

The temperature of the specified points shall not exceed the published ratings. If the flow of coolant is reduced or blocked, the thermostat must switch off the equipment before the maximum seal temperature is reached.

7.2.7 Stray magnetic fields

During development, the proximity of other magnetic materials should be checked concerning the influence on the magnetic field of the operating magnetron. This can be detected with the circuit for peak anode voltage (see 7.2.4).

7.2.8 Stray microwave leakage

During development, production and servicing care should be taken to ensure that the microwave leakage from the equipment is below the standards for particular countries concerned. Generally this is a cavity design problem but sometimes energy can leak from the r.f. couplings associated with the tube.

8 HANDLING AND MOUNTING

8.1 General

The magnetron is a delicate electronic tube and has parts made of glass and/or ceramic. Care must be taken in handling, installation, carriage (transport), storage, etc.

8.2 Handling and storage

The original packing should be used for transporting and storing the tube. Shipment of the tube mounted in equipment is not permitted unless specifically authorized by the tube manufacturer.

The strong magnetic field necessary for the operation of the tube must not be weakened permanently. Therefore the tube should NEVER be placed directly on any piece of ferromagnetic material (steel shelves, etc.). When the tubes have to be unpacked, e.g. at an assembly line or for measuring purposes, care should be taken that the tubes are not placed closer to each other than they would be placed when still packed. The storage area may be at normal room temperature and average humidity. Since the heater/filament is sensitive to shocks and vibration, care should be taken when handling and storing tubes such that shocks and vibrations are avoided. The best protection for the tube is the original pack.

8.3 Mounting position

There is a specified mounting position in the individual data. This mounting position normally refers to a certain axis. The specified axis is usually quoted on the outline drawing of the relevant magnetron.

8.4 Fixing or holding points

The fixing/holding/supporting points are generally specified on the outline drawing. The r.f. output coupling of the tube should not be used as the only means of supporting the tube. Adjustment should be available in the supporting brackets in the three directions of freedom to allow for manufacturing tolerances.

8.5 Electrical connections

The individual electrode connections to the tube should be flexible. Special places for the anode (earth) connection are indicated. These places are unpainted and therefore direct earth connections. Other places might not be electrically satisfactory.

8.6 Proximity of other magnets or ferromagnetic materials

The influence of other magnets or ferromagnetic materials on the magnetron magnetic field can result in degraded performance of the tube. Therefore magnets and stray magnetic field generators, either constant or varying, e.g. transformer cores, should be kept away at the specified distance from the magnetron in question.

8.7 Tools and instruments

All tools such as screwdrivers, wrenches, etc. used close to or in contact with the magnetron should be made of non-magnetic materials such as beryllium copper, brass or plastics to avoid unwanted attraction and possible mechanical damage to glass or ceramic parts as well as short-circuiting of the magnetic flux. Sensitive instruments may be influenced or damaged by being positioned too close to the magnetron.

8.8 General precautions

The tube, and particularly the r.f. output coupling, should be kept clean and should be inspected before installation. Any foreign matter, especially metal particles inside the coaxial line and dirt on the ceramic insulation may cause electrical breakdown during operation.

The magnetron should never be held by the cathode radiator because this might result in mechanical damage to the tube. When a magnetron is removed from service every effort should be made to put it back into its original packing.

8.9 Tube cleanliness

The ceramic parts of the input and output structures of the tube must be kept clean during operation. A protective cover of suitable material should be placed over the tube output if the output is inserted directly into a microwave cavity.

9 COOLING

9.1 General

In general, cooling of the filament terminals, anode block and output is necessary and individual data specify the extent to which cooling by air, forced air or water is required. Overheating of the tube due to insufficient cooling may damage the tube. The coupling requirements stated in the individual data refer to magnetrons operated under open bench conditions. In order to keep within the limiting temperatures for anode block, cathode terminal assembly and output seal, where appropriate, it may be necessary in the practical equipment to provide additional coolant on account of high environmental temperatures due to restrictions imposed by the cabinet and to high ambient temperatures at the equipment location.

The residual heat of the cathode on switch-off may raise the seal temperature above its permitted maximum. This danger can be avoided either by continuing the air flow after removal of cathode heater power or by using sufficient air during operation to keep the temperature of the cathode so low that the rise in seal temperature on switch-off can be accommodated.

9.2 Air cooling

Forced air cooling, when required, shall be in accordance with the information given under typical cooling air requirements. In addition a cooling air diagram (if available) indicates the variation of temperature at a certain point and the air pressure drop as a function of air flow rate. It is recommended that the cooling air temperature at the entrance to the tube cooling radiator does not exceed 40 °C. Care should be taken that air filters do not become blocked so that the flow rate is inhibited and the cooling air is heated to a too high temperature by surrounding dissipative components such as mains high-voltage transformer. It is important that the air should not contain dust, moisture and oil. If an air filter is incorporated in the system, allowance must be made for the pressure drop across the filter and ducting when choosing a blower.

9.3 Water cooling

Water cooling in accordance with the specified flow rate should be supplied to the tube. The cooling diagram specifies the inlet water temperature and pressure drop as a function of water flow rate. Closed or open water circuits may be used and the minimum water inlet temperature is 4 °C. Re-circulating systems are preferred, since, apart from saving water, they help to ensure a high standard of purity.

Some of the requirements for satisfactory cooling water are that it should not be corrosive or deposit scale, should not contain insoluble material that might cause blockages and should have a high electrical resistance to prevent electrolysis. Its mineral content and electrical conductivity should therefore be periodically checked, especially when it is not drawn from a circulating system. A non-corrosive water should be low in chlorides, oxygen and carbon dioxide.

Scale formation may be avoided by maintaining a low amount of silica and bicarbonates, especially calcium bicarbonate. No exact figures can be given for impurities as they are interdependent.

The cooling water must also be free from all traces of greasy substances since a small amount may form a dangerous heat barrier on the anode cooler, causing excessive anode temperatures despite an apparently adequate water flow. These greasy or oily films may be removed by repeated flushing of the cooling channels with a domestic liquid detergent or slight soapy water to which a small quantity of industrial alcohol and 33% ammonia has been added (approx.

10 cc/l of each). The cleaning process should be completed by repeated flushing with demineralized water. The cause of such greasy deposits will usually be found elsewhere in the cooling system as the result of, for example, leaky pump glands. After the necessary repairs have been carried out, the whole system must be cleaned in a similar manner to prevent deposits forming again. The cooling water system must be interlocked with all electrical supplies to the tube. As an added safeguard, the interlocks should be activated if the water outlet temperature exceeds the

indicated upper limit. To prevent the tube from running dry in the event of minor leakages in the system, the reservoir should always be above the level of the tube.

9.4 Thermostwitches

A thermostwitch must be used with each magnetron to protect the tube from overheating as a result of failure of the cooling system. The thermostwitch is normally 'closed' and opens when the temperature at the particular reference point exceeds the specified limit. The thermostwitch controls the power supply via a protection circuit and switches it off in the event of overheating.

A thermostwitch must be chosen which opens at the particular specified temperature when mounted at the specified place. In specifying the operating (opening) temperature, the temperature drop across the thermostwitch holder should be taken into account with respect to the temperature limit; under typical conditions this is about 5 K. Details of suggested thermostwitches can be supplied on request.

9.5 Temperature limits

Temperature reference points and maximum temperature limits are specified in the data. Under no circumstances shall these limits be exceeded. As for the limiting temperatures, measurements should be made in the development stage of the equipment, using suitable measuring methods.

9.6 Cooling during stand-by

Some forced-air or water cooling may be necessary during stand-by or starting filament heater voltage operation only. Tests should be carried out during the development of the equipment to ensure that sufficient cooling, even under extreme conditions, is available to keep the temperature of specified places below the maximum limit.

10 ACCESSORIES

10.1 General

The accessories recommended for use with relevant magnetrons should be used whenever possible. If an equipment maker considers it necessary to use other accessories he should ask the opinion of the tube manufacturer.

10.2 Fixed reflection elements

Fixed reflection elements are designed to adapt the operating position (in phase and VSWR) of the magnetron to a better position in the Rieke diagram (load diagram) to obtain more useful results, particularly with respect to power output. These accessories are not supplied by the tube manufacturer but drawings are given to facilitate manufacture if the use of these fixed reflection elements is recommended.

10.3 Gaskets and washers

Gaskets and washers are provided to ensure adequate and proper electrical and r.f. contact between the elements concerned. Generally, when a tube is installed, or re-installed, new gaskets and washers must be used.

10.4 Measuring probe

When available, the measuring probe should be used in place of the tube in development, production and servicing to ensure that the correct microwave impedance (phase and VSWR) is presented to the tube. See 7.1.

SURVEY

type		cooling	W_{op} kW	frequency range GHz
YJ1023		N	20	34,512 to 35,200
YJ1180		FA	200	9,050 X-band
YJ1181		FA	200	9,050 X-band
YJ1180L		FA	200	8,850 X-band
YJ1181L		FA	200	8,850 X-band
YJ1180H		FA	200	9,150 X-band
YJ1181H		FA	200	9,150 X-band
YJ1320		FA	65	16,5 Ku-band
YJ1321		FA	65	16,5 Ku-band
5586		FA	800	2,700 to 2,900
55029		FA	250	9,405 to 9,505
55030		FA	250	9,345 to 9,405
55031/01		FA	250	9,168 to 9,260
55031/02		FA	250	9,260 to 9,345
55032/01		FA	250	9,003 to 9,085
55032/02		FA	250	9,085 to 9,168

COOLING: FA = forced air
N = natural

SURVEY

type		cooling	W_o kW	V_a kV	I_a A	frequency MHz
YJ1160		W	2,5	4,95	0,8	2450
YJ1162		FA	2,5	4,95	0,8	2450
YJ1164		W	2,5	4,95	0,8	2375
YJ1193*		W	6	7,3	1,25	2450
YJ1194*		W	6	7,3	1,25	2375
YJ1280		FA	1,5	5,7	0,38	2450
YJ1441*		FA	2,5	5,5	0,7	2450
YJ1442*		W	3	5,8	0,8	2450
YJ1443*		W	3	5,8	0,8	2375
YJ1481*		FA	1,55	6	0,37	2450
YJ1500*		FA	1,1	4	0,38	2450
YJ1510**		FA	0,265	2,9	0,15	2450
YJ1520*		FA	0,85	4,15	0,3	2450
YJ1521*		FA	0,85	4,15	0,3	2450
YJ1522*		FA	0,85	4,15	0,3	2450
7090**		FA	0,2	1,65	0,2	2450

COOLING: FA = forced air
W = water

* With integral filter
** For diathermy.

MAGNETRONS FOR COMMUNICATIONS

B



MADE IN U.S.A. FOR COMMERCIAL

PULSED MAGNETRON

Packaged magnetron for pulsed service at a fixed frequency.

The YJ1023 incorporates a dispenser type of cathode to ensure a long life. A getter to maintain a high vacuum minimizes any tendency towards arcing, even when the magnetron is taken into operation after a period of storage.

QUICK REFERENCE DATA

Frequency, fixed within the band	f	34,512 to 35,200 GHz
Peak output power	W_{op}	20 kW
Construction		packaged

CATHODE: dispenser type

HEATING: Indirect by a.c. (30 to 1650 Hz) or d.c.

If d.c. is used the terminal f, k must have positive polarity.

Heater voltage, starting	V_{fo}	$4,5 \text{ V} \pm 10\%$
Heater current at $V_f = 4,5 \text{ V}$	I_f	$3,6 \text{ A} \pm 0,7 \text{ A}$
Heater current, peak starting	I_{fp}	max. 8 A
Cold heater resistance	R_{fo}	$> 0,16 \Omega$
Waiting time	t_w	min. 3 min

At an anode input power of more than 21 W the heater voltage must be reduced immediately after the application of anode input power in accordance with Fig. 5.

TYPICAL CHARACTERISTICS

notes

Stable range: peak anode current	I_{ap}	6 to 12 A	
Anode voltage, peak, at $I_{ap} = 9$ A	V_{ap}	12 to 14 kV	
Frequency temperature coefficient	$\frac{\Delta f}{\Delta T_a}$	-1 MHz/K	
Pulling figure (VSWR = 1,5)	Δf_p	40 MHz	
Pushing figure	$\frac{\Delta f}{\Delta I_a}$	< 4 MHz/A	
Distance of voltage standing wave minimum	d	0,25 to 0,40 λ_g = 2,6 to 4,4 mm	1
Capacitance, anode to cathode	C_{ak}	6 pF	

LIMITING VALUES (Absolute maximum rating system)

Pulse duration	t_{imp}	max. 0,2 μs	2
Pulse repetition rate	f_{imp}	max. 7200 p.p.s.	
Duty factor	δ	max. 0,0015	
Anode current, peak	I_{ap}	max. 12 A min. 6 A	2
Anode current, mean	I_a	max. 6 mA min. 3 mA	
Input power, peak	W_{iap}	max. 150 kW	
Input power, mean	W_{ia}	max. 75 W	
Rate of rise of anode voltage at $t_{imp} = 0,1 \mu s$	$\frac{dV_a}{dt}$	60 to 200 kV/ μs	2
Voltage standing-wave ratio	VSWR	max. 1,5	
Anode temperature	T_a	max. 150 °C	3
Cathode and heater terminal temperature	T	max. 150 °C	
Pressure, input and output	p	max. 30 N/cm ² abs min. 6 N/cm ² abs	

Notes

1. The distance of the VSW minimum outside the tube is between 0,25 and 0,4 λ_g (2,6 and 4,4 mm) with respect to reference plane A (see Fig. 3), measured with a standard cold test technique at the frequency of the oscillating magnetron operating into matched load.
2. See pulse definitions page B6.
3. Measured on the anode block between the second and third cooling fin.

OPERATING CHARACTERISTICS

			notes
Heater voltage, running	V_f	3 V	
Pulse duration	t_{imp}	0,14 μ s	2
Pulse repetition rate	f_{imp}	3600 p.p.s.	
Duty factor	δ	0,0005	
Anode voltage, peak	V_{ap}	12 to 14 kV	2
Rate of rise of anode voltage	$\frac{dV_a}{dt}$	100 kV/ μ s	
Anode current, mean	I_a	4,5 mA	
Anode current, peak	I_{ap}	9 A	2
Output power, mean	W_o	10 W	
Output power, peak	W_{op}	20 kW	

The manufacturer should be consulted whenever it is considered to operate the magnetron at conditions substantially different from those given above.

COOLING

Radiation and convection.

For normal operating conditions no additional cooling of the magnetron will be required to keep the temperature of the anode block and of the cathode and heater terminals below 150 °C.

To safeguard the magnetron against overheating, provision is made for mounting a thermoswitch, e.g. type 3BTL6 (Texas Instruments Inc.). This switch should become operative at a temperature of 140 °C at its mounting plate.

PRESSURE

The magnetron need not be pressurized when operating at atmospheric pressure. To prevent arcing, the pressure must exceed 6 N/cm² (Absolute maximum limit).

STARTING A NEW MAGNETRON

This magnetron is provided with a getter, so that ageing (of a new magnetron or of a magnetron that has been idle or stored for a period of time) will not be necessary in most cases. If, however, the magnetron is put into operation and some sparking and instability occur incidentally, it is recommended that the anode current gradually be increased and to operate the magnetron with reduced input for 15 to 30 minutes. After this period sparking usually ceases.

CIRCUIT NOTES

- To prevent heater burn-out the negative high-voltage pulse must be applied to the common heater/cathode terminal f, k.
- If no load isolator is inserted between the magnetron and the transmission line, the latter should be as short as possible to prevent long-line effects. Under no circumstances should the magnetron be operated with a load giving a VSWR exceeding 1.5. A ratio kept near unity will benefit tube life and reliability.
- The modulator must be so designed that, if arcing occurs, the energy per pulse supplied to the magnetron does not considerably exceed the normal energy per pulse. Modulators of the pulse-forming-network discharge type usually satisfy this requirement.
- It is required to bypass the magnetron heater with a 1000 V rated capacitor of minimum 4 nF directly across the heater terminals.
- Any diode current flowing during the intervals between the pulses should be taken into account when the peak anode current is calculated from the measured mean anode current. The occurrence of this diode current can be avoided by preventing the anode voltage becoming positive with respect to the cathode during the intervals between the pulses.
- The unwanted noise that may occur when the anode pulse voltage drops below the value required for oscillation can be minimized by making the trailing edge of the voltage pulse as steep as possible.

PULSE CHARACTERISTICS AND DEFINITIONS

The smooth peak value (V_{ap} or I_{ap}) of a pulse is the maximum value of a smooth curve through the average of the fluctuation over the top portion of the pulse as shown in the figures below.

The rate of rise of anode voltage is defined by the steepest tangent to the leading edge of the voltage pulse above 80% of the smooth peak value (Fig. 1). Any capacitance used in a removable viewing system shall not exceed 6 pF. For calculating the rate of rise of anode voltage the 100% value must be taken as 13 kV.

The pulse duration (t_{imp}) is the time interval between the two points on the current pulse at which the current is 50% of the smooth peak current (Fig. 2).

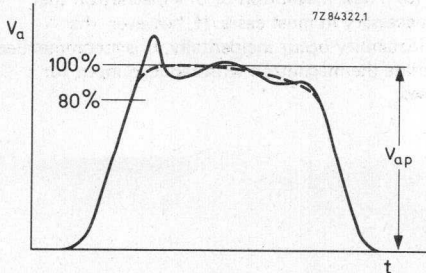


Fig. 1.

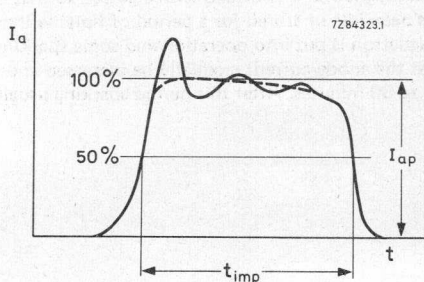


Fig. 2.

The current pulse must be substantially square and the ripple over the top portion of the current pulse must be kept as small as possible to avoid unwanted frequency modulation due to pushing effects. The spike on the top portion of the pulse must be small to avoid excessive peak pulse current. The leading edge of the pulse must be free from irregularities.

STORAGE, HANDLING AND MOUNTING

The original packing should be used for the transport of the magnetron.

The magnetron should never be held by the heater-cathode stem. Rough treatment of the metal envelope and of the cooling fins may impair the electrical characteristics or may result in loss of vacuum.

When storing, the packaged magnetrons should be kept not less than 15 cm (6 inches) apart, to prevent a decrease of field strength of the magnetron magnet as a result of interaction with the adjacent magnets. If the magnetrons are stored in their original inner container, no special precautions need be taken with regard to the distance apart. If the magnetrons are stored without their inner container, they should be stored in non-magnetic surroundings e.g. on wooden shelves. If the tubes cannot be stored at normal temperature they must be stored in protective packing.

When handling and mounting the magnetron, a minimum distance of 5 cm (2 inches) between the magnet and any piece of magnetic material should be maintained to avoid mechanical shocks to the magnet or to the glass of the heater-cathode stem. For this reason it is required that non-magnetic tools be used during installation, such as non-magnetic stainless steel, brass, beryllium copper and aluminium. Furthermore, the user should be aware of the detrimental influence of the strong magnetic field around the magnet on watches and other precision instruments nearby.

Mounting of the magnetron should be accomplished by means of its mounting flange. The tube should in no case be supported by the coupling to the waveguide output flange alone.

A dust-cover is placed on the output flange to keep its opening closed until the tube is mounted into the equipment. Before putting the magnetron into operation, the user should make sure that the output waveguide and the recessed cathode terminal are entirely clean and free from dust and moisture.

MECHANICAL DATA

Mounting position	any
Net mass	1,9 kg
Waveguide output system	153 IEC – R320 = RG-96/U
Waveguide coupling system	Z8 300 16

To facilitate this coupling the components Z8 300 17 and Z8 300 19 have been fixed permanently to the magnetron.

Cathode connector Jettron 91 – 010 or equivalent

The mounting flange and the waveguide output system are designed to permit the use of pressure seals. See also under "Limiting Values".



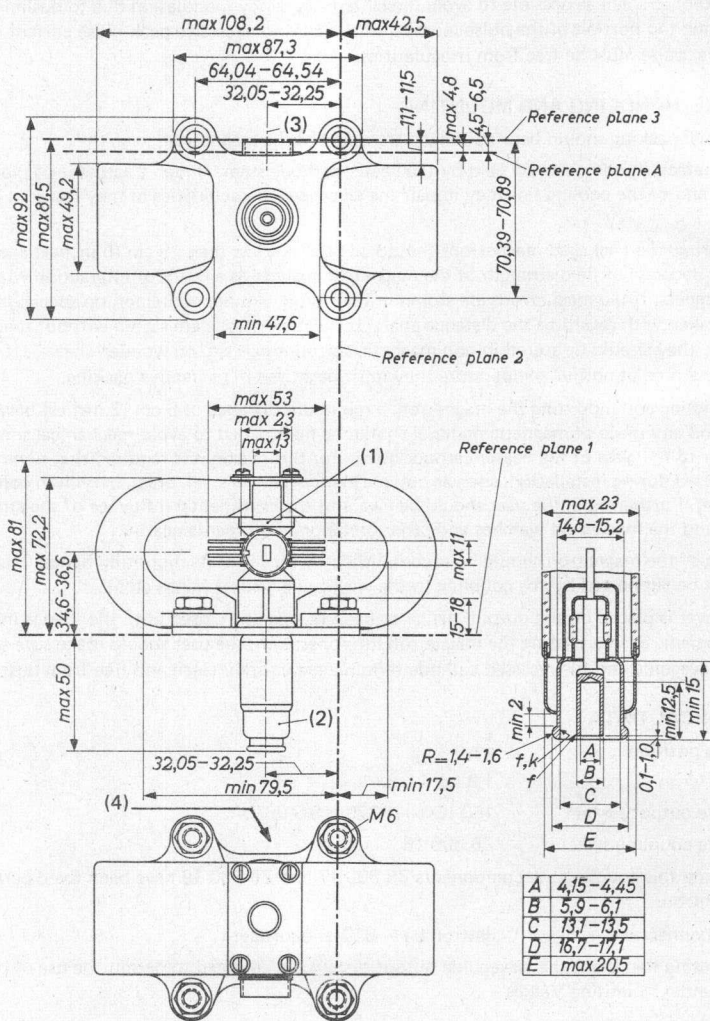


Fig. 3.

- (1) Inscription of serial number.
- (2) The axis of the common heater-cathode terminal is within a radius of 1,5 mm from the centre of the mounting plate. The eccentricity of the axis of the inner cylinder of the heater terminal with respect to the axis of the inner cylinder of the common heater-cathode terminal is max. 0,125 mm.
- (3) Centre of waveguide.
- (4) Plate for mounting a thermoswitch, see detail Fig. 4.

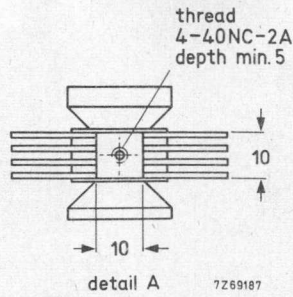


Fig. 4.

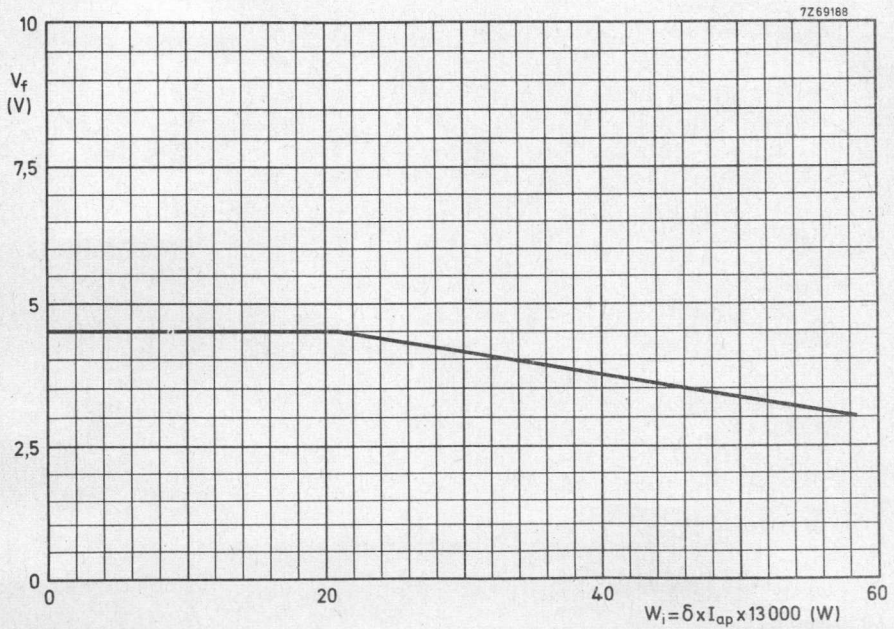
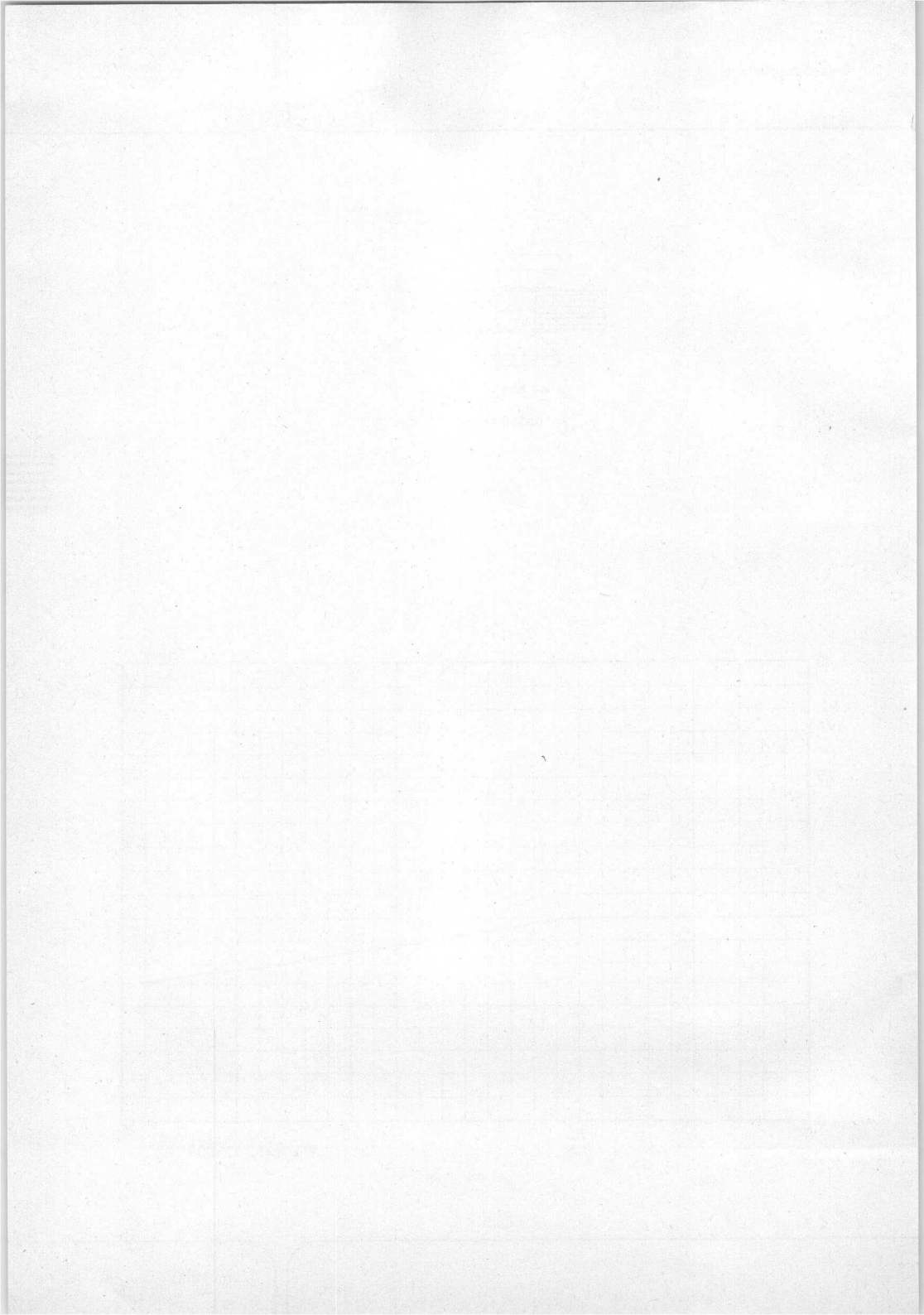


Fig. 5.



PULSED MAGNETRON

Frequency agile air cooled packaged magnetron for use as a pulsed oscillator in navigational, search, and fire-control radar systems. It can be pulsed by a hard tube, line type or magnetic modulator. The magnetron type YJ1181 provides in addition to frequency agile operation the possibility of selecting any fixed frequency within its band (e.g. for MTI).

QUICK REFERENCE DATA

type	nominal centre frequency GHz	Δf_{\min}^* GHz	Δf_{\max}^* GHz	agile frequency excursion MHz	peak output power kW
YJ1180, YJ1181	9,050	8,925 – 9,175	8,7 – 9,5	450	200
YJ1180L, YJ1181L	8,850	8,725 – 8,975	8,5 – 9,3		
YJ1180H, YJ1181H	9,150	9,025 – 9,275	8,8 – 9,6		

construction

packaged

HEATING: indirect by a.c. (30 to 1650 Hz) or d.c.

Heater voltage, starting and stand-by

V_{fo} 13,75 V \pm 10%

Heater current at $V_f = 13,75$ V

I_f 3,15 A \pm 0,35 A

Peak heater starting current

I_{fp} max. 12 A

Cold heater resistance

R_{fo} > 0,8 Ω

Waiting time

t_w min. 150 s

Immediately after the high voltage has been applied, the heater voltage must be reduced in accordance with the formula:

$$V_f = 14,8 \left(1 - \frac{I_a}{41,5} \right) V \quad (\text{see also Fig. 4})$$

where I_a (in mA) = duty factor x peak anode current.

When $I_a \leq 3$ mA the heater voltage must be 13,75 V.

* Δf_{\min} is the frequency band that is at least covered by any individual magnetron of the same type.

Δf_{\max} represents the outer limits for possible oscillation frequencies for any individual magnetron of the same type.

TYPICAL CHARACTERISTICS

Peak anode voltage at $I_{ap} = 26,5$ A	V_{ap}	21 to 24 kV
Pulling figure	Δf_p	< 15 MHz
Pushing figure	$\frac{\Delta f}{\Delta I_a}$	< 0,5 MHz/A
Passive oscillation frequency difference	Δf	9 to 16 MHz*
Frequency temperature coefficient	$\frac{\Delta f}{\Delta T_a}$	< -0,5 MHz/°C
Capacitance; anode to cathode	C_{ak}	< 20 pF

LIMITING VALUES (Absolute maximum rating system)

Pulse duration **	t_{imp}	max. 1,60 μs min. 0,13 μs
Duty factor	δ	max. 0,0011
Heater voltage	V_f	max. 15 V
Peak heater starting current	I_{fp}	max. 12 A
Anode current, peak**	I_{ap}	max. 27,5 A min. 15,0 A
Anode voltage, peak**	V_{ap}	max. 24 kV
Anode input power, mean	W_{ia}	max. 660 W
Anode input power, peak	W_{iap}	max. 660 kW
Rate of rise of anode voltage for pulse duration < 0,15 μs	$\frac{dV_a}{dt}$	max. 205 kV/ μs min. 60 kV/ μs
for pulse duration > 0,15 μs	$\frac{dV_a}{dt}$	max. 180 kV/ μs min. 60 kV/ μs
Voltage standing-wave ratio	VSWR	max. 1,5
Anode temperature at measuring point (see outline drawing)	T_a	max. 160 °C
Cathode and heater terminal temperature at measuring point (see outline drawing)	T	max. 165 °C
Input pressurization	p	max. 30 N/cm ² abs min. 8 N/cm ² abs
Output pressurization	p	max. 30 N/cm ² abs min. 10 N/cm ² abs

* The passive oscillation frequency difference will not vary more than 4 MHz for each individual tube over its frequency band.

** See "Pulse characteristics and definitions".

OPERATING CHARACTERISTICS

Pulse duration*	t_{imp}	0,15	1,0	1,5 μs
Pulse repetition rate	f_{imp}	2200	1000	670 p.p.s.
Duty factor	δ	0,00033	0,001	0,001
Peak anode voltage*	V_{ap}	22,5	22,5	22,5 kV
Rate of rise of voltage*	$\frac{dV_a}{dt}$	180	150	150 kV/ μs
Peak anode current*	I_{ap}	26,5	26,5	26,5 A
Heater voltage, running	V_f	11,7	5,3	5,3 V
Output power, mean	W_o	66	200	200 W
Output power, peak	W_{op}	200	200	200 kW

The manufacturer should be consulted whenever it is considered operating the magnetron at conditions substantially different from those given above.

COOLING

An adequate flow of cooling air should be directed through the ducts in the magnetron to keep the temperature of the anode block below 120 °C under any condition of operation. If necessary, the heater/cathode terminal should also be cooled to keep its temperature below 165 °C. An air flow of approximately 0,85 m³/min is normally sufficient.

PRESSURE

The mounting flange and the output waveguide flange are designed to permit the use of pressure seals. The minimum pressure to prevent cumulative electrical breakdown in the output coupling shall be 10 N/cm² abs. See also under "Limiting values".

LIFE

The life of the magnetron depends on the operating conditions, and is expected to be longer at shorter pulse durations.

AGEING OF MAGNETRON

It is recommended that magnetrons kept in store are re-aged every 12 to 24 months. Recommended ageing procedure available on request.

* See "Pulse characteristics and definitions".

STARTING A NEW MAGNETRON

When a magnetron is taken into operation for the first time some sparking and instability may occur. It is recommended that the magnetron be started in the following way:

1. Apply heater voltage (13,75 V) for at least 150 s.
2. Raise the anode current gradually, preferably starting at the shortest available pulse duration, until one half of the normal operating output power is obtained. Operate the magnetron at this power level at the lowest tunable frequency. Take care that the heater voltage is reduced in accordance with the heater voltage cut-back schedule.
3. As soon as the magnetron operates stably, gradually raise the anode current until the normal operating conditions are reached. If sparking occurs, stop raising anode current until the magnetron operates stably again. Care should be taken that the maximum ratings are not exceeded.
4. Repeat the procedure 1, 2 and 3 with the magnetron operating in the frequency agile mode.

After this running-in schedule the magnetron can be put into use at the normal operating conditions.

TUNING MECHANISM

The tuning is achieved by rotating a tuner inside the vacuum part of the magnetron. This tuner is magnetically coupled to the tuner motor and rotates with the same speed as the motor. The magnetron is tuned over one complete cycle when the motor shaft is rotated $1/16$ rev. ($22,5^\circ$). The tuner can rotate in both clockwise and counter-clockwise directions depending on the electrical connection of the tuner motor. See below for information on the connection of the tuner motor. It is advised to run the tuning motor normally only during oscillation conditions.

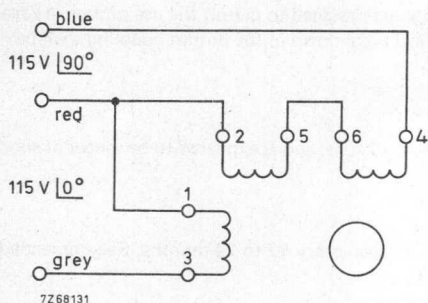


Fig. 1 Two-phase, 400 Hz supply 90° shift between phases:

Phase voltage	115 V
Input power	9 W/phase

FREQUENCY LOCK (YJ1181 only)

The YJ1181 is provided with a tuner lock added to the motor, so that it can be used for frequency agile or fixed frequency operation.

Agile tuning is only achieved when the motor rotates clockwise. Fixed frequency operation is obtained by reversing the direction of rotation of the motor axis. In this direction a built-in mechanical device is actuated that locks the motor shaft. This lock keeps the tuner in a defined angular position, corresponding to a predetermined frequency. This angular position can be adjusted by means of a shaft protruding from the motor housing (see outline drawing).

CIRCUIT NOTES

- In order to prevent heater burn-out the negative high-voltage pulse must be applied to the common heater/cathode terminal f(k).
- The magnetron is used in combination with an F.T.L.O. (fast-tuned local oscillator) including a circulator which provides load isolation at the same time. The distance between circulator and magnetron should be as short as possible. Under no circumstances should the magnetron be operated with a load giving a VSWR exceeding 1,5 A ratio kept near unity will benefit tube life and reliability.
- The modulator must be so designed that, if arcing occurs, the energy per pulse supplied to the magnetron does not considerably exceed the normal energy per pulse.
- It is required to bypass the magnetron heater with a 1000 V rated capacitor of minimum 4 nF directly across the heater terminals.
- Any diode current flowing during the intervals between the pulses should be taken into account when the peak anode current is calculated from the measured mean anode current. The occurrence of this diode current can be avoided by preventing the anode voltage becoming positive with respect to the cathode during the intervals between the pulses.
- The unwanted noise that may occur when the anode pulse voltage drops below the value required for oscillation can be minimized by making the trailing edge of the voltage pulse as steep as possible.

PULSE CHARACTERISTICS AND DEFINITIONS

The smooth peak value (V_{ap} or I_{ap}) of a pulse is the maximum value of a smooth curve through the average of the fluctuation over the top portion of the pulse as shown in the figures below.

The rate of rise of anode voltage is defined by the steepest tangent to the leading edge of the voltage pulse above 50% of the smooth peak value (Fig. 2). Any capacitance used in a removable viewing system shall not exceed 6 pF. For calculating the rate of rise of anode voltage the 100% value must be taken as 22,5 kV.

The pulse duration (t_{imp}) is the time interval between the two points on the current pulse at which the current is 50% of the smooth peak current (Fig. 3).

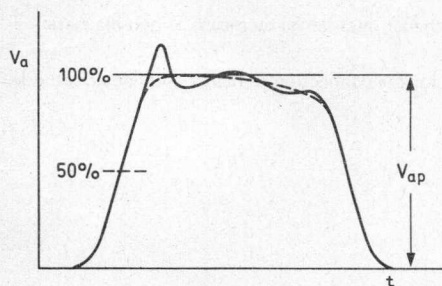


Fig. 2.

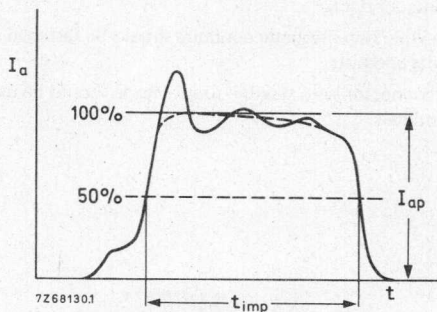


Fig. 3.

The current pulse must be substantially square and the ripple over the top portion of the current pulse must be kept as small as possible to avoid unwanted frequency modulation due to pushing effects. The spike on the top portion of the pulse must be small to avoid excessive peak pulse current. The leading edge of the pulse must be free from irregularities.

STORAGE, HANDLING AND MOUNTING

The original packing should be used for the transport of the magnetron.

The magnetron should never be held by the heater/cathode stem. Rough treatment of the envelope and of the cooling fins may impair the electrical characteristics or may result in loss of vacuum.

When storing, the packaged magnetrons should be kept not less than 15 cm (6 in) apart, to prevent a decrease of field strength of the magnetron magnet as a result of interaction with the adjacent magnets. If the magnetrons are stored in their original inner container, no special precautions need be taken with regard to the distance apart. If the magnetrons are stored without their inner container, they should be stored in non-magnetic surroundings e.g. on wooden shelves. If the tubes cannot be stored at normal temperature they must be stored in protective packing.

When handling and mounting the magnetron, a minimum distance of 5 cm (2 in) between the magnet and any piece of magnetic material should be maintained to avoid mechanical shocks to the magnet or to the glass of the heater/cathode stem. For this reason it is required that non-magnetic tools be used during installation, such as non-magnetic stainless steel, brass, beryllium copper and aluminium. Furthermore, the user should be aware of the detrimental influence of the strong magnetic field around the magnet on watches and other precision instruments nearby.

A dust-cover is placed on the output flange to keep its opening closed until the tube is mounted into the equipment. Before putting the magnetron into operation, the user should make sure that the output waveguide and the recessed cathode terminal are entirely clean and free from dust and moisture.

The magnetron should be mounted by means of its mounting flange; it should be secured to the chassis by means of four bolts (thread 1/4"-20NC-2). Special attention has been given to the flatness of the mounting flange, so that, if necessary, a pressure seal can be made for the input assembly. Consequently, the mounting surface should be sufficiently flat to avoid deformation of the flange. Furthermore, the mounting should be sufficiently flexible and adjustable so that no strain is exerted on the output system when the mounting bolts are tightened and when the output system is being coupled to the waveguide in the equipment.

To fasten the magnetron output flange to the 153 IEC-R 84 waveguide, a choke flange 154 IEC-CBR 84 should be used. The latter flange must be modified by reaming the four mounting holes with a 4,3 mm drill. It can then be fastened to the magnetron output flange by means of four M4 bolts. This connection should be such that a reliable contact is established in order to avoid arcing and other bad contact effects.

Flexible non-magnetic conduits should be fastened to the air inlet flange by means of non-magnetic bolts and nuts.

A connector with flexible supply leads should be used for the connection of heater and heater/cathode terminals.

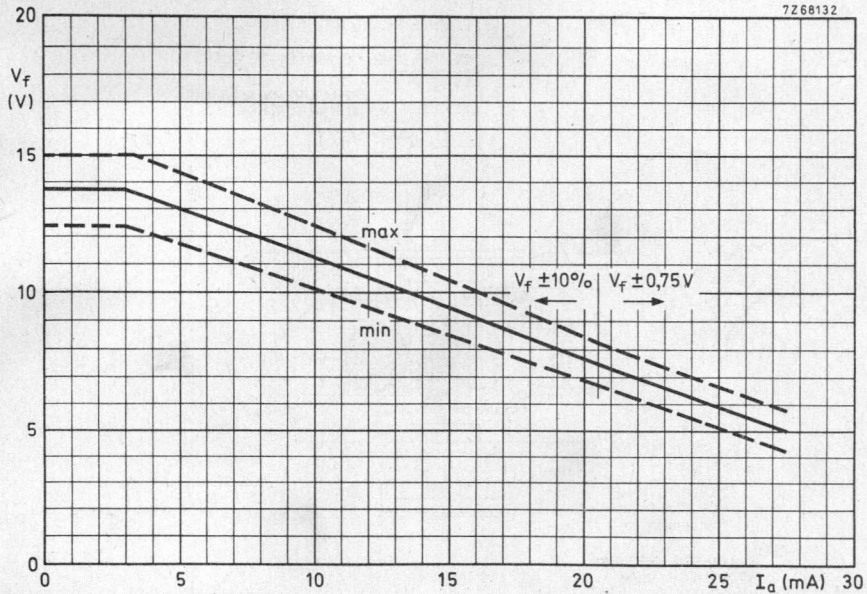


Fig. 4 Heater voltage reduction curve.

MECHANICAL DATA

Net mass: approx. 7 kg
 Mounting position: any
 Support: mounting flange

The waveguide output has been designed for coupling to standard rectangular waveguide 153 IEC-R 84.

Waveguide output flange: couples to 154 IEC-CBR 84 flange

Tuner speed: 4500 revolutions/minute

One revolution of the tuner shaft corresponds to 16 full tuning cycles. One cycle consists of a quasi-sinusoidal excursion through the entire tuning range and return.

THERMOSWITCH

Mounted on tube, see outline drawing.

Contact	S.P.S.T. normally closed
Opening temperature	110 to 122 °C
Closing temperature	approx. 100 °C
Contact ratings 220 V(a.c.), 1,5 A; 220 V(d.c.), 0,4 A	non-inductive load
Leads	black, 2

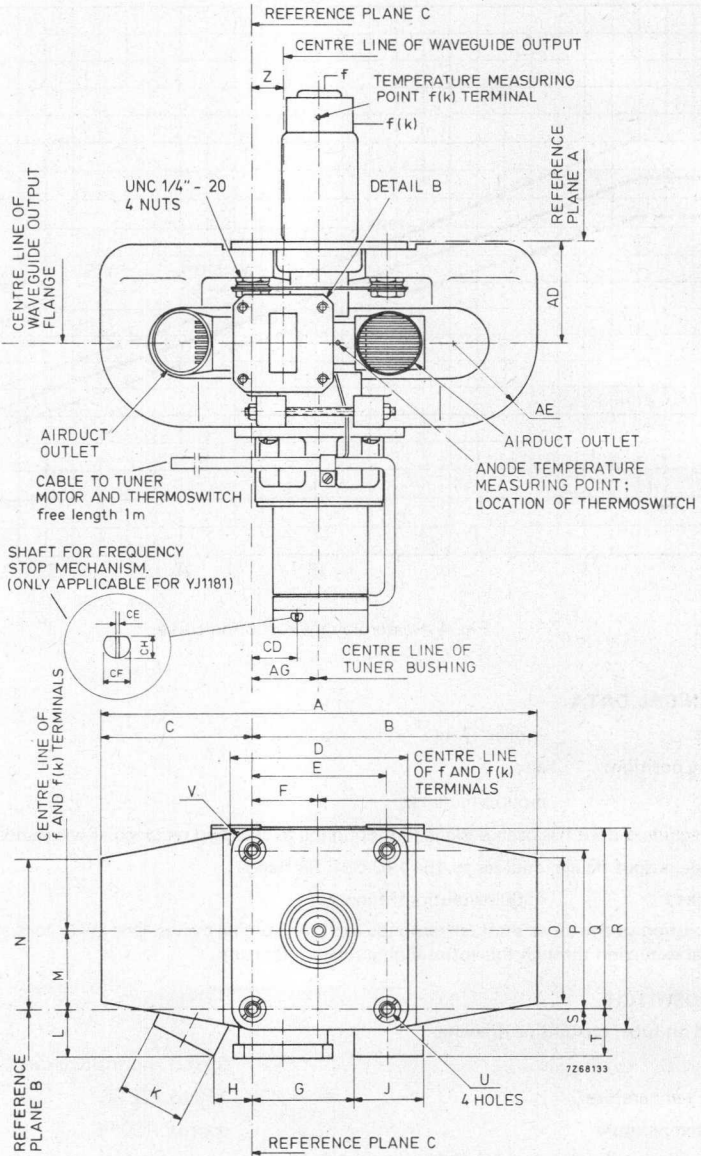


Fig. 5 Front and top view.

Table of dimensions of Fig. 5.

ref.	dimensions in mm		
	min.	nom.	max.
A			213,5
B			138,5
C			75
D			88,1
E	63,25	63,50	63,75
F	30,55	31,75	32,95
G		47,5	
H		18,5	
J		dia. 32	
K		dia. 32	
L		22,5	
M	36,9	38,1	39,3
N			75
O			73
P	75,95	76,2	76,45
Q			86,9
R			98,4
S			10,7
T		22,5	
U		dia. 7,15	
V		R 10,3	
Z	13,55	14,75	15,95
AD	45,9	47,1	48,3
AE		R 40	
AG	29,75	31,75	33,75
CD*	12,5	14,5	16,5
CE*	1,0	1,0	1,1
CF*	4,75	4,77	4,79
CH*	3,8	4,0	4,2

* Only applicable for YJ1181.

YJ1180
YJ1181

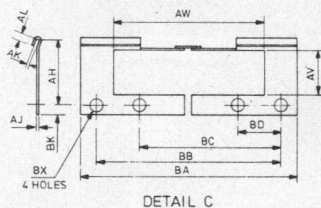
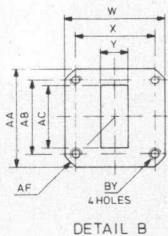
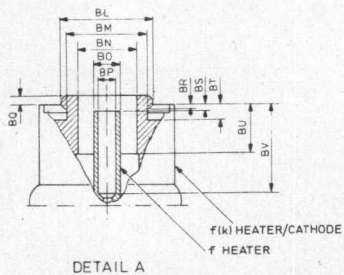
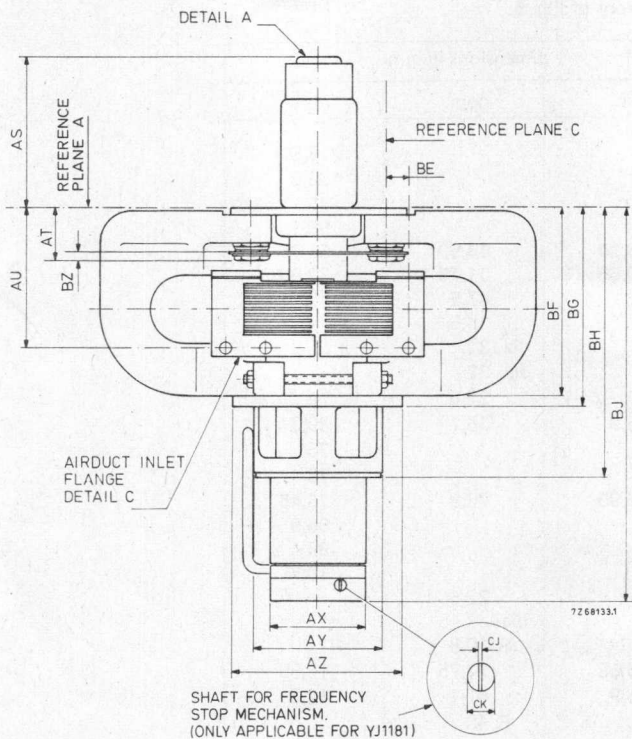


Fig. 6 Side view.

Table of dimensions of Fig. 6.

ref.	dimensions in mm		
	min.	nom.	max.
W		46,5	
X	37,3	37,4	37,5
Y		12,6	
AA		46,5	
AB	34,2	34,3	34,4
AC		28,5	
AF		R 29,5	
AH	34,5	36,0	37,5
AJ		1	
AK		1,6	
AL		4	
AS	65,10		69,85
AT		25	
AU	61,1	64,1	67,1
AV		24	
AW		70	
AX			dia. 44,5
AY			dia. 64
AZ			dia. 82
BA		100	
BB	85,5	87,0	88,5
BC	65,5	67,0	68,5
BD	18,5	20	21,5
BE	8,75	11,75	14,75
BF			90
BG			96
BH			127
BJ			185
BK		4	
BL	dia. 20,95	dia. 21,10	dia. 21,25
BM		dia. 19	
BN	dia. 13,55	dia. 13,70	dia. 13,85
BO	dia. 5,95	dia. 6,35	dia. 6,75
BP	dia. 4,18	dia. 4,30	dia. 4,42
BQ	0		
BR	2,95	3,20	3,45
BS	3,15	3,95	4,75
BT		6,35	
BU	13,1		
BV	19		
BX	dia. 6,0	dia. 6,0	dia. 6,5
BY		M4 thread	
BZ		5	
CJ*	1,0	1,0	1,1
CK*	dia. 4,75	dia. 4,77	dia. 4,79

* Only applicable for YJ1181.

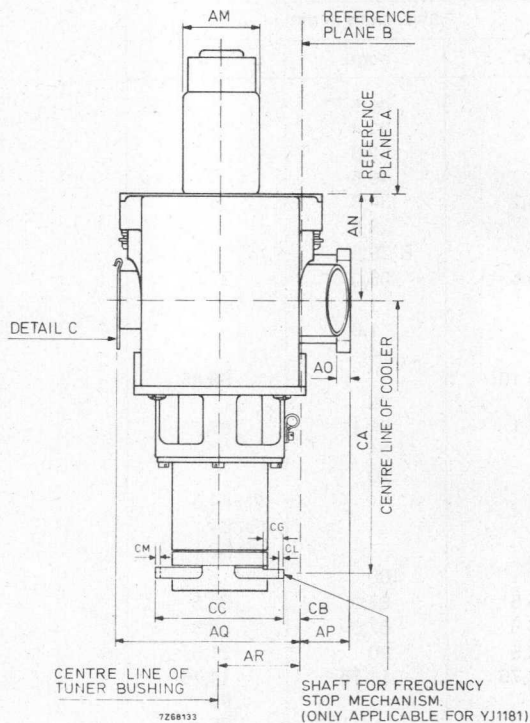


Fig. 7 Rear view.

ref.	dimensions in mm		
	min.	nom.	max.
AM			dia. 38,1
AN	44,1	47,1	50,1
AO		6,5	
AP	22,2	23,0	23,8
AQ	82,5	85,5	88,5
AR	36,1	38,1	40,1
CA *	170,0	173,5	177,0
CB *	6,35	7,85	9,35
CC *	59,35	60,35	61,35
CG *	15,4	15,9	16,4
CL *	3,1	3,9	4,7
CM *	3,1	3,9	4,7

* Only applicable for YJ1181.

PULSED MAGNETRON

Frequency agile air cooled packaged magnetron for use as a pulsed oscillator in navigational, search, and fire-control radar systems. It can be pulsed by a hard tube, line type or magnetic modulator. The magnetron type YJ1321 provides in addition to frequency agile operation the possibility of selecting any fixed frequency within its band (e.g. for MTI).

QUICK REFERENCE DATA

Frequency		Ku-band
Nominal centre frequency	f	16,5 GHz
Agile frequency excursion		670 MHz
Peak output power	W_{op}	65 kW
Construction		packaged

HEATING: indirect by a.c. (30 to 1000 Hz) or d.c.

Heater voltage, starting and stand-by	V_{fo}		12,6 V \pm 10%
Heater current at $V_f = 12,6$ V	I_f		1,0 A \pm 0,1 A
Peak heater starting current	I_{fp}	max.	5 A
Cold heater resistance	R_{fo}	>	2,2 Ω
Waiting time	t_w	min.	120 s

Immediately after the high voltage has been applied, the heater voltage must be reduced in accordance with the formula:

$$V_f = 12,6 \left(1 - \frac{I_a}{10}\right) \text{ V (see also Fig. 4)}$$

where I_a (in mA) = duty factor x peak anode current.

When $I_a > 10$ mA the heater voltage must be 0 V.

TYPICAL CHARACTERISTICS

Peak anode voltage at $I_{ap} = 15 \text{ A}$	V_{ap}	14,5 to 16,5 kV
Pulling figure	Δf_p	< 22 MHz
Pushing figure	$\frac{\Delta f}{\Delta I_a}$	< 1 MHz/A
Passive oscillation frequency difference	Δf	22 to 37 MHz*
Capacitance, anode to cathode	C_{ak}	< 10 pF

LIMITING VALUES (Absolute maximum rating system)

Pulse duration**	t_{imp}	max. 1,0 μs min. 0,1 μs
Duty factor	δ	max. 0,0011
Heater voltage	V_f	max. 14 V
Peak heater starting current	I_{fp}	max. 5 A
Anode current, peak**	I_{ap}	max. 17 A min. 10 A
Anode voltage, peak**	V_{ap}	max. 16,5 kV
Anode input power, mean	W_{ia}	max. 250 W
Anode input power, peak	W_{iap}	max. 280 kW
Rate of rise of anode voltage for pulse duration $\leq 0,15 \mu\text{s}$	$\frac{dV_a}{dt}$	max. 150 kV/ μs min. 40 kV/ μs
for pulse duration $> 0,15 \mu\text{s}$	$\frac{dV_a}{dt}$	max. 130 kV/ μs min. 40 kV/ μs
Voltage standing-wave ratio	VSWR	max. 1,5
Anode temperature at measuring point (see outline drawing)	T_a	max. 160 °C
Input pressurization	p	max. 30 N/m ² abs min. 8 N/m ² abs
Output pressurization	p	max. 30 N/m ² abs min. 10 N/m ² abs

* The passive oscillation frequency difference will not vary more than 7 MHz for each individual tube over its frequency band.

** See "Pulse characteristics and definitions".

OPERATING CHARACTERISTICS

Pulse duration*	t_{imp}	0,1	1,0 μs
Pulse repetition rate	f_{imp}	3300	1000 p.p.s.
Duty factor	δ	0,000 33	0,001
Peak anode voltage*	V_{ap}	15,5	15,5 kV
Rate of rise of voltage*	$\frac{dV_a}{dt}$	143	126 kV/ μs
Peak anode current*	I_{ap}	15	15 A
Heater voltage, running	V_f	6,3	0 V
Output power, mean	W_o	22	65 W
Output power, peak	W_{op}	65	65 kW

The manufacturer should be consulted whenever it is considered operating the magnetron at conditions substantially different from those given above.

COOLING

An adequate flow of cooling air should be directed along the cooling fins on the anode block to keep the temperature of the anode block below 120 °C under any condition of operation. An air flow of approximately 0,85 m³/min is normally sufficient.

PRESSURE

The mounting flange and the output waveguide flange are designed to permit the use of pressure seals. The minimum pressure to prevent cumulative electrical breakdown in the output coupling shall be 10 N/cm² abs. See also under "Limiting values".

LIFE

The life of the magnetron depends on the operating conditions, and is expected to be longer at shorter pulse durations.

AGEING OF MAGNETRON

It is recommended that magnetrons kept in store are re-aged every 12 to 24 months. Recommended ageing procedure available on request.

* See "Pulse characteristics and definitions".

STARTING A NEW MAGNETRON

When a magnetron is taken into operation for the first time some sparking and instability may occur. It is recommended that the magnetron be started in the following way:

1. Apply heater voltage (12,6 V) for at least 120 s.
2. Raise the anode current gradually, preferably starting at the shortest available pulse duration, until one half of the normal operating output power is obtained. Operate the magnetron at this power level at the lowest tunable frequency. Take care that the heater voltage is reduced in accordance with the heater voltage cut-back schedule.
3. As soon as the magnetron operates stably, gradually raise the anode current until the normal operating conditions are reached. If sparking occurs, stop raising anode current until the magnetron operates stably again. Care should be taken that the maximum ratings are not exceeded.
4. Repeat the procedure 1, 2, and 3 with the magnetron operating in the frequency agile mode.

After this running-in schedule the magnetron can be put into use at the normal operating conditions.

TUNING MECHANISM

The tuning is achieved by rotating a tuner inside the vacuum part of the magnetron. This tuner is magnetically coupled to the tuner motor and rotates with the same speed as the motor. The magnetron is tuned over one complete cycle when the motor shaft is rotated 1/16 rev. (22,5°). The tuner can rotate in both clockwise and counter-clockwise directions depending on the electrical connection of the tuner motor. See below for information on the connection of the tuner motor. It is advised to run the tuner motor normally only during oscillation conditions.

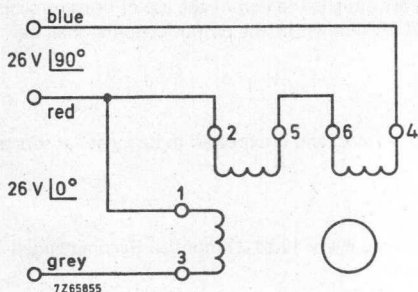


Fig. 1 Two-phase, 400 Hz supply
90° shift between phases:
Phase voltage 26 V
Input power 6 W/phase
Motors for other voltages
can be supplied on request.

FREQUENCY LOCK (YJ1321 only)

The YJ1321 is provided with a tuner lock added to the motor, so that it can be used for frequency agile or fixed frequency operation.

Agile tuning is only achieved when the motor rotates clockwise. Fixed frequency operation is obtained by reversing the direction of rotation of the motor axis. In this direction a built-in mechanical device is actuated that locks the motor shaft. This lock keeps the tuner in a defined angular position, corresponding to a predetermined frequency. This angular position can be adjusted by means of a shaft protruding from the motor housing (see outline drawing).

CIRCUIT NOTES

- (a) In order to prevent heater burn-out the negative high-voltage pulse must be applied to the common heater/cathode terminal f(k).
- (b) The magnetron is used in combination with an F.T.L.O. (fast-tuned local oscillator) including a circulator which provides load isolation at the same time. The distance between circulator and magnetron should be as short as possible. Under no circumstances should the magnetron be operated with a load giving a VSWR exceeding 1,5. A ratio kept near unity will benefit tube life and reliability.
- (c) The modulator must be so designed that, if arcing occurs, the energy per pulse supplied to the magnetron does not considerably exceed the normal energy per pulse.
- (d) It is required to bypass the magnetron heater with a 1000 V rated capacitor of minimum 4 nF directly across the heater terminals.
- (e) Any diode current flowing during the intervals between the pulses should be taken into account when the peak anode current is calculated from the measured mean anode current. The occurrence of this diode current can be avoided by preventing the anode voltage becoming positive with respect to the cathode during the intervals between the pulses.
- (f) The unwanted noise that may occur when the anode pulse voltage drops below the value required for oscillation can be minimized by making the trailing edge of the voltage pulse as steep as possible.

PULSE CHARACTERISTICS AND DEFINITIONS

The smooth peak value (V_{ap} or I_{ap}) of a pulse is the maximum value of a smooth curve through the average of the fluctuation over the top portion of the pulse as shown in the figures below.

The rate of rise of anode voltage is defined by the steepest tangent to the leading edge of the voltage pulse above 50% of the smooth peak value (Fig. 2). Any capacitance used in a removable viewing system shall not exceed 6 pF. For calculating the rate of rise of anode voltage the 100% value must be taken as 15,5 kV.

The pulse duration (t_{imp}) is the time interval between the two points on the current pulse at which the current is 50% of the smooth peak current (Fig. 3).

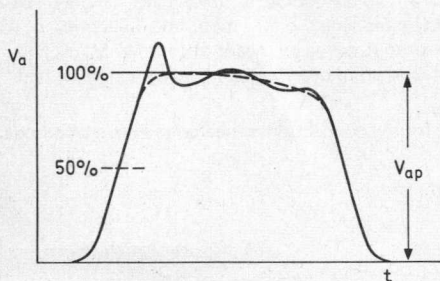


Fig. 2.

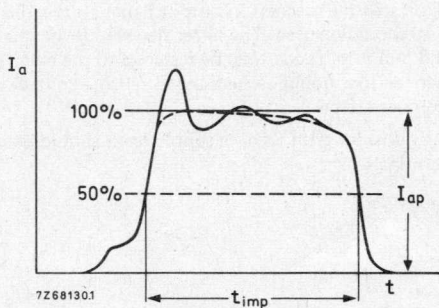


Fig. 3.

The current pulse must be substantially square and the ripple over the top portion of the current pulse must be kept as small as possible to avoid unwanted frequency modulation due to pushing effects. The spike on the top portion of the pulse must be small to avoid excessive peak pulse current. The leading edge of the pulse must be free from irregularities.

STORAGE, HANDLING AND MOUNTING

The original packing should be used for the transport of the magnetron.

The magnetron should be handled carefully. Rough treatment of the envelope and of the cooling fins may impair the electrical characteristics or may result in loss of vacuum.

When storing, the packaged magnetrons should be kept not less than 15 cm (6 in) apart, to prevent a decrease of field strength of the magnetron magnet as a result of interaction with the adjacent magnets. If the magnetrons are stored in their original inner container, no special precautions need to be taken with regard to the distance apart. If the magnetrons are stored without their inner container, they should be stored in non-magnetic surroundings e.g. on wooden shelves. If the tubes cannot be stored at normal temperature they must be stored in protective packing.

When handling and mounting the magnetron, a minimum distance of 5 cm (2 in) between the magnet and any piece of magnetic material should be maintained to avoid mechanical shocks to the magnetron. For this reason it is required that non-magnetic tools be used during installation, such as non-magnetic stainless steel, brass, beryllium copper and aluminium. Furthermore, the user should be aware of the detrimental influence of the strong magnetic field around the magnet on watches and other precision instruments nearby.

A dust-cover is placed on the output flange to keep its opening closed until the tube is mounted into the equipment. Before putting the magnetron into operation, the user should make sure that the output waveguide is entirely clean and free from dust and moisture.

The magnetron should be mounted by means of its mounting flange; it should be secured to the chassis by means of four bolts (thread M6). Special attention has been given to the flatness of the mounting flange, so that, if necessary, a pressure seal can be made for the input assembly. Consequently, the mounting surface should be sufficiently flat to avoid deformation of the flange. Furthermore, the mounting should be sufficiently flexible and adjustable so that no strain is exerted on the output system when the mounting bolts are tightened and when the output system is being coupled to the waveguide in the equipment.

To fasten the magnetron output flange to the 153 IEC—R 140 waveguide, a choke flange 154 IEC—CBR 140 should be used. The latter flange must be modified by reaming the four mounting holes with a 4,3 mm drill. It can then be fastened to the magnetron output flange by means of four M4 bolts. This connection should be such that a reliable contact is established in order to avoid arcing and other bad contact effects.

A connector with flexible supply leads should be used for the connection of heater and heater/cathode terminals.

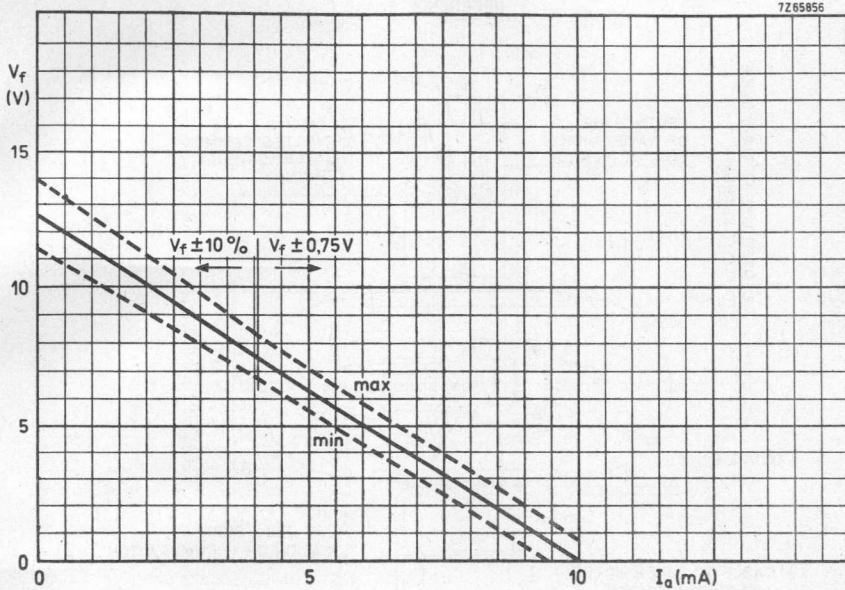


Fig. 4 Heater voltage reduction curve.

MECHANICAL DATA

Net mass: approx. 3,2 kg

Mounting position: any

Support: mounting flange

The waveguide output has been designed for coupling to standard rectangular waveguide 153 IEC-R 140.

Waveguide output flange: couples to 154 IEC-CBR 140 flange

Tuner speed: 4500 revolutions/minute

One revolution of the tuner shaft corresponds to 16 full tuning cycles. One cycle consists of a quasi-sinusoidal excursion through the entire tuning range and return.

THERMOSWITCH

Mounted on tube, see outline drawing.

Contact	S.P.S.T. normally closed
Opening temperature	110 to 122 °C
Closing temperature	approx. 100 °C
Contact ratings 220 V (a.c.), 1,5 A; 220 V (d.c.) 0,4 A	non-inductive load
Leads	black, 2

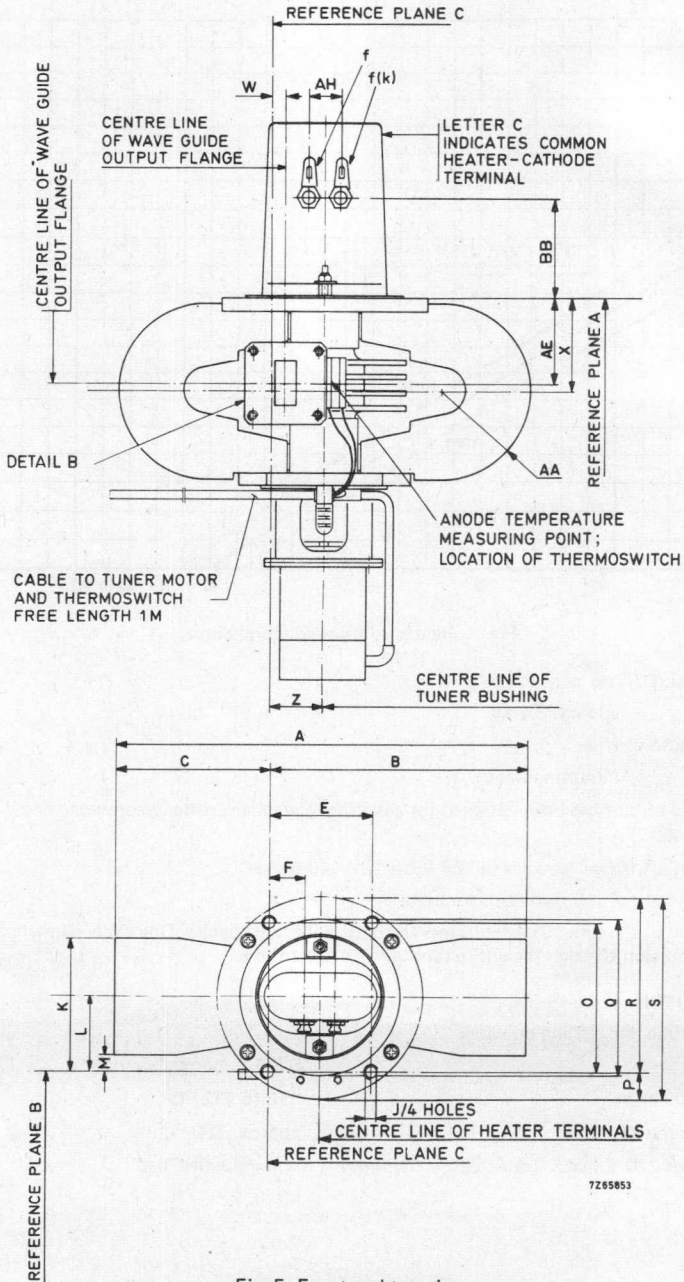
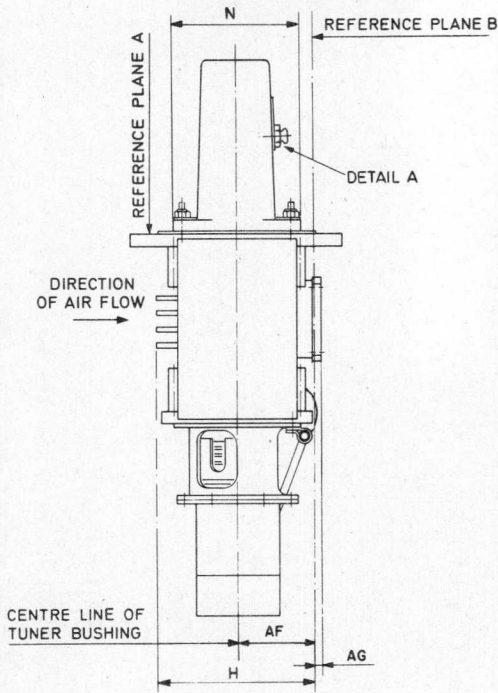


Fig. 5 Front and top view.

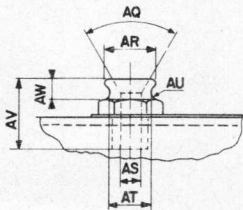
Table of dimensions of Fig. 5.

ref.	dimensions in mm		
	min.	nom.	max.
A			180
B			112
C			68
E	43,8	44,0	44,2
F	15,0	15,6	16,3
J	M6 screwthread		
K			59,5
L	31,4	32,0	32,6
M	4		
O	63,8	64,0	64,2
P			13,5
Q	66,5	66,7	66,9
R			78
S			dia. 91
W	2,3	3,2	4,0
X		37,2	
Z	20	22	24
AA		R34	
AE	34,4	35,5	36,6
AH	12,45	12,70	12,95
BB	40,6	42,6	44,6

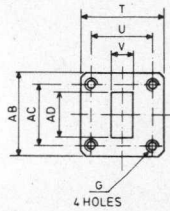
YJ1320
YJ1321



ref.	dimensions in mm		
	min.	nom.	max.
G	M4 screwthread		
H			70
N			dia. 55
T		33,3	
U	24,2	24,3	24,4
V		7,9	
AB		33,3	
AC	25,2	25,3	25,4
AD		15,8	
AF	30	32	34
AG	2,7	3,4	4,1
AQ		60°	
AR	7,06	7,14	7,21
AS	4,16	4,29	4,42
AT	5,82	5,94	6,06
AU		R1	
AV		17,5	
AW	2,64	2,76	2,88



DETAIL A
(FLYING LEADS ALSO AVAILABLE)



DETAIL B
4 HOLES

7265853

Fig. 6 Side view.

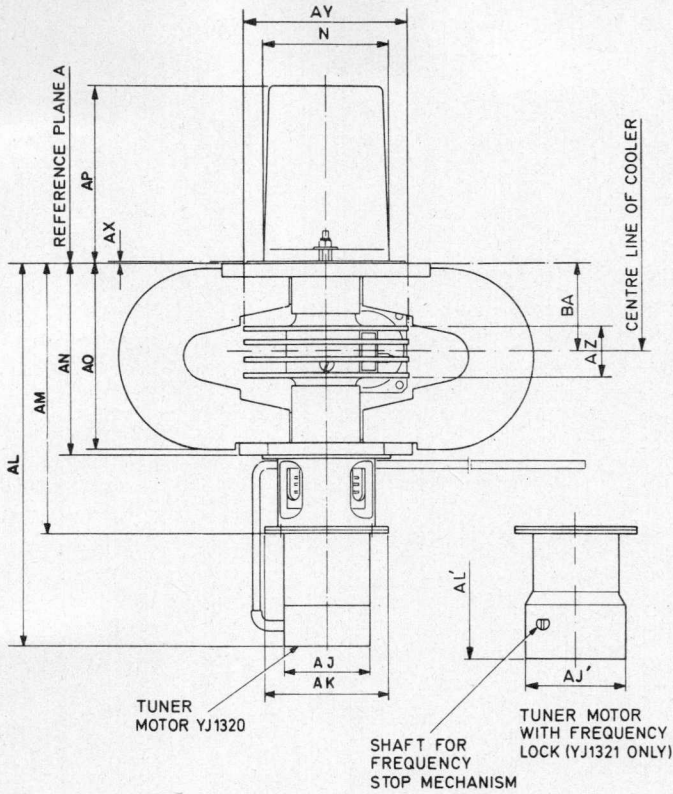
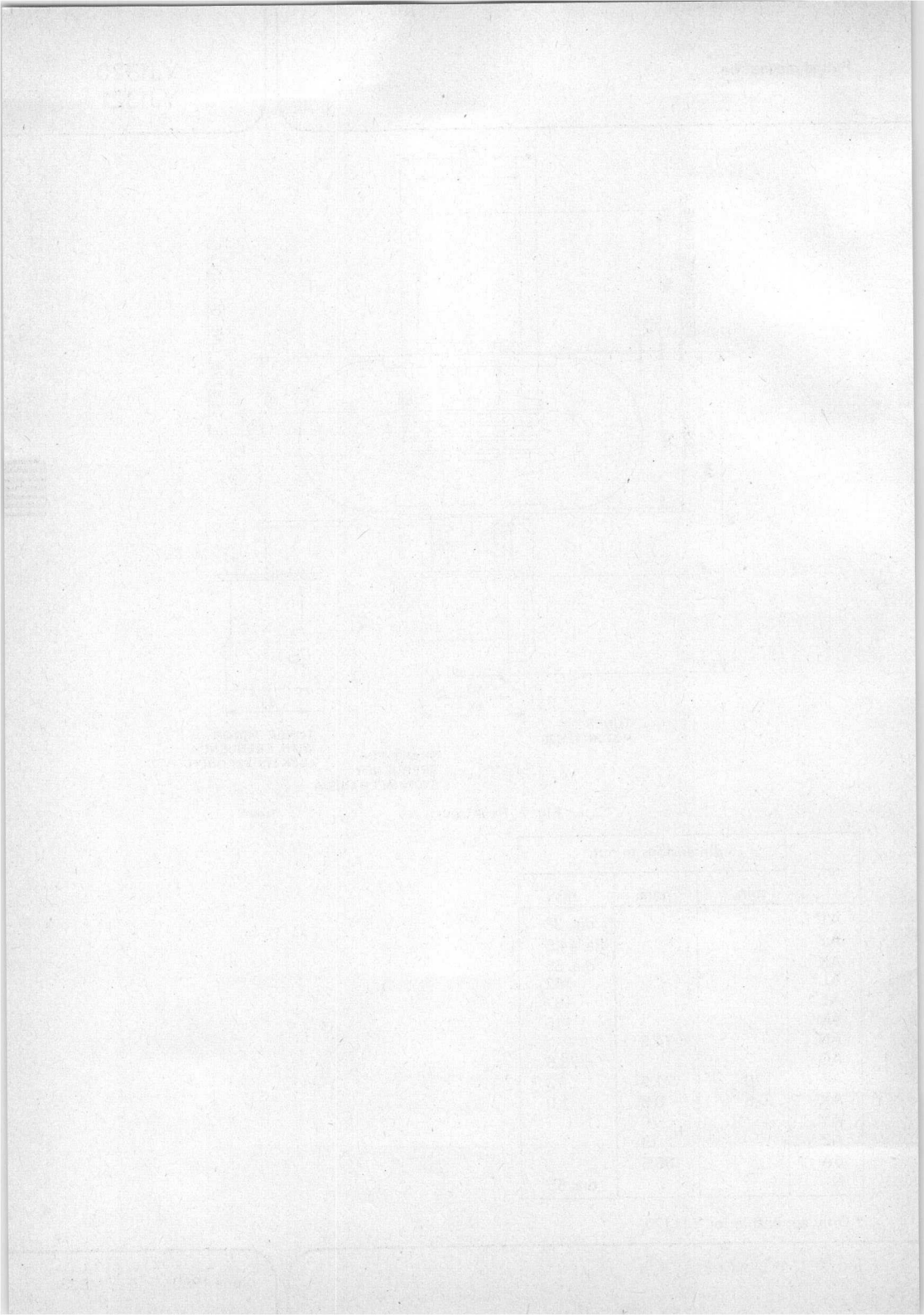


Fig. 7 Rear view.

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ref.	dimensions in mm		
	min.	nom.	max.
AJ*			dia. 38
AJ'			dia. 44,5
AK			dia. 55
AL*			162
AL'*			167
AM			115
AN		74,5	
AO			73,5
AP	70	71,5	73
AX	0,6	0,8	1,0
AY			70
AZ			19
BA		35,5	
N			dia. 55

* Only applicable for YJ1320.



PULSED MAGNETRON

Forced air-cooled unpackaged tunable magnetron for pulsed service.

QUICK REFERENCE DATA

Frequency, tunable within the band	f	2,700 to 2,900 GHz
Peak output power	W_{op}	800 kW
Construction		unpackaged

The magnetron is used with a 1 5/8 inch coaxial output transmission line and a separate magnet having an air gap of 1,8 inch and a magnetic field strength of 216 A/mm (2700 Oe).

HEATING: indirect

Heater starting voltage	V_{fo}	16 V ± 10%
Heater current at $V_f = 16$ V	I_f	2,8 to 3,4 A
Peak heater starting current	I_{fp}	max. 12 A
Waiting time	t_w	min. 2 min

During high-voltage operation the heater voltage must be reduced according to the following schedule.

W_{ia} (W)	V_f (V)
< 400	16
400 to 600	15
600 to 800	13
800 to 1000	10,5
1000 to 1200	8

This schedule is valid only for repetition rates of 300 or more pulses per second.

LIMITING VALUES (Absolute maximum rating system)

Pulse duration	t_{imp}	max.	2,5 μ s
Duty factor	δ	max.	0,001
Peak anode current	I_{ap}	max.	70 A
Mean anode input power	W_{ia}	max.	1200 W
Peak anode input power	W_{iap}	max.	2100 kW
Peak anode voltage	V_{ap}	max.	32 kV
Rate of rise of anode voltage*	dV_a/dt	max.	150 kV/ μ s
		min.	75 kV/ μ s
Voltage standing-wave ratio	VSWR	max.	1,5
Anode temperature	T_a	max.	100 $^{\circ}$ C

OPERATING CHARACTERISTICS

Frequency	f		2,7 to 2,9 GHz
Peak anode current	I_{ap}		70 A
Mean anode current	I_a		35 mA
Peak anode voltage	V_{ap}		27 to 30 kV
Rate of rise of anode voltage*	dV_a/dt		140 kV/ μ s
Pulse duration	t_{imp}		1 μ s
Duty factor	δ		0,0005
Magnetic field strength	H		216 A/mm (2700 Oe)
Mean output power	W_o		400 W
Peak output power	W_{op}		800 kW
Bandwidth	B	<	2,5 MHz
Pulling figure	Δf_p	<	15 MHz

The manufacturer should be consulted whenever it is considered to operate the magnetron at conditions substantially different from those given above.

* The rate of rise of anode voltage is defined by the steepest tangent to the leading edge of the voltage pulse above 50% of the smooth peak value.

MECHANICAL DATA

Dimensions in mm

Net mass: 2,3 kg

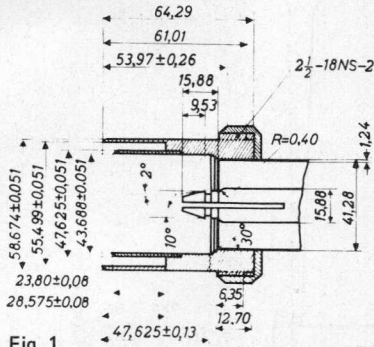


Fig. 1.

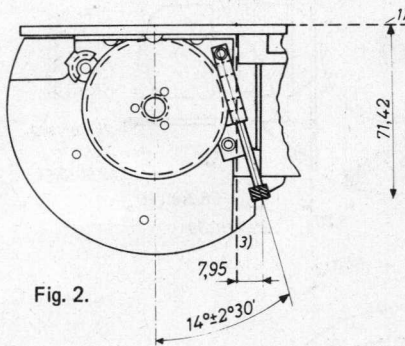


Fig. 2.

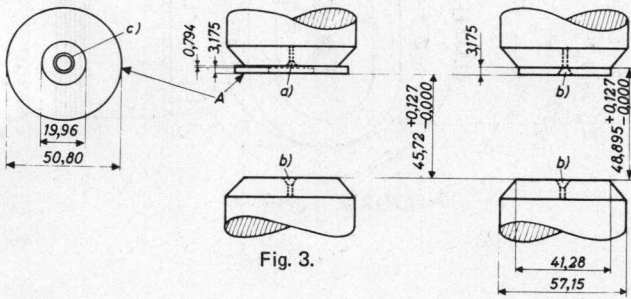
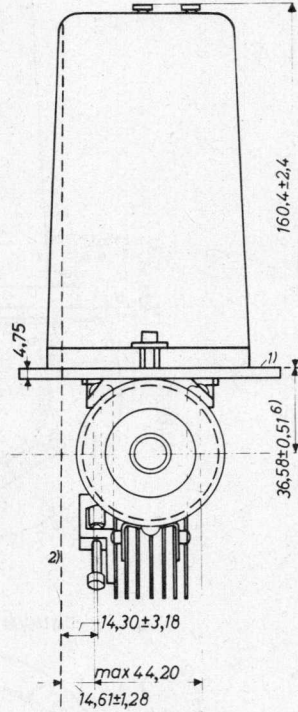


Fig. 3.

Fig. 4.

See also page B39.

Mounting position: any

The tube may be supported by the mounting plate or by the guard pipe.

The output of the tube can be maintained at a pressure of 280 to 310 kPa.

The input flange can also be pressurized.

The tuning mechanism will provide the full range of tuning with 110 complete revolutions of the tuning spindle.

The cathode side (non-tuner side) of the magnetron anode should be adjacent to the north pole of the magnet.

From page B37

Fig. 1: Test coupling, not furnished with the tube.

Fig. 2: Optional location of the tuning spindle.

Figs 3 and 4: Magnetic field calibrators.

Fig. 3: Magnet with distortion pole piece.

Fig. 4: Magnet with single conventional pole piece.

(A) = cold rolled steel insert.

(a) = 10-32 flat head brass screw.

(b) = 10-32 flat head steel screw.

(c) = 5/16 hole countersunk.

For the calibration procedure of the magnetic field please communicate with the manufacturer.

- (1) Reference plane A.
- (2) Reference plane B.
- (3) Reference plane C.
- (4) This annular area is flat within 0,4 mm. A thickness gauge 3,175 mm wide will not enter more than 6,35 mm.
- (5) The periphery of the anode lies within a 54,87 mm diameter circle located as specified for the non-tunable side of the anode.
- (6) Applies to the location of the centre line of the guard pipe only.
- (7) The centre line of max. diameter is concentric with the centre line of the guard pipe to within 1,02 mm.
- (8) Applies to the inner conductor insert only. The centre line of the inner conductor insert is concentric with the centre line of the guard pipe to within 0,64 mm.
- (9) Applies to the straight portion of the inner conductor wall.
- (10) The centres of the jack holes are within a radius of 2,54 mm of the location specified, but are spaced $20, 24 \pm 0,39$ mm with respect to each other.
- (11) Hex locking head banana pin jack 15 mm long hole, $4,29 \pm 0,13$ mm diameter. The common heater-cathode connection is marked with the letter C.
- (12) Protective guard for shipping purposes.



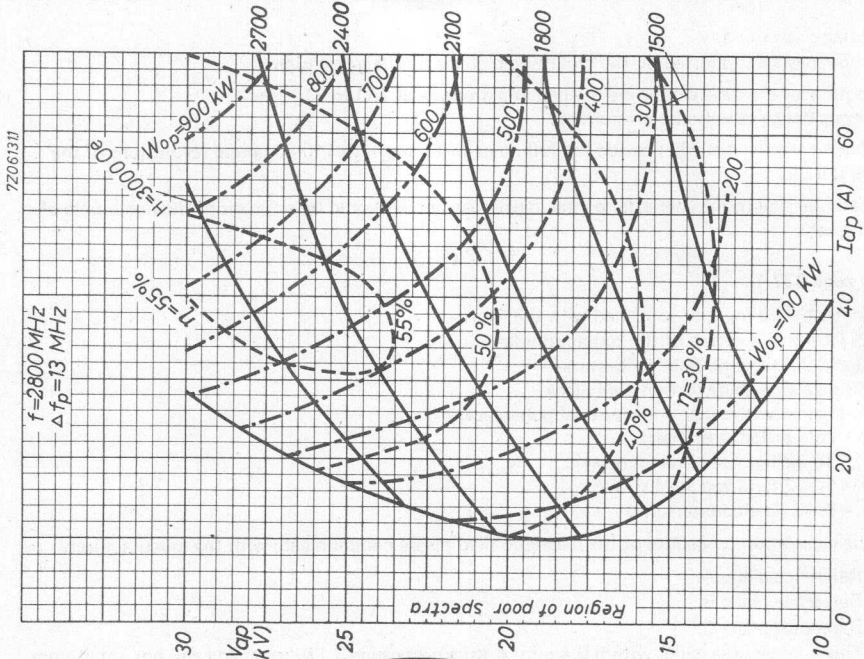
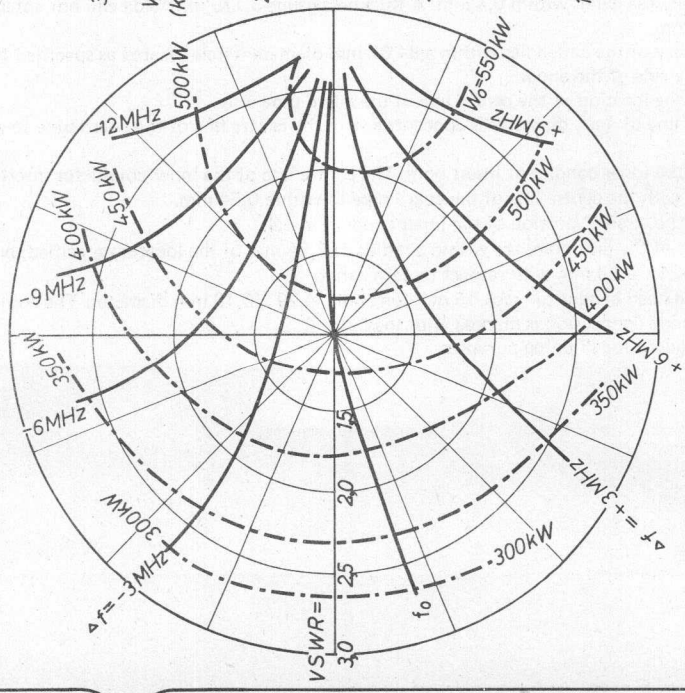


Fig. 7.

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 5586 28-9-60



$I_{ap} = 50 \text{ A}$
 $H = 2100 \text{ Oe}$
 $f = 2800 \text{ MHz}$

Fig. 6.

PULSED MAGNETRONS

Forced-air cooled packaged magnetrons intended for service as pulsed oscillator at a fixed frequency. They have been designed for operation at pulse durations of 1 to 0,1 μ s.

QUICK REFERENCE DATA

type	frequency band (MHz)	peak output power (kW)	
		$t_{imp} = 0,1 \mu s$	$t_{imp} = 1 \mu s$
55029	9405 to 9505	200	250
55030	9345 to 9405		
55031/02	9260 to 9345		
55031/01	9168 to 9260		
55032/02	9085 to 9168		
55032/01	9003 to 9085		
construction		packaged	

HEATING: indirect

Heater voltage, starting	V_f	13,75 $V^{+10\%}_{-5\%}$
Heater current at $V_f = 13,75 V$	I_f	3,00 to 3,75 A
Peak heater starting current	I_{fp}	max. 15 A
Cold heater resistance	R_{fo}	> 0,6 Ω
Waiting time	t_w	min. 4 min

It is necessary to reduce the heater voltage immediately after applying the high voltage.

The reduced heater voltage is given under "Operating characteristics" and Fig. 1.

TYPICAL CHARACTERISTICS

Peak anode voltage	V_{ap}	20 to 23 kV
Pulling figure (VSWR = 1,5)	Δf_p	13 MHz < 17,5 MHz
Pushing figure	$\frac{\Delta f}{\Delta I_{ap}}$	< 0,25 MHz/A
Temperature coefficient	$\frac{\Delta f}{\Delta T}$	< -0,25 MHz/K
Anode to cathode capacitance	C_{ak}	14 pF

LIMITING VALUES (Absolute maximum rating system)

Each limiting value should be regarded independently of other values, so that under no circumstances it is permitted to exceed a limiting value whichever.

Pulse duration	t_{imp}	max.	1 μ s
Duty factor	δ	max.	0,001
Heater starting voltage	V_f	max.	15 V
Peak heater starting current	I_{fp}	max.	15 A
Peak anode current	I_{ap}	max.	27,5 A
Mean input power	W_{ia}	max.	635 W
Peak input power	W_{iap}	max.	635 kW
Rate of rise of anode voltage for $t_{imp} = 1 \mu$ s	dV_a/dt	max. min.	110 kV/ μ s 70 kV/ μ s
for $t_{imp} = 0,25 \mu$ s	dV_a/dt	max. min.	160 kV/ μ s 120 kV/ μ s
for $t_{imp} = 0,1 \mu$ s	dV_a/dt	max. min.	220 kV/ μ s 160 kV/ μ s
Voltage standing-wave ratio	VSWR	max.	1,5
Anode temperature at measuring point	T_a	max.	150 °C
Cathode/heater terminal temperature	T	max.	165 °C
Pressurization of input and output assemblies	p	max.	310 kPa

OPERATING CHARACTERISTICS

Frequency	see "Quick Reference Data"			
Pulse duration	t_{imp}	0,1	0,25	1,0 μ s
Duty factor	δ	0,0002	0,0005	0,001
Heater voltage	V_f	12	9	6,5 V (note 1)
Peak anode voltage	V_{ap}	$21,5 \pm 1,5$	$21,5 \pm 1,5$	$21,5 \pm 1,5$ kV
Rate of rise of voltage pulse	$\Delta V_a / \Delta t_{rv}$	190	140	90 kV/ μ s (note 2)
Average anode current	I_a	4,5	12	27,5 mA (note 3)
Peak anode current	I_{ap}	22,5	24	27,5 A
Average output power	W_o	41	110	250 W
Peak output power	W_{op}	205	220	250 kW

The manufacturer should be consulted whenever it is considered operating the magnetron at conditions substantially different from those given above.

Notes

1. The tolerance of the heater voltage is +10 and -5% of the indicated value. The heater voltage must be reduced from 13,75 V to the indicated value as soon as the magnetron starts oscillating.
2. For the definition of the rate of rise of voltage pulse see under "Pulse definitions".
3. See "Circuit notes".

COOLING

An adequate air flow should be directed along the cooling fins towards the body of the tube to keep the anode block temperature below 150 °C under any condition of operation.

LIFE

The life of the magnetron depends on the operating conditions, and is expected to be longer at shorter pulse lengths.

STARTING A NEW MAGNETRON

This magnetron is provided with a getter, so that ageing (of a new magnetron or of a magnetron that has been idle or stored for a period of time) will not be necessary in most cases. If, however, the magnetron is put into operation and some sparking and instability occur incidentally, it is recommended that the anode current be increased gradually and to operate the magnetron with reduced input for 15 to 30 minutes. After this period sparking usually ceases.

PULSE CHARACTERISTICS AND DEFINITIONS

The smooth peak value (V_{ap} or I_{ap}) of a pulse is the maximum value of a smooth curve through the average of the fluctuation over the top portion of the pulse as shown in the figures below.

The rate of rise of anode voltage is defined by the steepest tangent to the leading edge of the voltage pulse above 80% of the smooth peak value (Fig. 1). Any capacitance used in a removable viewing system shall not exceed 6 pF. For calculation of the rate of rise of anode voltage the 100% value must be taken as 21,5 kV.

The pulse duration (t_{imp}) is the time interval between the two points on the current pulse at which the current is 50% of the smooth peak, current (Fig. 2).

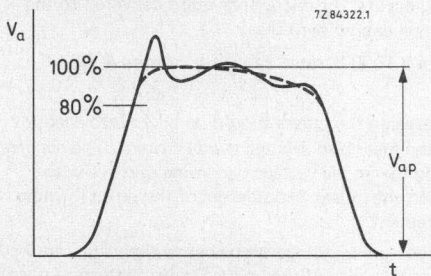


Fig. 1.

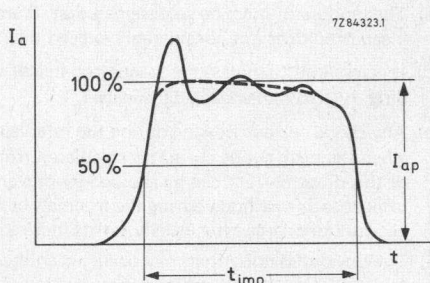


Fig. 2.

STORAGE, HANDLING AND MOUNTING

In handling the magnetron, it should never be held by the heater-cathode stem. Rough treatment of the metal envelope and of the cooling fins may impair the electrical characteristics or may result in loss of vacuum.

In storage a minimum distance of 15 cm (6") should be maintained between the packaged magnetrons to prevent the decrease of field strength of the magnetron magnet due to the interaction with adjacent magnets.

Magnetic materials should be kept away from the magnet a distance of at least 5 cm (2") to avoid mechanical shocks to the magnet. For this reason it is required to use non-magnetic tools during installation.

All tubes are delivered with a dust cover placed on the waveguide output flange. It is recommended that the opening in the flange be kept closed by this dust cover until the tube is mounted into the equipment. Before putting the magnetron into operation, the user should make sure that the output waveguide is entirely clean and free from dust and moisture.

Mounting of the magnetron should be accomplished by means of its mounting flange. The tube should in no case be supported by the coupling to the waveguide output flange alone.

CIRCUIT NOTES

- (a) In order to prevent heater burn-out the negative high-voltage pulse must be applied to the common cathode-heater terminal.
- (b) If no load isolator is inserted between the magnetron and the transmission line, the latter should be as short as possible to prevent long-line effects. Under no circumstances should the magnetron be operated with a VSWR of the load exceeding 1,5 . A ratio kept near unity will benefit tube life and reliability.
- (c) The modulator must be so designed that, if arcing occurs, the energy per pulse delivered to the magnetron does not considerably exceed the normal energy per pulse.
- (d) It is required to bypass the magnetron heater with a 1000 V rated capacitor of min. 4000 pF directly across the heater terminals.
- (e) Any diode current flowing during the intervals between the pulses should be taken into account when the peak anode current is calculated from the measured average anode current. The occurrence of this diode current can be avoided by preventing the anode voltage becoming positive with respect to the cathode during the intervals between the pulses. Modulators of the pulse forming network discharge type usually satisfy this requirement.
- (f) The unwanted noise that may occur when the anode pulse voltage drops below the value required for oscillation can be minimized by making the trailing edge of the voltage pulse as steep as possible.

Operation at pressures lower than 80 kPa may result in arc-over across the heater-cathode stem with consequent damage to the magnetron. The output assembly must always be pressurized. When the magnetron is not working into a matched load, the pressure on the output window must be higher than 100 kPa.

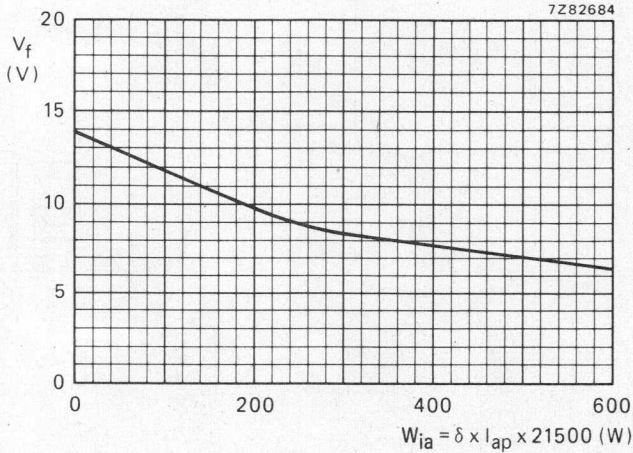


Fig. 3.

MECHANICAL DATA

The waveguide output is designed for coupling to standard rectangular waveguide RG-51/U (E.I.A. designation WR112, British designation WG15) with outside dimensions $1\frac{1}{4} \times 5/8''$.

To fasten the magnetron output flange to the RG-51/U waveguide, a choke flange Z83 00 33 (British designation) or type UG-52A/U should be inserted between these parts. This choke flange should be modified to fit the magnetron output flange. This is accomplished by reaming the four mounting holes in the above choke flange with a No. 15 drill. The choke flange can then be fastened to the magnetron output flange by means of four size 8-32 bolts.

MECHANICAL DATA (continued)

Dimensions in mm

Net mass: 5 kg

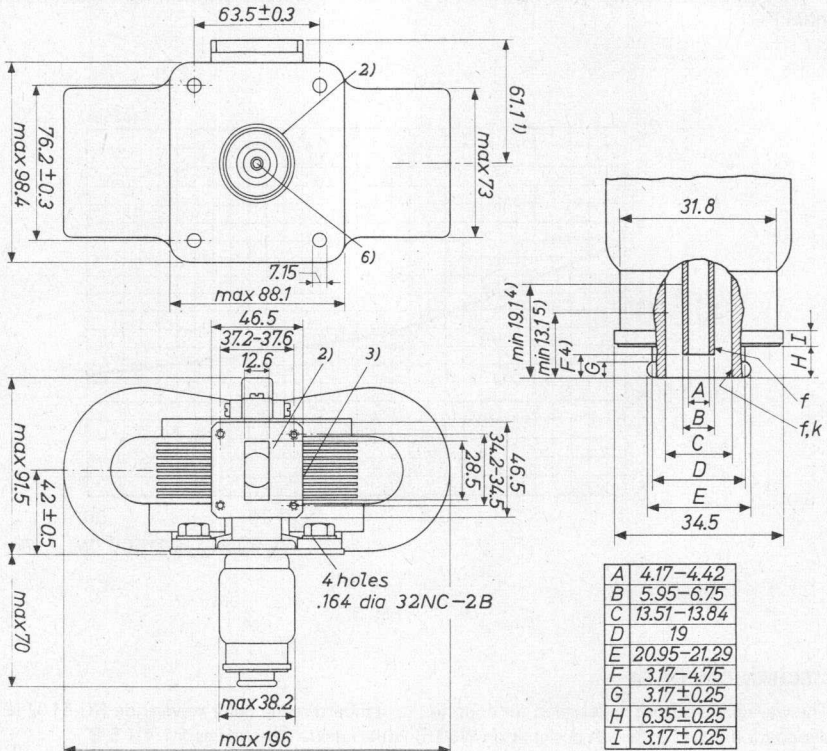


Fig. 4.

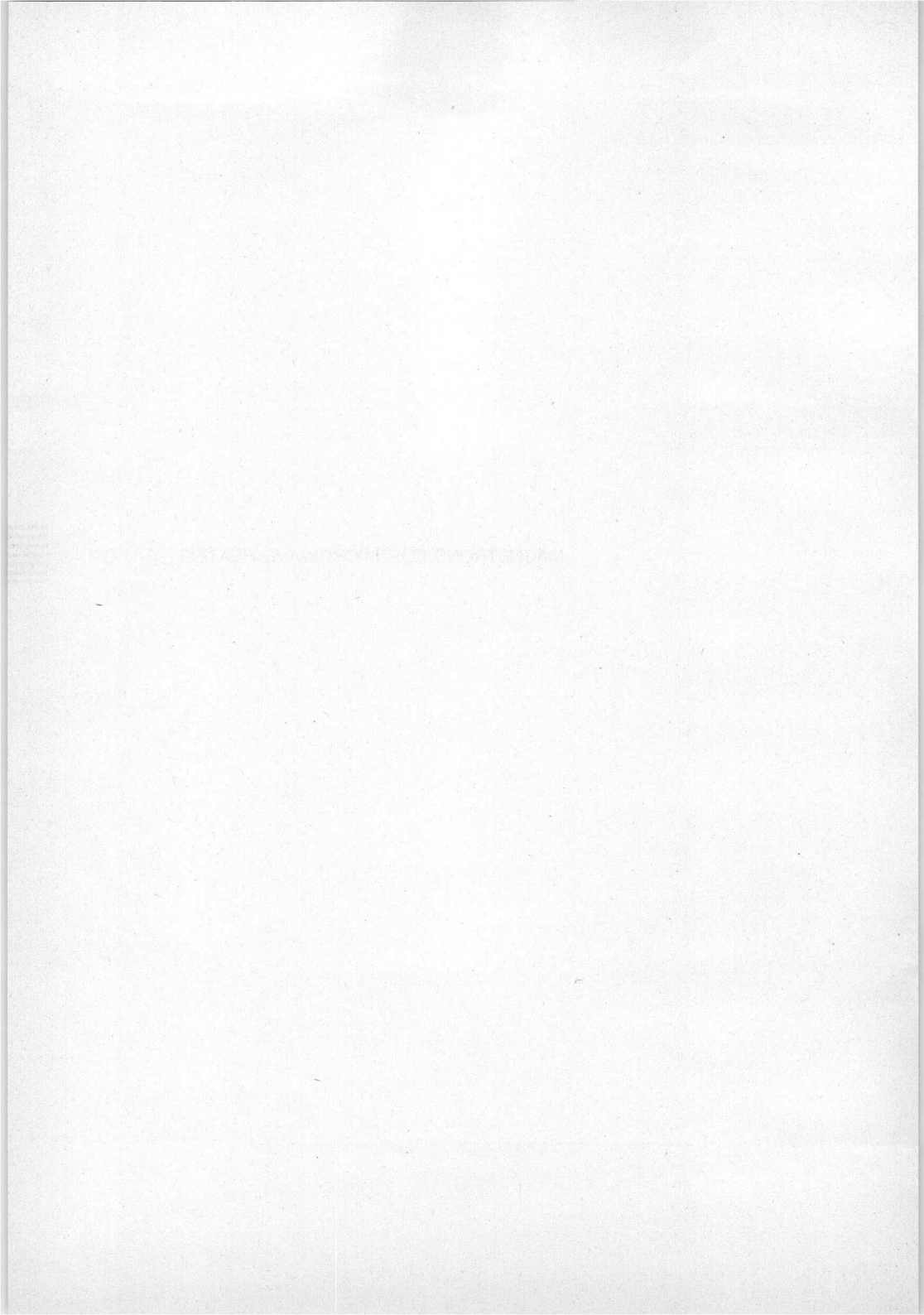
Mounting position: any

- (1) This dimension applies to the magnetron types 55029, 55030 and 55031. The output system of the 55032 is 6 mm longer (67,1 mm).
- (2) Hermetic connections can be made to the mounting flange and the waveguide output flange.
- (3) Anode temperature measuring point on the anode block in front of the cooling fins.
- (4) These dimensions define the cylindrical part of the heater terminal.
- (5) This dimension defines the cylindrical part of the common heater-cathode terminal.
- (6) The axis of the common heater-cathode terminal is within a radius of 1,19 mm from the centre of the mounting plate.

MAGNETRONS FOR MICROWAVE HEATING

C





CONTINUOUS-WAVE MAGNETRON

Continuous-wave water-cooled packaged magnetron intended for microwave heating applications.

QUICK REFERENCE DATA

Frequency, fixed with the band	f	2,425 to 2,475 GHz
Output power	W_0	2,0 to 2,5 kW
Construction		packaged
Anode supply		unfiltered single-phase full-wave, or three-phase half-wave rectification

CATHODE: Dispenser type

HEATING: Indirect by a.c. (50 to 60 Hz) or d.c. See also page C7.

Heater voltage, starting	V_f		5 V	+ 5%	-10%
Heater voltage, stand-by	V_f		4,8 V	+ 5%	-10%
Heater current at $V_f = 5$ V	I_f	\approx	35 A		
		<	38 A		
Heater current, peak starting	I_{fp}	max.	100 A		
Cold heater resistance	R_{f0}	\approx	20 m Ω		
Waiting time (time before application of high voltage at $V_f = 5$ V)	t_w	min.	120 s		

TYPICAL CHARACTERISTICS measured under matched load conditions ($VSWR \leq 1,05$) and a d.c. power supply

Frequency, fixed within the band	f	2,425 to 2,475 MHz
Anode voltage at $I_a = 750$ mA	V_a	4,45 to 4,85 kV

LIMITING VALUES AND OPERATING CHARACTERISTICS

Anode voltage obtained from a single-phase full-wave, or three-phase half-wave, rectifier without smoothing filter.

A. OPERATION WITH $W_0 = 2$ kW

LIMITING VALUES (Absolute maximum rating system)

Anode current, mean	I_a	max.	0,8 A
		min.	0,1 A
Anode current, peak	I_{ap}	max.	2,1 A
Voltage standing-wave ratio at $0,37 \lambda < d < 0,44 \lambda$	VSWR	max.	4
remaining region	VSWR	max.	5

TYPICAL OPERATION (into a matched load)

Heater voltage, running	V_f		2 V
Anode current, mean	I_a		0,75 A
Anode current, peak	I_a		2 A
Anode voltage (measured with d.c.)	V_a		4,75 kV
Output power	W_o	>	2 kW 1,85 kW
Efficiency	η		55 %

B. OPERATION WITH $W_o = 2,5$ kW

A fixed reflection element with a VSWR of 1,5 and a phase position of $0,41 \lambda$ should be inserted between magnetron and load.

LIMITING VALUES (Absolute maximum rating system)

Anode current	I_a	max.	0,9 A
		min.	1,1 A
Anode current, peak	I_{ap}	max.	2,1 A
Voltage standing-wave ratio at $0,37 \lambda < d < 0,44 \lambda$	VSWR	max.	2,5
remaining region	VSWR	max.	4

TYPICAL OPERATION (into a matched load) *

Heater voltage, running	V_f		1,5 V
Anode current, mean	I_a		0,85 A
Anode current, peak	I_{ap}		2 A
Anode voltage (measured with d.c.)	V_a		4,8 kV
Output power	W_o	>	2,5 kW 2,3 kW
Efficiency	η	\approx	60 %

C. OPERATION WITH $W_o = 2,5$ kW FOR MICROWAVE OVENS

The average VSWR should be 3 at $d = 0,41 \lambda$.

LIMITING VALUES (Absolute maximum rating system)

Anode current, mean	I_a	max.	0,85 A
		min.	0,1 A
Anode current, peak	I_{ap}	max.	2,1 A
Voltage standing-wave ratio at $0,3 \lambda < d < 0,5 \lambda$	VSWR	max.	4
intermittent ($t = \text{max. } 0,02 \text{ s and max. } 20\% \text{ of the time}$)	VSWR	max.	10 **
remaining region	VSWR	max.	4

* With respect to reference plane B of fixed reflection element.

** The average reflected power for any one-second period must not exceed the reflected power equivalent to a VSWR of 4. When operating under these conditions, the tube should not be permitted to mode.

TYPICAL OPERATION

Heater voltage, running	V_f		1,8 V
Anode current, mean	I_a		0,8 A
Anode current, peak	I_{ap}		2 A
Anode voltage	V_a		4,95 kV
Voltage standing-wave ratio at $0,3 \lambda < d < 0,5 \lambda$	VSWR		3
Output power	W_o	>	2,5 kW 2,3 kW
Efficiency	η	≈	60 %

COOLING

Anode block	water
Required quantity of water	see cooling curve
Cathode radiator, via air duct	low-velocity air flow > 0,2 m ³ /min

TEMPERATURE LIMITS (Absolute maximum rating system)

Anode temperature at reference point for temperature measurement	T_a	max.	125 °C
Cathode radiator temperature	T	max.	180 °C

To safeguard the magnetron from overheating if the cooling fails, provision is made for mounting a thermoswitch. This switch should become operative at a temperature of 120 °C to 125 °C at the mounting plate.

MECHANICAL DATA

Net mass: ≈ 4,7 kg

Mounting position: any

ACCESSORIES

Cap nut	type	55312
Spring ring	type	55313
Heater connector	type	40634
Heater/cathode connector	type	40649

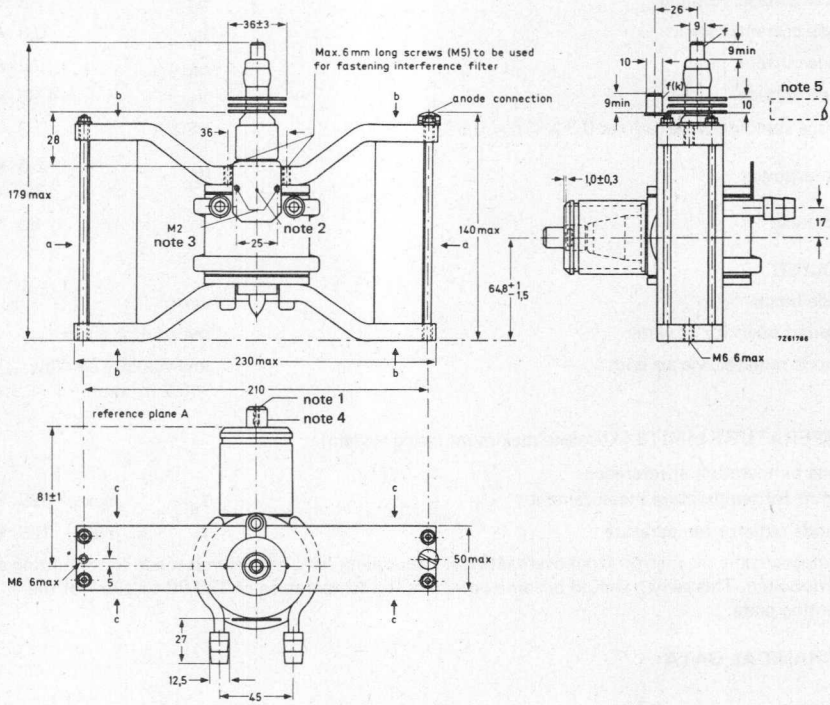


Fig. 1.

Notes

1. Axial hole for short antenna: M4, depth 9 mm minimum.
2. Reference point for temperature measurements.
3. Mounting holes for thermoswitch.
4. Eccentricity of inner conductor with respect to the outer conductor max. 0,4 mm.
5. Non-metallic air duct, inner diameter 13 mm.

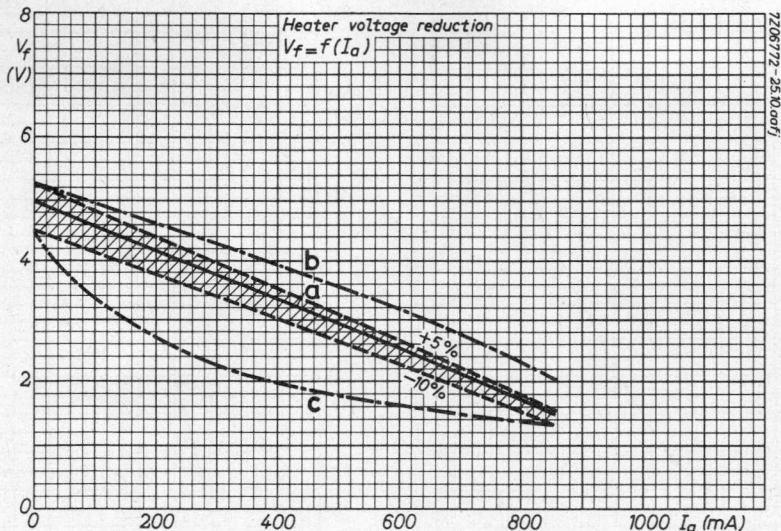


Fig. 2.

Immediately after applying the anode voltage the heater voltage must be reduced as a function of the anode current according to the diagram above. The life of the magnetron will be greatest if the heater voltage is reduced to a value given by the fully drawn line a. The heater voltage should be adjusted within +5 and -10% as given by the dashed lines which border the hatched area.

If the equipment has been designed for a predetermined number of steps of output power level, the reduced heater voltage for each step must be set to a value within the area bordered by the lines b and c, and preferably within or close to the hatched area. In no circumstances should the heater voltage reach a value outside the limits given by the curves b and c.

The limits $V_f = 5\text{ V} - 10\%$ and $t_w = 120\text{ s}$ should not be used simultaneously. With V_f below the nominal value, t_w should be increased in linear proportion up to min. 180 s at $V_f = 5\text{ V} - 10\%$. It is also possible to preheat the tube at stand-by conditions if the waiting time is extended to at least 10 minutes.

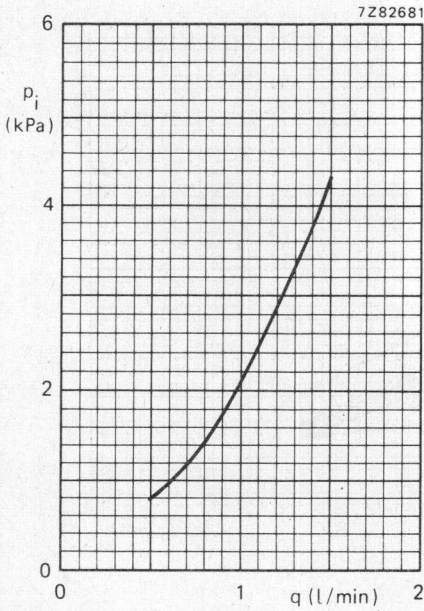


Fig. 3.

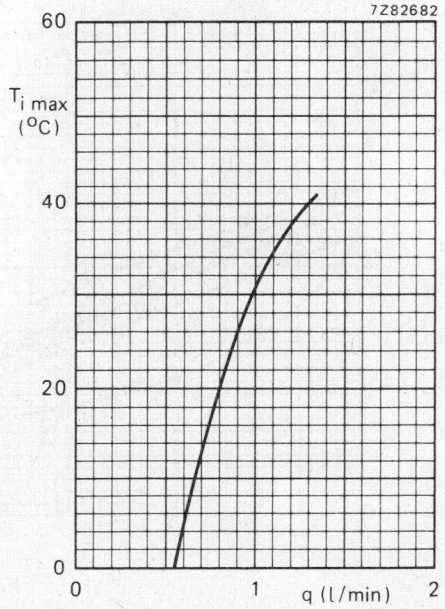
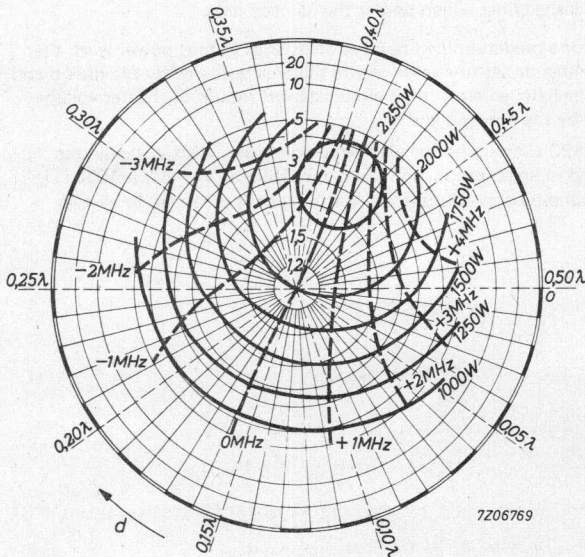


Fig. 4.

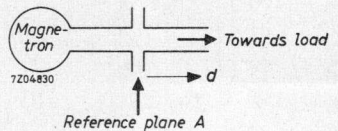


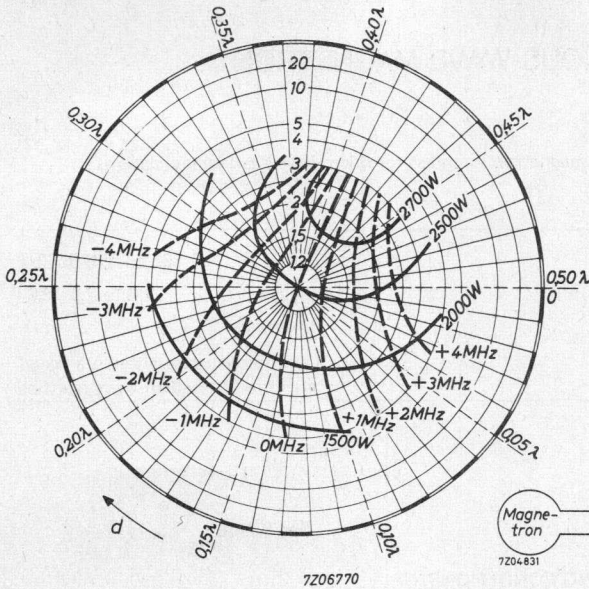
Load diagram Operation A

Fig. 5 Mean anode current 0,75 A
Peak anode current 2 A

d = distance of standing wave minimum from reference plane A towards load

Temperature at reference point 85 °C





Load diagram Operation B

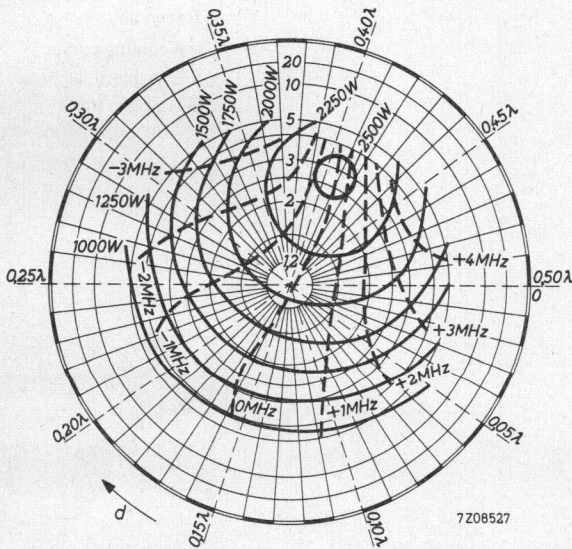
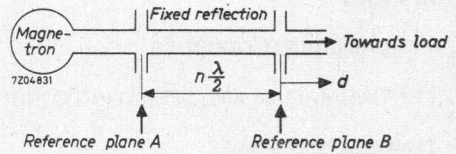
Fig. 6 Mean anode current 0,85 A

Peak anode current 2 A

Fixed reflection VSWR = 1,5
 $d = 0,41 \lambda$

d = distance of standing wave minimum from reference plane B towards load

Temperature at reference point 85 °C



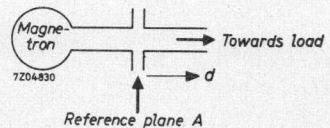
Load diagram Operation C

Fig. 7 Mean anode current 0,8 A

Peak anode current 2 A

d = distance of standing wave minimum from reference plane A towards load

Temperature at reference point 85 °C



CONTINUOUS-WAVE MAGNETRON

Continuous-wave air-cooled packaged magnetron intended for microwave heating applications.

QUICK REFERENCE DATA

Frequency, fixed within the band	f	2,425 to 2,475 GHz
Output power	W_o	2,0 to 2,5 kW
Construction		packaged
Anode supply		unfiltered single-phase full-wave, or three-phase half-wave rectified

CATHODE

HEATING

TYPICAL CHARACTERISTICS

LIMITING VALUES AND OPERATING CONDITIONS

TEMPERATURE LIMITS

COOLING

Anode block

Required quantity of air

Cathode radiator, via air duct

See YJ1160

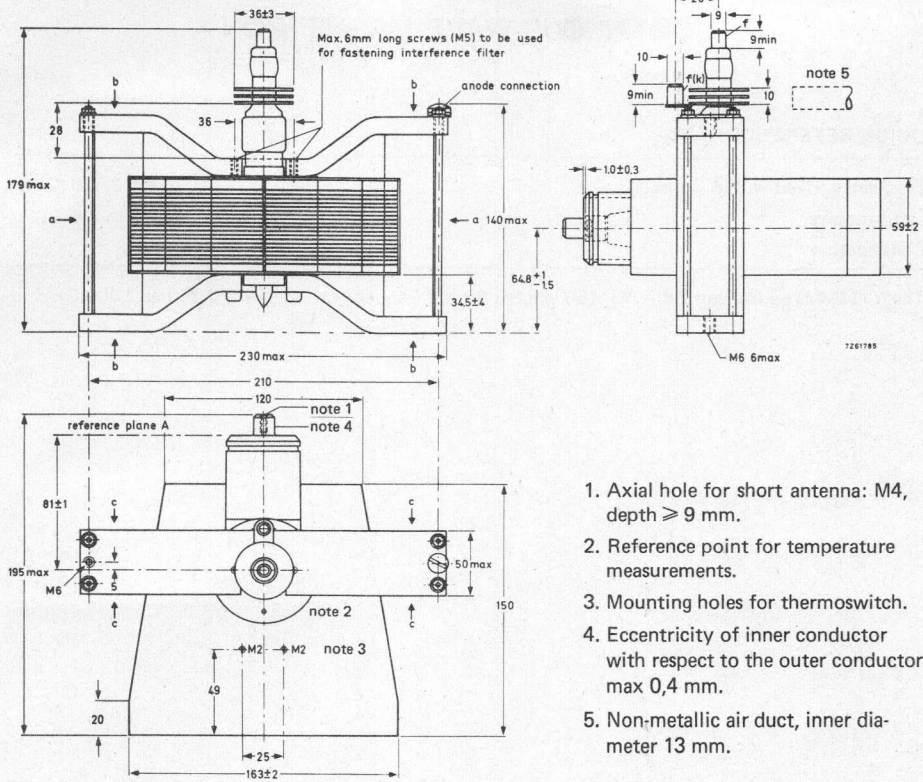
forced air

see cooling curve

low-velocity air flow
($> 0,2 \text{ m}^3/\text{min}$)

MECHANICAL DATA

Dimensions in mm



1. Axial hole for short antenna: M4, depth ≥ 9 mm.
2. Reference point for temperature measurements.
3. Mounting holes for thermoswitch.
4. Eccentricity of inner conductor with respect to the outer conductor max 0,4 mm.
5. Non-metallic air duct, inner diameter 13 mm.

Fig. 1.

CONTINUOUS-WAVE MAGNETRON

QUICK REFERENCE DATA

Frequency, fixed within the band	f	2,350 to 2,400 GHz
Output power	W_o	2,0 to 2,5 kW
Construction		packaged

The YJ1164 is equivalent to the YJ1160, except for the frequency band, being 2,350 to 2,400 GHz.

CONTINUOUS-WAVE MAGNETRON

Packaged, water-cooled continuous-wave magnetron with integral r.f. filter, intended for industrial microwave heating applications. The tube features a quick-heating cathode, high efficiency, and has a typical output power of 6 kW.

QUICK REFERENCE DATA

Frequency, fixed within the band	f	2,430 to 2,470 GHz
Output power	W_o	6 kW
Construction		packaged, metal ceramic
Cathode		quick heating
Cooling		water and air
R.F. filter		integral

TYPICAL OPERATION

Conditions

Filament voltage, starting	V_f	5,5 V
Waiting time	t_w	45 s
Filament voltage, operating	V_f	1,0 V
Anode supply		three-phase full-wave rectifier
Anode current, mean	I_a	1,25 A
Anode current, peak	I_{ap}	1,5 A
Load impedance		
Voltage standing-wave ratio	VSWR	1,5
Phase, in direction of load with respect to reference plane	d	0,42 λ
Cooling		see relevant paragraph

Performance

Filament current at $V_f = 1,0$ V	I_f	5 A
Anode voltage, mean	V_a	7,3 kV
Output power	W_o	6 kW
	W_o	> 5,4 kW
Efficiency	η	65 %

For other load impedance and anode current conditions see pages C22 and C23 and "Design and operating notes".

CATHODE: thoriated tungsten

HEATING: direct by a.c. (50 Hz or 60 Hz) or d.c.

With d.c. the filament terminal (f) must have positive polarity.

Filament voltage, starting and stand-by
operating at $I_{a\text{ mean}} = 1,25\text{ A}$

V_f		$5,5\text{ V} \pm 10\%$
V_f		$1,0\text{ V} \pm 10\%$

Filament current at $V_f = 5,5\text{ V}; I_a = 0$

I_f	<	44 A
		48 A

at $V_f = 1,0\text{ V}; I_{a\text{ mean}} = 1,25\text{ A}$

I_f		5 A
-------	--	-----

Filament starting current, peak

I_{fp}	max.	150 A
----------	------	-------

Cold filament resistance

R_{fo}		17 mΩ
----------	--	-------

Waiting time (time before application of high voltage)

t_w	min.	30 s
-------	------	------

Immediately after applying the anode voltage the filament voltage must be reduced to the operating value.

If it is intended to design the equipment for a variable output power, either continuously adjustable or stepped, the filament voltage must be reduced as a function of the anode current (see graph below).

The reduced filament voltage may be set to a value within the area bordered by the lines b and c, but for longest life it should be within the hatched area. In no circumstances should the filament voltage reach a value outside the limits given by the lines b and c.

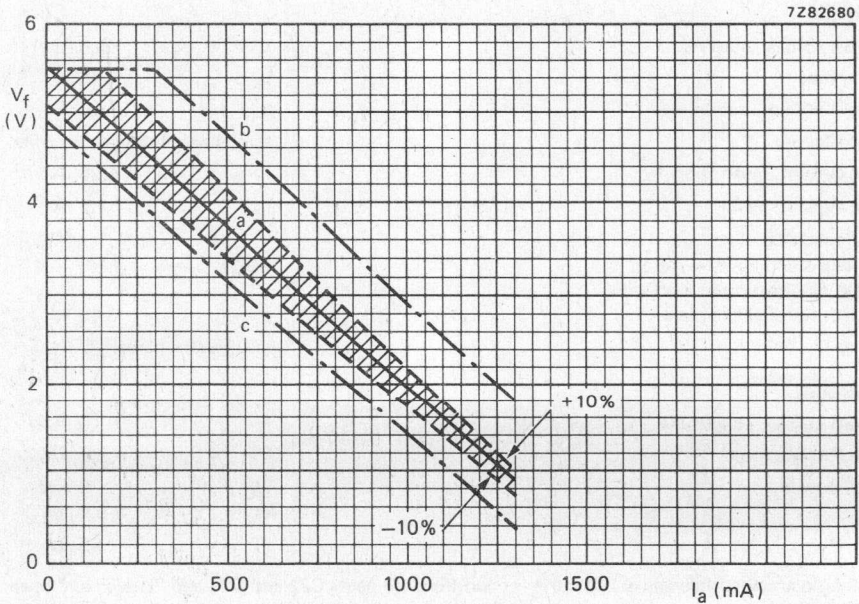


Fig. 1 Filament voltage reduction curve.

TYPICAL CHARACTERISTICS

Measured under matched load conditions ($V_{SWR} \leq 1,05$) and three-phase full-wave rectified supply.
(See "Design and operating notes".)

Frequency, fixed within the band	f	2,430 to 2,470	GHz
Anode voltage, mean	V_a	7,2	kV
Anode current, mean	I_a	1,25	A
Output power	W_o	5,5	kW

LIMITING VALUES (Absolute maximum rating system)

Anode current, mean	I_a	max.	1,3	A
Anode current, peak	I_{ap}	max.	1,7	A
Anode input power	W_{ia}	max.	9,6	kW
Temperature at reference point, closed cooling circuit	T_a	max.	85	°C
open cooling circuit	T_a	max.	70	°C
Cooling water outlet temperature, closed cooling circuit	T_o	max.	75	°C
open cooling circuit	T_o	max.	65	°C
Voltage standing-wave ratio	VSWR	max.	2,5	

COOLING

Anode block	water		
Minimum required rate of flow and pressure drop	see Fig. 11		
R.F. filter box	air		
Required rate of flow at room temperature	q	min.	60 l/min.
Pressure drop	see Fig. 12		
R.F. output system	air		
Required rate of flow at room temperature	q	min.	100 l/min.

With only the filament voltage applied some water and air cooling is required.

To safeguard the magnetron against overheating if the water cooling fails, provision is made for mounting a thermoswitch. This switch should operate at a mounting disc temperature of 70 °C for an open water cooling circuit and 85 °C for a closed system.

The r.f. output system of the magnetron is provided with air inlet and outlet holes for the application of at least 100 l/min of cooling air to the ceramic part inside the outer conductor. For an example of a cooling device around the output system see "Output coupling". All inlet holes must be used for entrance of air to obtain the required uniform cooling. The cooling air must be filtered to be free from dust, water and oil.

ACCESSORIES

Cap nut for output coupling

type 55312

Spring ring

type 55313

Soft copper washer, supplied with tube

type 55328

Cap nut

type TE1051b

Hose nipple

type TE1051c

Recommended isolator

2722 163 02004

Dimensions in mm

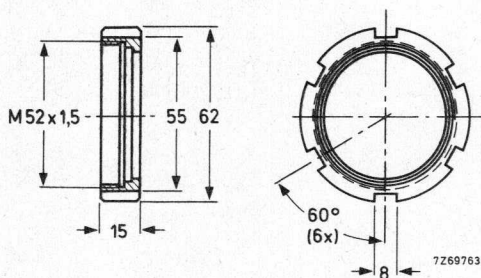


Fig. 2 Cap nut type 55312.

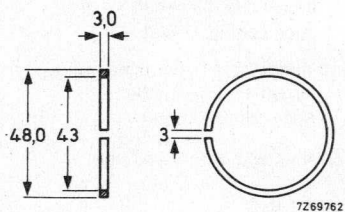


Fig. 3 Spring ring type 55313.

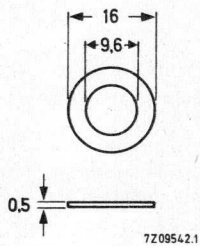


Fig. 4 Washer type 55328.

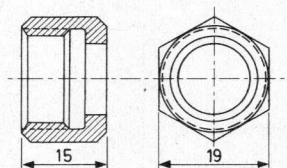


Fig. 5 Cap nut type TE1051b (thread 3/8 in gas).

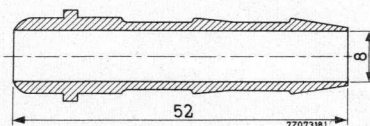


Fig. 6 9 mm hose nipple type TE1051c.

DESIGN AND OPERATING NOTES

General

Whenever it is considered necessary to operate the magnetron at conditions substantially different from those indicated under "Typical operation" the tube manufacturer should be consulted.

The equipment should be designed around the tube specifications given in this data and not around one particular tube since, due to normal production variations, the electrical and mechanical parameters will vary around the nominal values.

Anode supply

The magnetron may be operated from a three-phase full-wave rectified supply unit. This unit should be so designed that no limiting value for the mean and peak anode currents is exceeded, whatever the operating conditions. The use of a current regulating and limiting device is recommended.

Filament supply

The secondary of the filament transformer must be well insulated from the primary since in normal magnetron operation the anode is earthed and the cathode will be at high negative potential with respect to the anode.

The transformer should be so designed that the filament voltage and the peak filament starting current limits are not exceeded.

Load impedance

Optimum output power and life are obtained when the magnetron is loaded with an impedance giving a VSWR of approximately 1,5 in the phase of sink region. This phase condition is reached when the position of the voltage standing wave minimum is at a distance of about $0,42 \lambda$ from the reference plane for electrical measurements (see outline drawing) in the direction of the load.

When using the coaxial-to-R26 waveguide transition shown in Fig. 9 this condition is automatically reached, provided antenna type B is used. Antenna type A, together with the above transition, gives a VSWR of about 1 (matched). Detailed construction drawings available on request.

Tube cleanness

The ceramic parts of the cathode and output structure of the tube must be kept clean during operation. The cooling air should be filtered to prevent deposits forming on the insulation.



STORAGE, HANDLING AND MOUNTING

Storage and handling

The original pack should be used for transporting and storing the tube. Shipment of the tube mounted in the equipment is only permitted if specifically authorized by the manufacturer.

When the tubes have to be unpacked, e.g. at an assembly line for measurement purposes, care should be taken that a minimum distance of 13 cm is maintained between the tubes. As the thoriated tungsten filament is sensitive to shocks and vibration, care should be taken when handling unpacked tubes that undue shocks and vibrations are avoided. High intensity magnetic fields associated with transformers and other magnetic equipment can demagnetize the magnets. Such fields should not be present when the tube is stored or serviced. The best protection of the tube is its original pack.

The user should be aware of the strong magnetic fields around the magnet. When handling and mounting the magnetron, he must use non-magnetic tools and be extremely careful not to have precision instruments nearby.

Mounting

When magnetic materials are present in two or more planes, their minimum distance from the magnet shall be 13 cm in all directions.

All tools (screwdrivers, wrenches, etc.) used close to or in contact with the magnetron must be made of non-magnetic material to avoid unwanted attraction and possible mechanical damage to ceramic parts as well as short-circuit of the magnetic flux.

To prevent mechanical stresses and torques, the output coupling should not be used as the only means of mounting; an additional flexible support of the tube is necessary.

OUTPUT COUPLING

The output system of the magnetron must be coupled via a 16/39 coaxial line (characteristic impedance 53,4 Ω (see Fig. 7) to the load system.

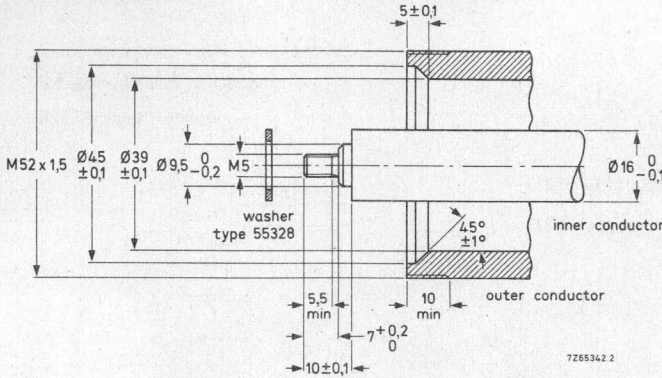


Fig. 7 Output coupling.

The inner conductor should be able to accept the tolerances of the magnetron output system (see outline drawing) and thermal expansion.

The soft copper washer type 55328 shall be used between the inner conductor and the magnetron output system. A firm contact between antenna and inner conductor of tube must be assured.

When screwing the inner conductor into the magnetron output system the maximum permissible torque is 1,5 Nm.

Example of a cooling device for output system (not supplied by the manufacturer)

Material: non-magnetic

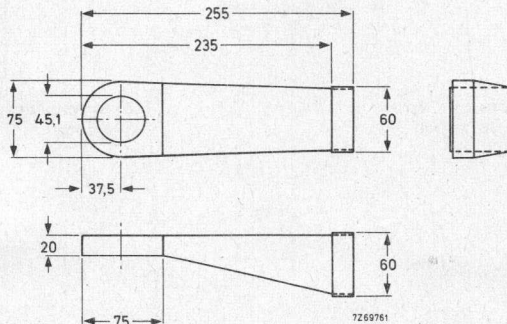


Fig. 8 Cooling device.

Pressure drop at 100 l/min:

about 600 Pa with air outlet via outlet holes;

about 300 Pa if air can also escape towards the load through coaxial line.

An example of the coupling of the tube via a coaxial to an R26 waveguide transition is shown in Fig. 9.

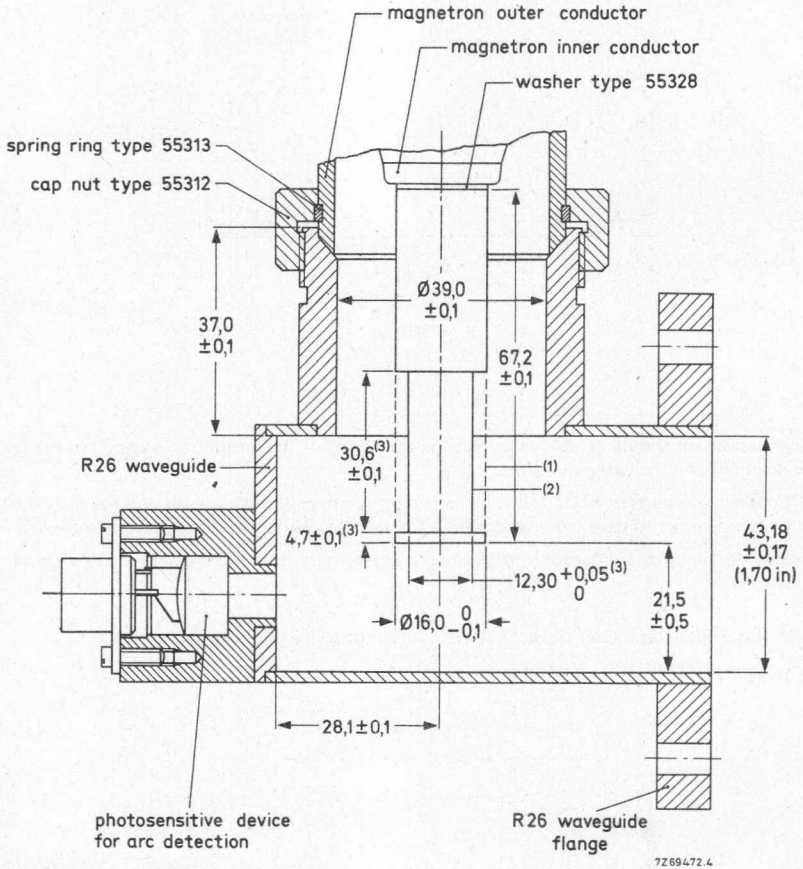


Fig. 9.

- (1) Antenna type A (cylindrical) for matched load.
- (2) Antenna type B, VSWR ≈ 1,5 in direction of sink for matched waveguide load.
- (3) These dimensions for antenna type B only.

MECHANICAL DATA

Dimensions in mm

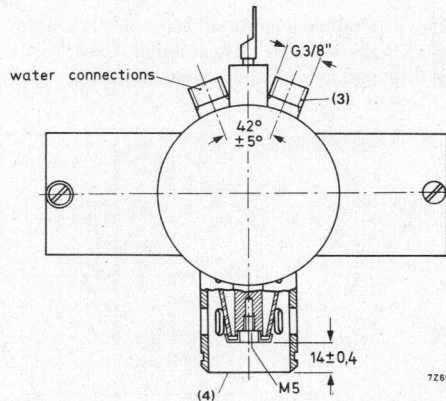
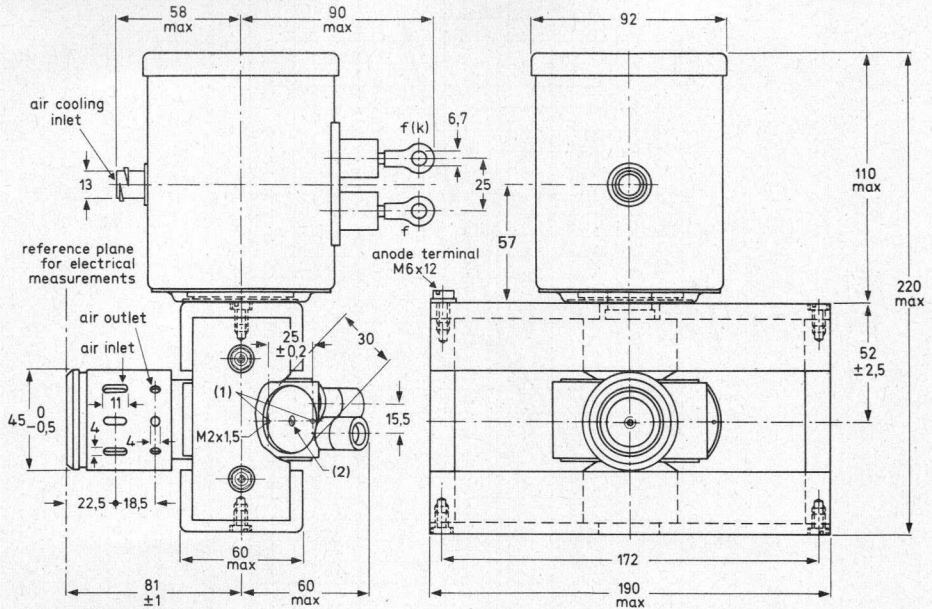


Fig. 10 Outline drawing.

Mounting position: any

Net mass: approx. 4,7 kg

- (1) Two M2 screws for mounting a thermoswitch are supplied with the magnetron.
- (2) Plate for mounting a thermoswitch; temperature reference point.
- (3) To be connected to hose nipple type TE1051c (DIN 44415) for 9 mm hose with cap nut type TE1051b (CR3/8 in DIN 8542 Ms).
- (4) Eccentricity of inner conductor with respect to outer conductor max. 0,4 mm.

7269637.2

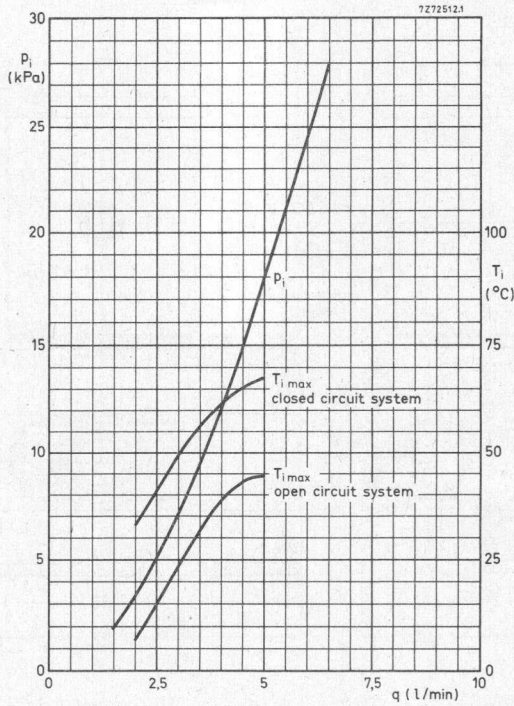


Fig. 11 Minimum required quantity of water q , and pressure drop p_i as a function of water inlet temperature T_i . Water supplied via hose nipple TE1051c. If additional information is required please contact the manufacturer.

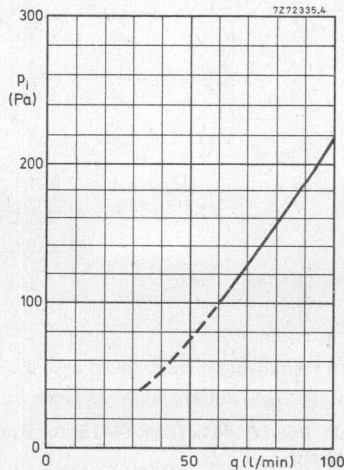


Fig. 12 Pressure drop as a function of air flow through filter box.

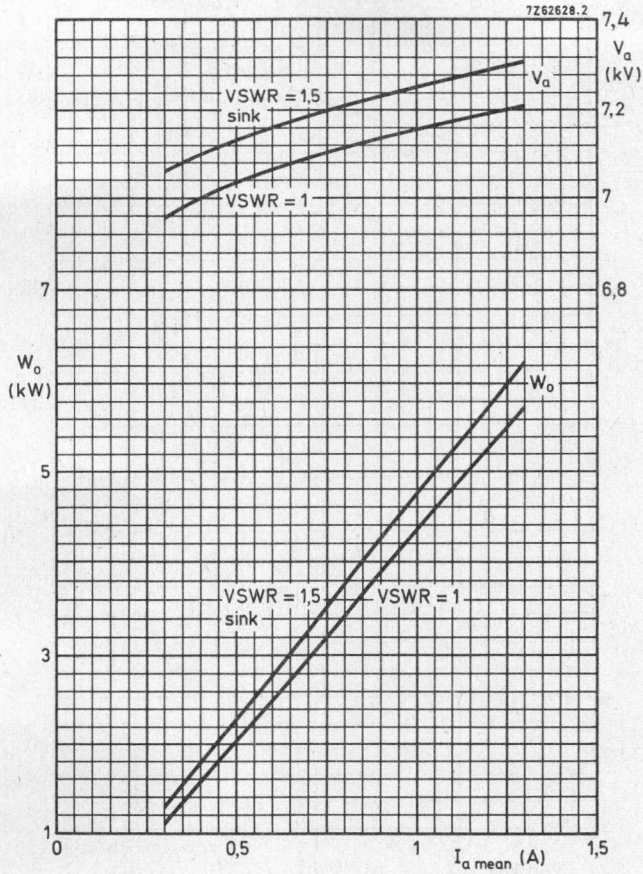


Fig. 13 Output power and anode voltage as a function of anode current.

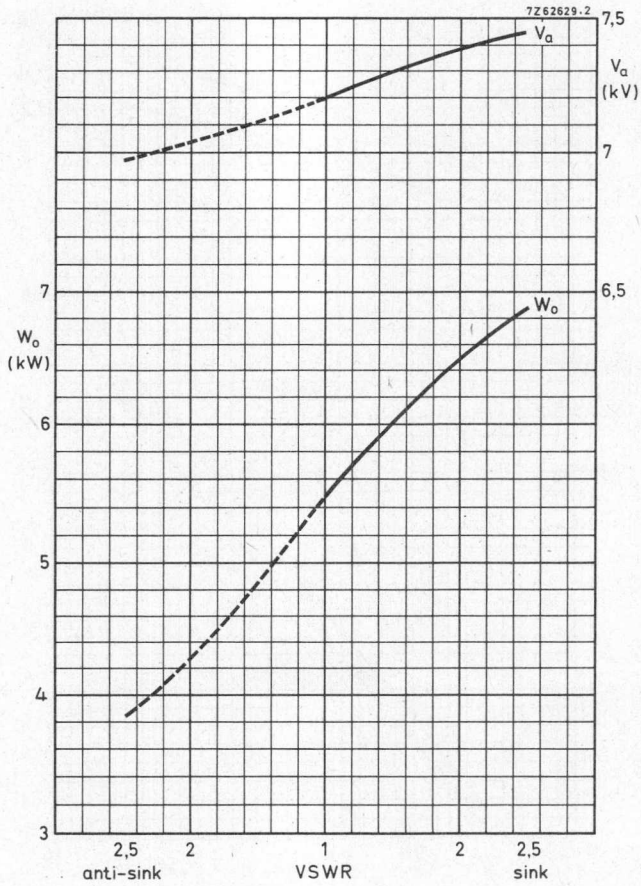


Fig. 14 Output power and anode voltage as a function of load impedance, $V_f = 1,0 \text{ V}$; $I_a \text{ mean} = 1,25 \text{ A}$.

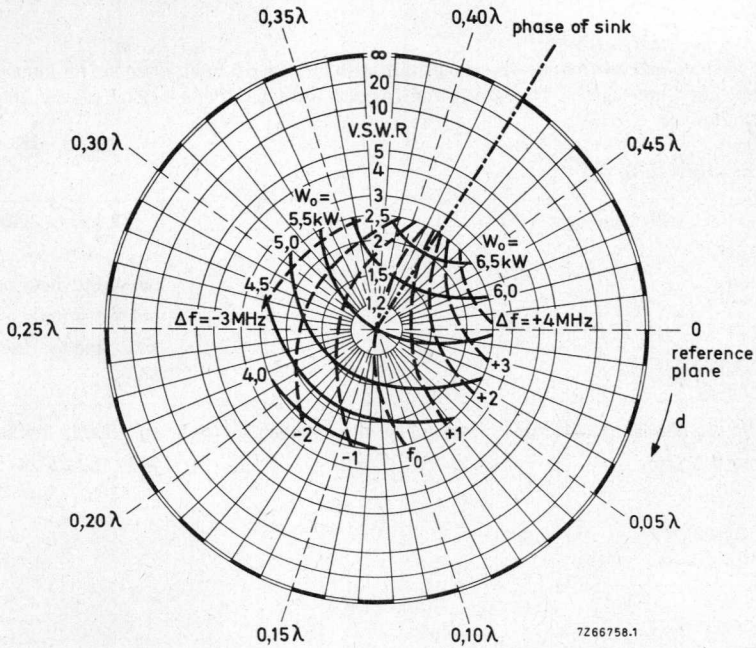


Fig. 15 Load diagram.

- | | |
|---|---------------------------------|
| Anode supply | three-phase full-wave rectified |
| Filament voltage | 1 V |
| Anode current, mean | 1,25 A |
| Anode current, peak | 1,5 A |
| Constant cooling | |
| d = distance of standing wave minimum from reference plane towards load | |

CONTINUOUS-WAVE MAGNETRON

Packaged, water-cooled continuous-wave magnetron with integral r.f. filter, intended for industrial microwave heating applications. The tube features a quick-heating cathode, high efficiency, and has a typical output power of 6 kW.

QUICK REFERENCE DATA

Frequency, fixed within the band	f	2,350 to 2,400 GHz
Output power	W_o	6 kW
Construction		packaged, metal-ceramic
Cathode		quick-heating
Cooling		water and air
R.F. filter		integral

The YJ1194 is equivalent to the YJ1193, except for the frequency band, being 2,350 to 2,400 GHz.

Recommended isolator

2722 163 02024

CONTINUOUS-WAVE MAGNETRON

The YJ1280 is an integral magnet c.w. magnetron designed for use in microwave heating applications. With an LC stabilized power supply, it can produce up to 1,5 kW under typical operating conditions. The magnetron is air-cooled and is of a metal-ceramic construction.

QUICK REFERENCE DATA

Frequency, fixed within the band	f	2,425 to 2,475 GHz
Output power	W_O	1,5 kW
Construction		metal-ceramic, packaged

TYPICAL OPERATION

Anode supply		L-C stabilized	
Filament voltage, stand-by	V_f	5,0 V	
Filament voltage, operating	V_f	3,5 V	
Anode current, mean *	I_a	380 mA	
Anode current, peak	I_{ap}	650 mA	
Load impedance	VSWR	2,5	
	in direction of sink		matched
Anode voltage*	V_a	5,7	5,7 kV
Output power	W_O	1,5	1,3 kW
			min. 1,15 kW

For other load impedance and anode current conditions see Figs 3 and 10.

CATHODE: Thoriated tungsten

HEATING: direct by a.c. (50 Hz or 60 Hz) or d.c.**

Filament voltage, starting and stand-by	V_f	5,0 V ± 10%
Filament voltage, operating at I_a mean = 380 mA	V_f	3,5 V ± 10%
Filament current at $V_f = 5,0$ V and $V_a = 0$ V	I_f	typ. 28 A max. 32 A
Filament peak starting current	I_{fp}	max. 70 A
Cold filament resistance	R_{fo}	approx. 0,020 Ω
Waiting time (time before application of high voltage)	t_w	min. 10 s

* Measured with a moving-coil instrument.

** With d.c. heating the filament connector must have positive polarity.

TYPICAL CHARACTERISTICS

			notes
Frequency, fixed within the band	f	2,425 to 2,475 GHz	1
Anode voltage at I_a mean = 380 mA	V_a	5,8 $\begin{smallmatrix} +0 \\ -0,4 \end{smallmatrix}$ kV	1,2,3
Output power into matched load	W_o	1,3 kW	

LIMITING VALUES (Absolute maximum rating system)

Anode current, mean	I_a	max.	450 mA	2
	I_a	min.	100 mA	
Anode current, peak at I_a mean = 380 mA	I_{ap}	max.	800 mA	2
Anode voltage, positive and negative	V_a	max.	10 kV	4
Anode input power	W_{ia}	max.	2,7 kW	
Voltage standing-wave ratio (measured with probe 55336) continuous	VSWR	max.	4	5
	VSWR	max.	10	
during max. 0,02 s and max. 20% of the time				
Anode temperature at reference point indicated on outline drawing	T_a	max.	180 °C	
Temperature at any other point on the tube	T	max.	200 °C	

COOLING

Anode block		forced air
Filament terminal structure		forced air
Inlet air, typical		
Temperature	T_i	35 °C
Quantity	q	1,2 m ³ /min
Pressure drop	p_i	100 Pa

It is recommended that a thermoswitch be mounted at the place indicated in the outline drawing to protect the magnetron against overheating.

On stand-by, with $V_f = 5,0$ V, some air-cooling is necessary to keep the temperature of the filament terminal, the filament/cathode terminal and the anode block below the maximum limit.

Notes

1. Measured under matched load conditions ($VSWR \leq 1,05$).
2. Measured with a moving-coil instrument.
3. Measured on a filtered anode voltage supply ($I_{ap} \leq 480$ mA).
4. It is recommended that a suitable spark gap be connected between the filament connectors and the anode (earth) to prevent the maximum anode voltage being exceeded.
5. This means: Any period of time up to 0,02 s during which the VSWR is between 4 and 10 must be followed by a period four times as long during which the VSWR is < 4 . When operated under these conditions the magnetron should not be permitted to mode.

DESIGN AND OPERATING NOTES

General

Whenever it is considered necessary to operate the magnetron at conditions substantially different from those indicated under "Typical operation" the tube manufacturer should be consulted.

The equipment should be designed around the tube specifications given in this data and not around one particular tube since, due to normal production variations, the design parameters (V_a , R_{fo} , f , W_o etc.) will vary around the nominal values.

Anode supply

It is recommended that the magnetron be operated from an LC stabilized anode supply unit. The unit should be designed so that the limiting values for mean and peak anode current are not exceeded.

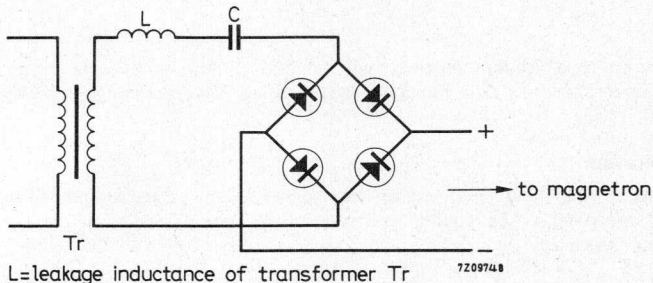


Fig. 1 Basic series resonant circuit of an LC power supply.

Filament supply

The secondary of the filament transformer must be well insulated from the primary since in normal magnetron operation the cathode will be at high negative potential and the anode will be earthed.

The transformer should be designed so that the filament voltage and surge current limits are not exceeded.

Filament/cathode connectors

The magnetron has a high filament current and losses in filament voltage caused by bad connections will result in poor operation. Therefore, it is important to ensure that the filament and filament/cathode connectors make good electrical and thermal contact with their respective terminals.

The connectors, types 55323 and 55324, shown in the drawings have been designed to give the required contact and are recommended for use with this magnetron. A coating of a high temperature resistant silicone grease is recommended to prevent oxidation.

The electrical conductors of the cathode and filament connectors should be of flexible construction in order to eliminate undue stress on the terminals.

Load impedance, measured with measuring probe

The probe 55336 measures the r.f. output system of the magnetron; it may be coupled to a waveguide, a coaxial line, or directly into a cavity in place of the magnetron; in all cases the type 55341 gasket should be used. The termination of the probe matches a standard male N-type connector.

The use of this measuring probe enables the designer of microwave heating equipment to determine the value of the load impedance (VSWR and phase of reflection), using standard cold measuring techniques, and to arrive at the correct coupling for the magnetron.

Antenna

When an antenna is used, the part of the antenna screwed into the magnetron should be according to Fig. 2.

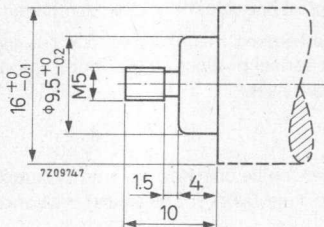


Fig. 2.

A soft copper washer of 0,5 mm thickness type no. 55328 is required between the antenna and the tube to ensure reliable r.f. contact. The maximum torque applied when screwing the antenna into the tube is 150 Ncm.

Stand-by operation

Without anode voltage, the filament voltage during any stand-by period should be kept at $V_f = 5,0$ V. Some forced-air cooling will be required to prevent overheating. The full anode voltage may be applied without further waiting time.

Shielding

Where required, r.f. radiation from the filament terminals may be reduced by external filtering and/or shielding. Detailed information may be obtained from the manufacturer.

Tube cleanliness

The ceramic parts of the input and output structures of the tube must be kept clean during operation. A protective cover of suitable material should be placed over the tube output if the tube is inserted directly into a cavity. The cooling air should be filtered and ducted to prevent deposits forming on the insulation during operation.

Output coupling

The tube may be coupled by suitable means to a waveguide, a coaxial line, or directly into a cavity.

HANDLING, STORAGE AND MOUNTING

Handling and storage

The original pack should be used for transporting and storing the tube. Shipment of the tube mounted in the equipment is not permitted unless specifically authorized by the tube manufacturer.

When the tubes have to be unpacked, e.g. at an assembly line or for measurement purposes, care should be taken that a minimum distance of 15 cm is maintained between magnets. As the thoriated tungsten filament is sensitive to shocks and vibration, care should be taken when handling and storing unpacked tubes that such shocks and vibration are avoided. High intensity magnetic fields associated with transformers and other magnetic equipment can demagnetize the magnets. Such fields should not be present when the tube is stored, handled or serviced. The best protection of the tube is its original pack.

The user should be aware of the strong magnetic fields around the magnet. When handling and mounting the magnetron, he must use non-magnetic tools and be extremely careful not to have watches and other precision instruments nearby.

Mounting

When magnetic materials are present in two or more planes, the minimum distance from the magnet shall be 13 cm in all directions.

In order to assure a good r.f. contact between the output of the tube and the circuit in which it is connected, the use of the gasket 55341 is essential.

The output coupling of the tube should not be used as the only means of mounting the magnetron. The magnetron should be mounted and secured by the two mounting holes indicated on the outline drawing. When mounting the magnetron, all tools (screwdrivers, wrenches etc.) used close to or in contact with the magnetron must be made of non-magnetic material to avoid unwanted attraction and possible mechanical damage to ceramic parts as well as short-circuiting of the magnetic flux.

The power supply lead to the anode shall be connected to one of the mounting holes (see "a" on the outline drawing).

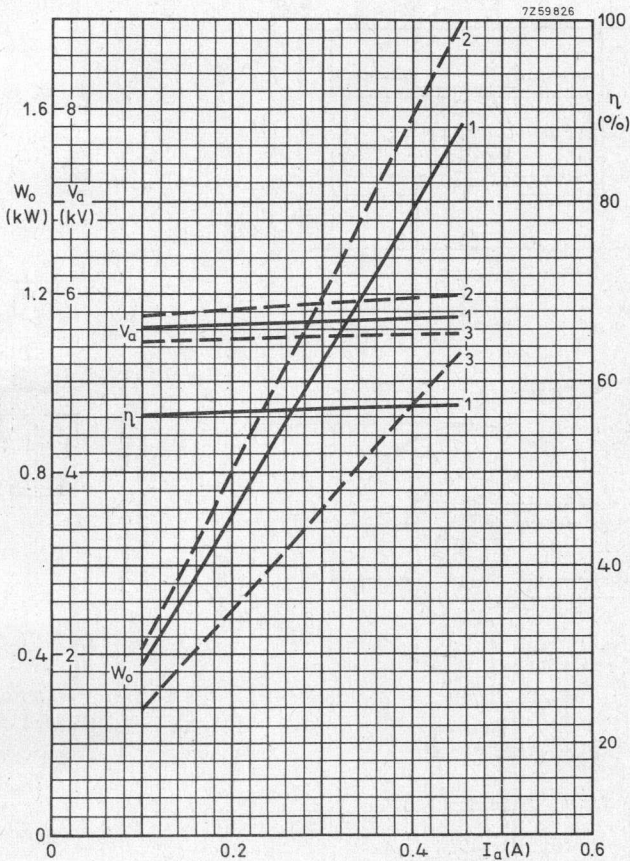


Fig. 3.
 1) with VSWR $\leq 1,05$
 2) with VSWR = 3 in sink region
 3) with VSWR = 3 in anti sink region

ACCESSORIES

Dimensions in mm

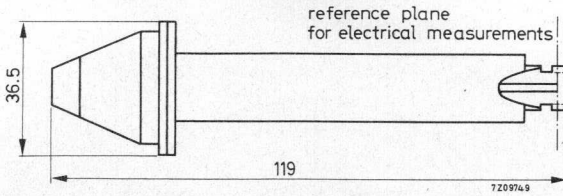


Fig. 5 Measuring probe 55336, for cold measurements only.

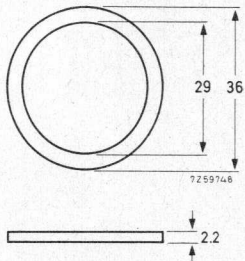
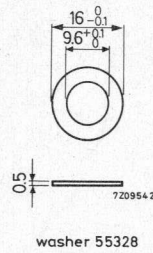


Fig. 6 R.F. gasket 55341, material: monel mesh.



washer 55328

Fig. 7 Washer 55328, material: soft copper.

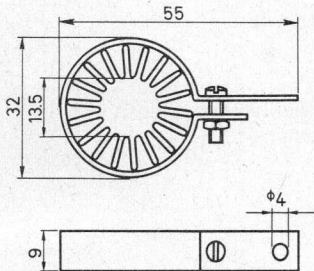


Fig. 8 Filament/cathode connector 55324.

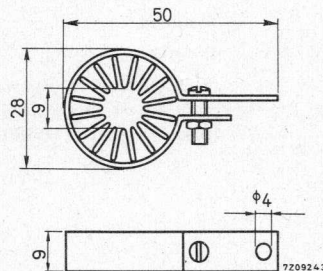


Fig. 9 Filament connector 55323.

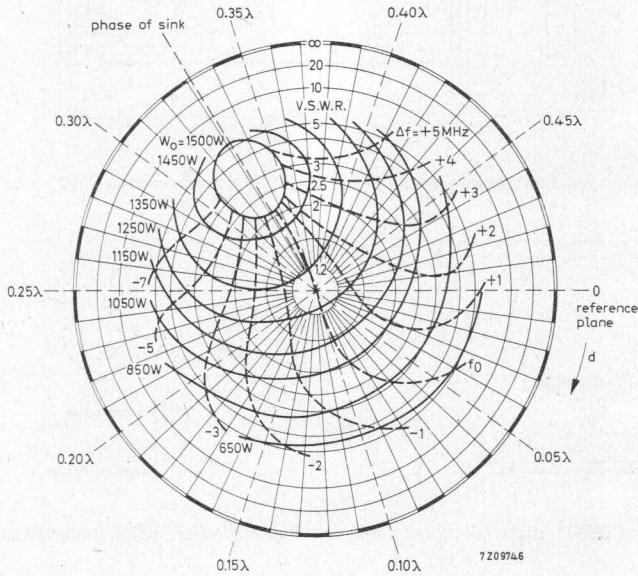


Fig. 10 Load diagram.

Mean anode current 380 mA

Frequency f_0 2,450 GHz

Constant air cooling

d= distance of voltage standing wave minimum from the reference plane for electrical measurements (measuring probe 55336) towards load

CONTINUOUS-WAVE MAGNETRON

Integral-magnet, forced-air cooled continuous-wave magnetron with integral r.f. filter intended for microwave heating applications. The tube features a quick-heating cathode, high efficiency, and has a typical output power of 2,5 kW.

QUICK REFERENCE DATA

Frequency, fixed within the band	f	2,425 to 2,475 GHz
Output power	W_o	2,5 kW
Construction		packaged, metal-ceramic
Cathode		quick heating
R.F. filter		integral

TYPICAL OPERATION with the tube coupled to an R26 waveguide according to Fig. 3

Conditions

Filament voltage, starting	V_f	5,0 V
Waiting time	t_w	7 s
Filament voltage, operating	V_f	3,5 V
Anode supply		L-C stabilized
Anode current, mean	I_a	680 mA
Anode current, peak	I_{ap}	1100 mA
Load impedance, measured with probe 55345		
Voltage standing-wave ratio	VSWR	2,5
Phase, in direction of load, with respect to reference plane	d	0,14 λ
Cooling; rate of flow	q	min. 2,5 m ³ /min*

Performance

Filament current at $V_f = 3,5$ V	I_f	27 A
Anode voltage, peak	V_{ap}	5,7 kV
Output power	W_o	2,5 kW
	W_o	min. 2,25 kW
Efficiency	η	69 %

CATHODE: Thoriated tungsten

* Based on a cooling air inlet temperature $T_i = \text{max. } 50^\circ\text{C}$.

HEATING: direct by a.c. (50 Hz or 60 Hz) or d.c.

With d.c. the terminal f(k) must have positive polarity.

Filament voltage, starting and stand-by	V_f	5,0 V \pm 10%
operating at $I_a \text{ mean} = 680 \text{ mA}$	V_f	3,5 V \pm 10%
Filament current at $V_f = 5,0 \text{ V}$, $I_a = 0$	I_f	41 A
		45 A
at $V_f = 3,5 \text{ V}$, $I_a = 680 \text{ mA}$	I_f	27 A
Filament current, peak starting	I_{fp}	max. 150 A
Cold filament resistance	R_{fo}	13 m Ω
Waiting time (time before application of high voltage)	t_w	min. 6 s

TYPICAL CHARACTERISTICS

Measured under matched load conditions (VSWR \leq 1,05) and L-C stabilized power supply. (See "Design and operating notes".)

Frequency, fixed within the band	f	2,425 to 2,475 GHz
Anode voltage, peak	V_{ap}	5,5 kV
Anode current, mean	I_a	700 mA
Output power	W_o	2,2 kW

LIMITING VALUES (Absolute maximum rating system)

Anode current, mean	I_a	max.	750 mA
Anode current, peak	I_{ap}	max.	1250 mA
Anode voltage*	V_a	max.	10 kV
Temperature of mounting bracket at central contact point of thermoswitch (see also under "Cooling")	T	max.	140 $^{\circ}\text{C}$
Voltage standing-wave ratio, measured with probe 55345 during max. 0,02 s and max. 20% of the time	VSWR	max.	5
	VSWR	max.	10

Any period of time up to 0,02 s during which the VSWR is between 5 and 10 must be followed by a period four times as long during which the VSWR is \leq 5. When operating under these conditions the magnetron should not be permitted to mode.

COOLING

Anode block and filament structure forced air

For pressure drop as a function of rate of flow see Fig. 8.
 The cooling air must be so ducted that it is uniformly distributed.
 Direction of air flow: see outline drawing.

With only the filament voltage applied some air cooling is required to keep the temperature below the limiting value.

The magnetron is provided with a normally closed thermoswitch to protect the tube against overheating. The thermoswitch is rated 250 V (a.c.), 10 A. Switching-off temperature $135 \pm 5 \text{ }^{\circ}\text{C}$.

* It is recommended that a suitable spark gap be connected between the filament/cathode terminal and the anode (earth) to prevent the max. anode voltage being exceeded.

DESIGN AND OPERATING NOTES

General

Whenever it is considered necessary to operate the magnetron at conditions substantially different from those indicated under "Typical operation" the tube manufacturer should be consulted.

The equipment should be designed around the tube specifications given in this data and not around one particular tube since, due to normal production variations, the design parameters (V_a , R_{fo} , f , W_o etc.) will vary around the nominal values.

ANODE SUPPLY

The magnetron may be operated from an L-C stabilized power supply. Detailed information on power supply design available on request.

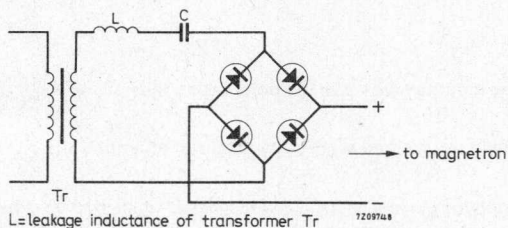


Fig. 1 Basic series resonant circuit of an L-C power supply.

Filament supply

The secondary of the filament transformer must be well insulated from the primary since during normal magnetron operation the anode is earthed and the cathode will be at a high negative potential with respect to the anode.

The transformer should be so designed that the filament voltage and peak filament starting current limits are not exceeded.

Filament and filament/cathode connections

The magnetron has a high filament current and losses in filament voltage caused by bad connections, will result in poor operation. Therefore, it is important to ensure that the leads make good electrical and thermal contact with the tube terminals.

Load impedance, measured with measuring probe

The probe 55345 simulates the r.f. output system of the magnetron; it may be coupled to an R26 waveguide to replace the magnetron; in all cases the type 55344 gasket should be used. The termination of the probe matches a standard N-type connector.

This measuring probe enables the designer of the microwave heating equipment to determine the value of the load impedance (VSWR and phase of reflection), using standard cold measuring techniques, and to arrive at the correct coupling for the magnetron.

Tube cleanness

The ceramic parts of the input and output structure of the tube must be kept clean during installation and operation. The cooling air should be filtered to prevent deposits forming on the insulation.

STORAGE, HANDLING AND MOUNTING

Storage and handling

The original pack should be used for transporting the tube. Shipment of the tube mounted in the equipment is permitted if specifically authorized by the manufacturer.

When the tubes have to be unpacked, e.g. at an assembly line or for measurement purposes, care should be taken that a minimum distance of 13 cm is maintained between tubes. As the thoriated tungsten filament is sensitive to shocks and vibration, care should be taken when handling and storing unpacked tubes that such shocks and vibration are avoided. High intensity magnetic fields associated with transformers and other magnetic equipment can demagnetize the magnets. They should not be present when the tube is stored or serviced. The best protection of the tube is its original pack.

The user should be aware of the strong magnetic fields around the tube. When handling and mounting the magnetron, he must use non-magnetic tools and be extremely careful not to have precision instruments nearby.

Mounting

The magnetron should be mounted with two M4 bolts fitting the nuts on the mounting bracket (see outline drawing).

The output coupling should not be used as the only means of mounting and be kept free from undue stress.

The minimum distance between the magnetron and magnetized materials shall be 13 cm. The minimum distance between the magnetron and other ferromagnetic materials shall be 3 cm.

The gasket 55344 is essential to ensure good r.f. contact between the output of the magnetron and the waveguide to which it is connected.

All tools (screwdrivers, wrenches, etc.) used close to or in contact with the magnetron must be of non-magnetic material to avoid unwanted attraction and possible mechanical damage to ceramic parts as well as short-circuit of the magnetic flux.

MECHANICAL DATA

Mounting position: any

Net mass: approx. 2 kg

ACCESSORIES

Thermoswitch, mounted on tube	type 55347
R.F. gasket, supplied with tube	type 55344
Measuring probe (for measurements only, see Fig. 2)	type 55345

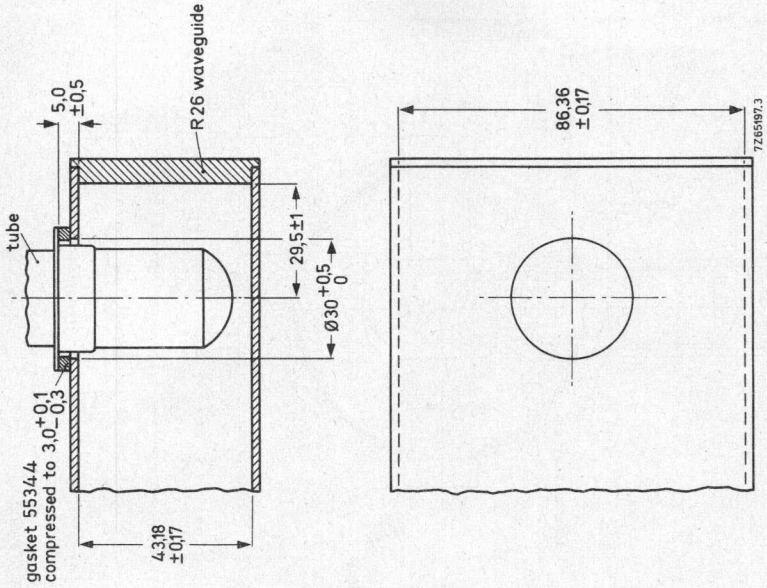


Fig. 3 Launching section.

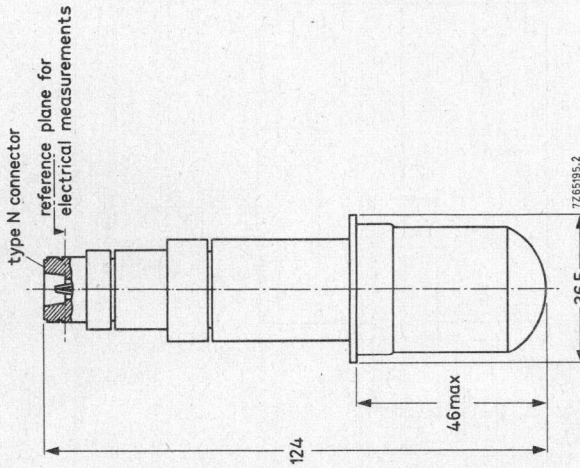


Fig. 2 Measuring probe 5534/5.

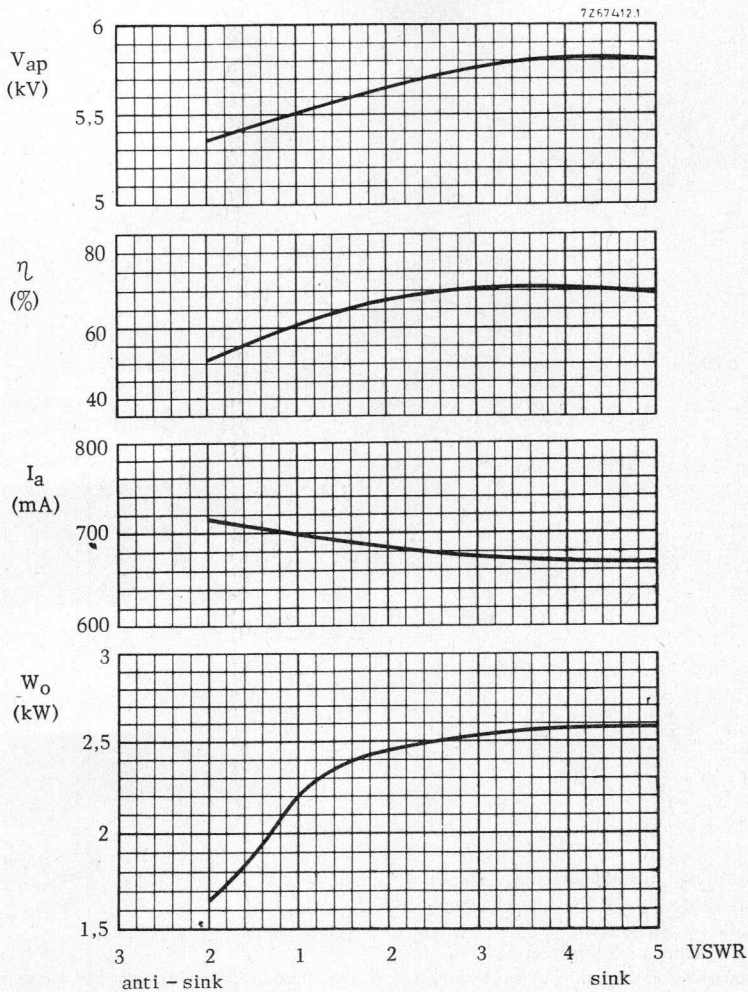


Fig. 5.

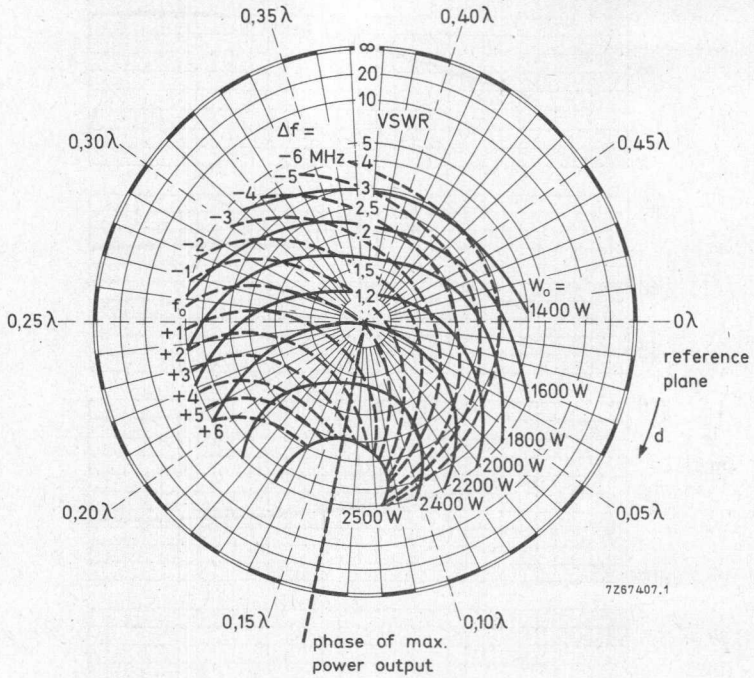


Fig. 6 Load diagram.

Measured with an L-C stabilized power supply.

Mean anode current $I_a = 700 \text{ mA}$ at matched load.

Frequency $f_0 = 2,450 \text{ GHz}$.

Constant air cooling $q = 2,5 \text{ m}^3/\text{min}$.

d = Distance of voltage standing wave minimum from the reference plane for electrical measurements (measuring probe 55345) towards load.

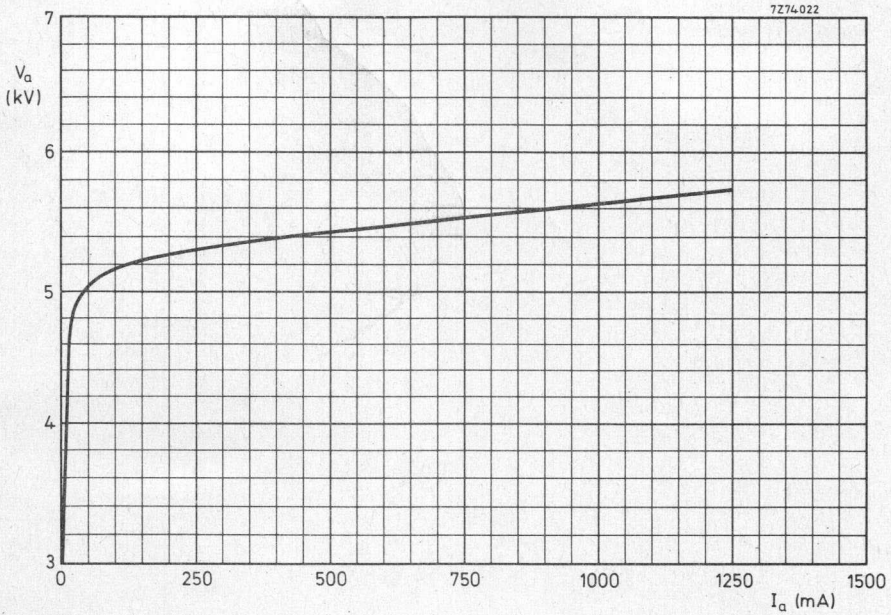


Fig. 7 Dynamic characteristic; anode voltage as a function of anode current at VSWR = 2,5 in direction of sink.

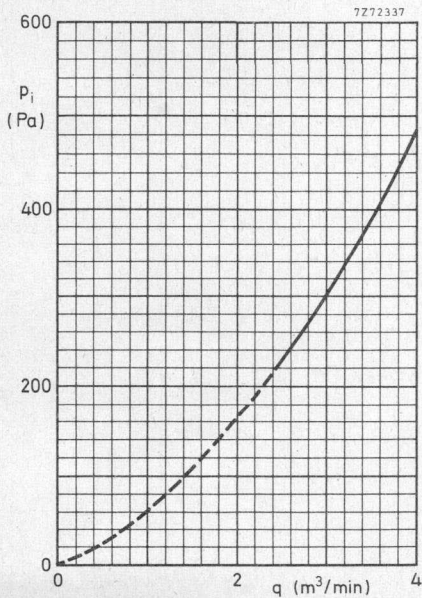
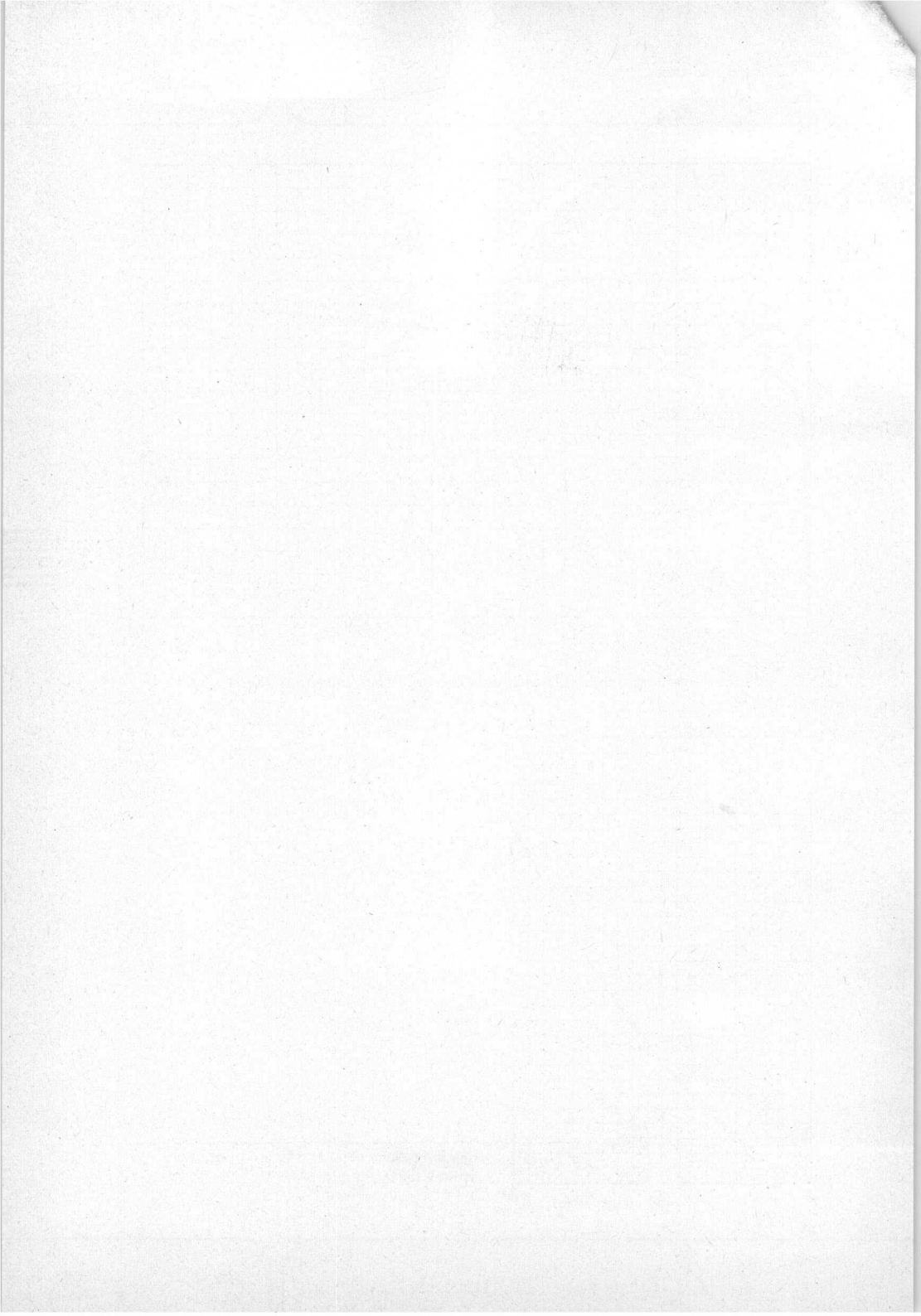


Fig. 8 Pressure drop as a function of rate of flow (air).



CONTINUOUS-WAVE MAGNETRON

Integral-magnet, water cooled continuous-wave magnetron with integral r.f. filter, intended for industrial microwave applications. The tube features a quick-heating cathode, high efficiency, and has a typical output power of 3 kW.

QUICK REFERENCE DATA

Frequency, fixed within the band	f	2,425 to 2,475 GHz
Output power	W_o	3 kW
Construction		packaged, metal-ceramic
Cathode		quick heating
R.F. filter		integral

TYPICAL OPERATION with the tube coupled to an R26 waveguide according to Fig. 2

Conditions

Filament voltage, starting	V_f	5,0 V
Waiting time	t_w	10 s
Filament voltage, operating	V_f	2,5 V
Anode supply		three-phase, full-wave rectified
Anode current, mean	I_a	800 mA
Anode current, peak	I_{ap}	< 1100 mA
Load impedance measured with probe 55345		
Voltage standing-wave ratio	VSWR	2,5
Phase, in direction of load, with respect to reference plane	d	0,14 λ
Cooling of anode block		water, see Fig. 9
Cooling of filter box		air, $q = 60$ l/min. see Fig. 8. Inlet temperature $T_i = \text{max. } 50$ °C

Performance

Filament current at $V_f = 2,5$ V	I_f	20 A
Anode voltage, peak	V_{ap}	6 kV
Output power	W_o	3,2 kW
	W_o	> 2,9 kW
Efficiency	η	70 %

CATHODE: Thoriated tungsten

HEATING: direct by a.c. (50 Hz or 60 Hz) or d.c.

With d.c. the terminal f(k) must have positive polarity.

Filament voltage, starting and stand-by	V_f	5,0 V \pm 10%
operating at I_a mean = 800 mA	V_f	2,5 V \pm 10%
Filament current at $V_f = 5,0$ V, $I_a = 0$	I_f	41 A
		< 45 A
at $V_f = 2,5$ V, $I_a = 800$ mA	I_f	20 A
Filament current, peak starting	I_{fp}	max. 150 A
Cold filament resistance	R_{fo}	13 m Ω
Waiting time (time before application of high voltage)	t_w	min. 8 s

Immediately after applying the anode voltage the filament voltage must be reduced to the operating value. See Fig. 7.

TYPICAL CHARACTERISTICS

Measured under matched load conditions (VSWR \leq 1,05) and three-phase full-wave rectified supply. (See "Design and operating notes".)

Frequency, fixed within the band	f	2,425 to 2,475 GHz
Anode voltage, peak	V_{ap}	5,8 kV
Anode current, mean	I_a	800 mA
Output power	W_o	2,8 kW

LIMITING VALUES (Absolute maximum rating system)

Anode current, mean	I_a	max. 850 mA
Anode current, peak	I_{ap}	max. 1100 mA
Anode voltage*	V_a	max. 10 kV
Cooling water outlet temperature, open cooling circuit	T_o	max. 65 °C
closed cooling circuit	T_o	max. 75 °C
Temperature of mounting bracket at central contact point of thermoswitch (see also under "Cooling")	T	max. 120 °C
Voltage standing-wave ratio, measured with probe 55345 during max. 0,02 s and max. 20% of the time	VSWR	max. 5
	VSWR	max. 10

Any period of time up to 0,02 s during which the VSWR is between 5 and 10 must be followed by a period four times as long during which the VSWR is \leq 5. When operating under these conditions the magnetron should not be permitted to mode.

* It is recommended that a suitable spark gap be connected between the filament/cathode terminal and the anode (earth) to prevent the maximum anode voltage being exceeded.

COOLING

Anode block water

For pressure drop as a function of rate of flow see Fig. 9.

Filter box air

For pressure drop as a function of rate of flow see Fig. 8.

With only the filament voltage applied the air cooling and some water cooling is required.

The magnetron is provided with a normally closed thermostwitch to protect the tube against overheating. The thermostwitch is rated 250 V (a.c.), 10 A. Switching-off temperature 115 ± 5 °C.

DESIGN AND OPERATING NOTES

General

Whenever it is considered necessary to operate the magnetron at conditions substantially different from those indicated under "Typical operation" the tube manufacturer should be consulted.

The equipment should be designed around the tube specification given in this data and not around one particular tube since, due to normal production variations, the design parameters (V_a , R_{fo} , f , W_o etc.) will vary around the nominal values.

Anode supply

The magnetron may be operated from a non-smoothed three-phase full-wave rectified supply unit. This unit should be so designed that no limiting value for the mean and peak anode current is exceeded, whatever the operating conditions. The use of a current limiting device is recommended.

Filament supply

The secondary of the filament transformer must be well insulated from the primary since during normal magnetron operation the anode is earthed and the cathode will be at high negative potential with respect to the anode.

The transformer should be so designed that the filament voltage and peak filament starting current limits are not exceeded.

Filament and filament/cathode connections

The magnetron has a high filament current and losses in filament voltage caused by bad connections will result in poor operation. Therefore, it is important to ensure that the leads make good electrical and thermal contact with the tube terminals.

Load impedance, measured with measuring probe

The probe 55345 simulates the r.f. output system of the magnetron; it may be coupled to an R26 waveguide to replace the magnetron; in all cases the type 55344 gasket should be used. The termination of the probe matches a standard N-type connector.

The measuring probe enables the designer of the microwave heating equipment to determine the value of the load impedance (VSWR and phase of reflection), using standard cold measuring techniques, and to arrive at the correct coupling for the magnetron.

Tube cleanness

The ceramic parts of the input and output structure of the tube must be kept clean during installation and operation. The cooling air should be filtered to prevent deposits forming on the insulation.

STORAGE, HANDLING AND MOUNTING

Storage and handling

The original pack should be used for transporting the tube. Shipment of the tube mounted in the equipment is permitted if specifically authorized by the manufacturer.

When the tubes have to be unpacked, e.g. at an assembly line or for measurement purposes, care should be taken that a minimum distance of 13 cm is maintained between tubes. As the thoriated tungsten filament is sensitive to shocks and vibration, care should be taken when handling and storing unpacked tubes that such shocks and vibration are avoided. High intensity magnetic fields associated with transformers and other magnetic equipment can demagnetize the magnets. They should not be present when the tube is stored or serviced. The best protection of the tube is its original pack.

The user should be aware of the strong magnetic fields around the tube. When handling and mounting the magnetron, he must use non-magnetic tools and be extremely careful not to have precision instruments nearby.

Mounting

The magnetron should be mounted with two M4 bolts fitting the nuts on the mounting bracket (see outline drawing).

The output coupling should not be used as the only means of mounting and be kept free from undue stress.

The minimum distance between the magnetron and magnetized materials shall be 13 cm. The minimum distance between the magnetron and other ferromagnetic materials shall be 3 cm.

The gasket 55344 is essential to ensure good r.f. contact between the output of the magnetron and the waveguide to which it is connected.

All tools (screwdrivers, wrenches etc.) used close to or in contact with the magnetron must be of non-magnetic material to avoid unwanted attraction and possible mechanical damage to ceramic parts as well as short circuit of the magnetic flux.

MECHANICAL DATA

Mounting position: any

Net mass: approx. 1,8 kg

Accessories

Thermoswitch, mounted on tube	type 55364
R.F. gasket, supplied with tube	type 55344
Measuring probe (for measurements only, see Fig. 1)	type 55345
Recommended isolator	2722 163 02004

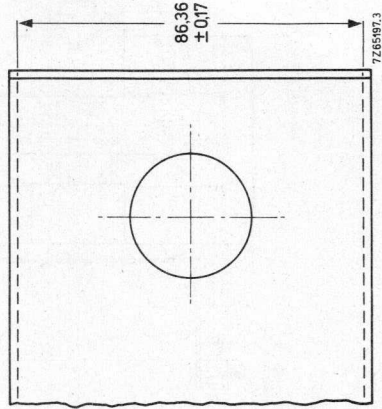
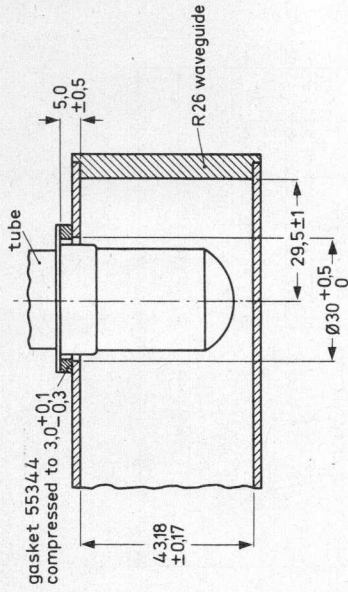


Fig. 2 Launching section.

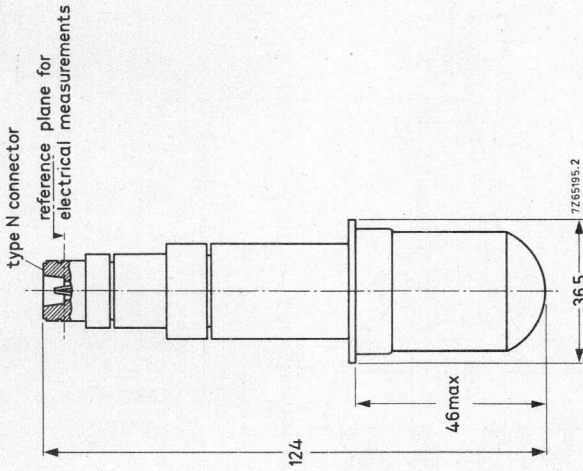


Fig. 1 Measuring probe 55345.

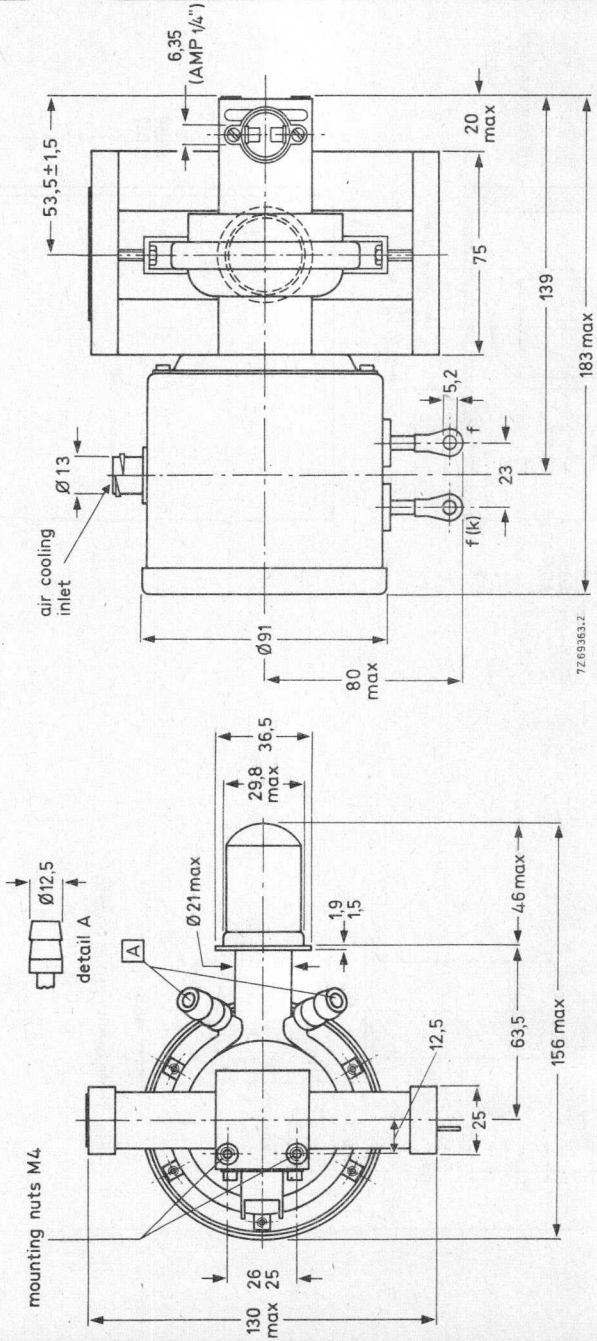
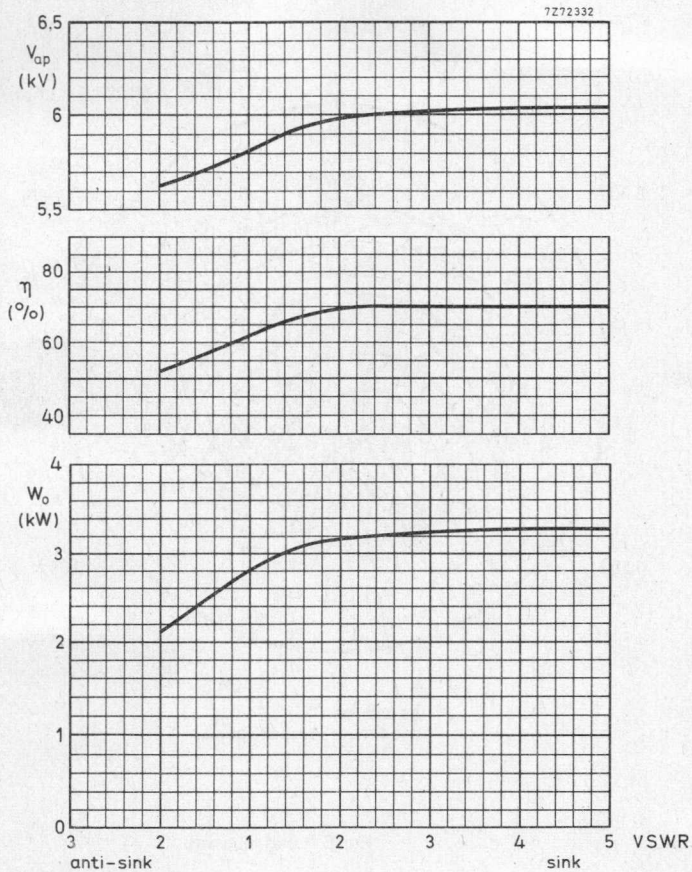


Fig. 3 Outline drawing.



$I_a = 800 \text{ mA}$

Fig. 4.

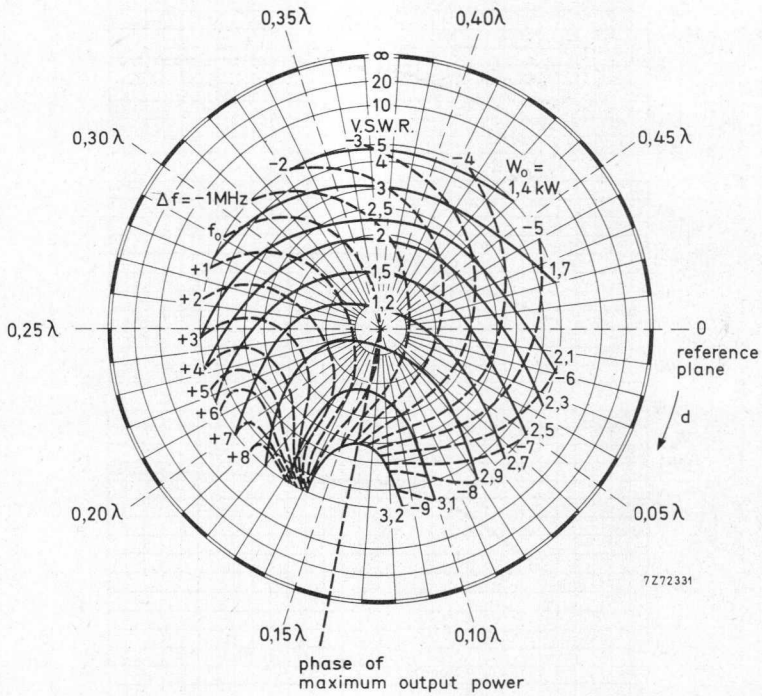


Fig. 5 Load diagram.

Measured with a three-phase full-wave rectified power supply.

Frequency $f_0 = 2,450\text{ GHz}$.

Anode current, mean

$I_a = 800\text{ mA}$.

Anode current, peak

$I_{ap} = 1000\text{ mA}$ at matched load.

Constant cooling.

d = Distance of voltage standing wave minimum from the reference plane for electrical measurements (measuring probe 55345) towards load.

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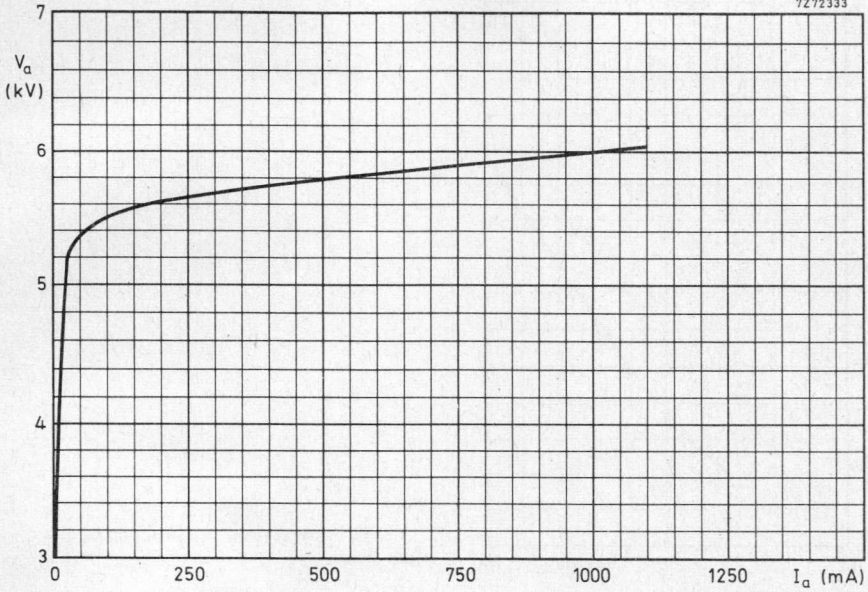


Fig. 6 Dynamic characteristic: anode voltage as a function of anode current at VSWR = 2,5 in direction of sink.

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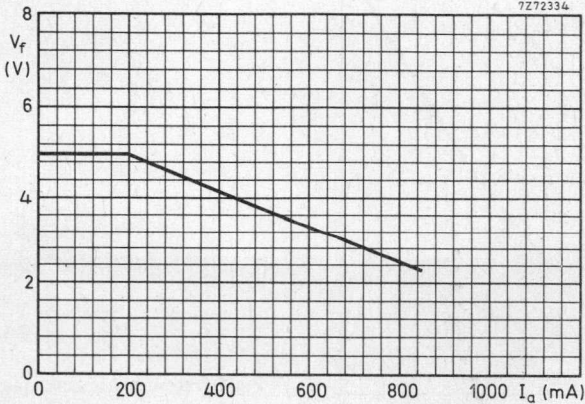


Fig. 7 Filament voltage reduction curve.

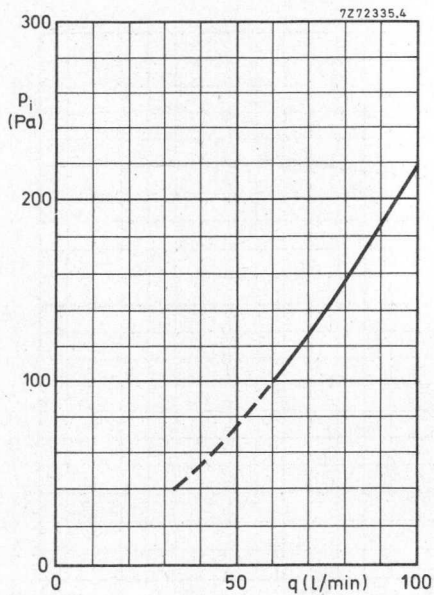


Fig. 8 Pressure drop as a function of rate of air flow.

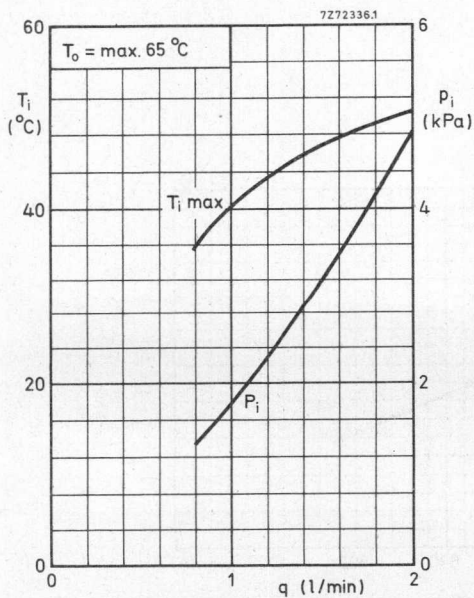


Fig. 9 Pressure drop and maximum inlet temperature as a function of rate of water flow.

CONTINUOUS-WAVE MAGNETRON

Integral-magnet, water-cooled, continuous-wave magnetron with integral r.f. filter, intended for industrial microwave applications. The tube features a quick-heating cathode, high efficiency, and has a typical output power of 3 kW.

QUICK REFERENCE DATA

Frequency, fixed within the band	f	2,350 to 2,400 GHz
Output power	W_o	3 kW
Construction		packaged, metal-ceramic
Cathode		quick heating
R.F. filter		integral

The YJ1443 is equivalent to the YJ1442, except for the frequency band, being 2,350 to 2,400 GHz, and the measuring probe, having type no. 55373.

Recommended isolator 2722 163 02024

CONTINUOUS-WAVE MAGNETRON

Integral-magnet, forced-air cooled continuous-wave magnetron with integral r.f. filter intended for microwave heating applications. The tube features a quick-heating cathode, high efficiency, and has a typical output power of 1,5 kW.

QUICK REFERENCE DATA

Frequency, fixed within the band	f	2,425 to 2,475 GHz
Output power	W_o	1,55 kW
Construction		packaged, metal-ceramic
Cathode		quick heating
R.F. filter		integral

TYPICAL OPERATION with the tube coupled to an R26 waveguide according to Fig. 3

Conditions

Filament voltage, starting	V_f	5,0 V
Waiting time	t_w	7 s
Filament voltage, operating	V_f	3,5 V
Anode supply (see "Design and operating notes")		L-C stabilized
Anode current, mean	I_a	370 mA
Anode current, peak	I_{ap}	600 mA
Load impedance, measured with probe 55345		
Voltage standing-wave ratio	VSWR	2,5
Phase, in direction of load, with respect to reference plane	d	0,14 λ
Cooling: rate of flow*	q	min. 2 m ³ /min

Performance

Filament current at $V_f = 3,5$ V	I_f	18 A
Anode voltage, peak	V_{ap}	6 kV
Output power	W_o	1,55 kW
	W_o min.	1,4 kW
Efficiency	η	70 %

CATHODE: Thoriated tungsten

* Based on a cooling air inlet temperature $T_i = \text{max. } 50^\circ\text{C}$.

HEATING: Direct by a.c. (50 Hz or 60 Hz) or d.c.

With d.c. the terminal f(k) must have positive polarity.

Filament voltage, starting and stand-by	V_f	$5,0 \text{ V} \pm 10\%$
operating at $I_{a \text{ mean}} = 370 \text{ mA}$	V_f	$3,5 \text{ V} \pm 10\%$
Filament current at $V_f = 5,0 \text{ V}$, $I_a = 0$	I_f	26 A
		< 29 A
at $V_f = 3,5 \text{ V}$, $I_a = 370 \text{ mA}$	I_f	18 A
Filament current, peak starting	I_{fp}	max. 100 A
Cold filament resistance	R_{fo}	20 m Ω
Waiting time (time before application of high voltage)	t_w	min. 6 s

TYPICAL CHARACTERISTICS

Measured under matched load conditions ($VSWR \leq 1,05$) and L-C stabilized power supply. (See "Design and operating notes".)

Frequency, fixed within the band	f	2,425 to 2,475 GHz
Anode voltage, peak	V_{ap}	5,9 kV
Anode current, mean	I_a	370 mA
Output power	W_o	1,35 kW

LIMITING VALUES (Absolute maximum rating system)

Anode current, mean	I_a	max.	400 mA
Anode current, peak	I_{ap}	max.	900 mA
Anode voltage*	V_a	max.	10 kV
Temperature of mounting bracket at central contact point of thermoswitch (see also under "Cooling")	T	max.	140 °C
Voltage standing-wave ratio, measured with probe 55345 during max. 0,02 s and max. 20% of the time	VSWR	max.	5,5
	VSWR	max.	10

Any period of time up to 0,02 s during which the VSWR is between 5,5 and 10 must be followed by a period four times as long during which the VSWR is $\leq 5,5$. When operating under these conditions the magnetron should not be permitted to mode.

COOLING

Anode block and filament structure forced air

For pressure drop as a function of rate of flow, see Fig. 8.

The cooling air must be so ducted that it is uniformly distributed.

Direction of airflow: see outline drawing.

With only the filament voltage applied some air cooling is required to keep the temperature below the limiting value.

The magnetron is provided with a normally closed thermoswitch to protect the tube against over-heating. The thermoswitch is rated 250 V (a.c.), 10 A. Switching-off temperature $135 \pm 5 \text{ }^\circ\text{C}$.

* It is recommended that a suitable spark gap be connected between the filament/cathode terminal and the anode (earth) to prevent the maximum anode voltage being exceeded.

DESIGN AND OPERATING NOTES

General

Whenever it is considered necessary to operate the magnetron at conditions substantially different from those indicated under "Typical operation" the tube manufacturer should be consulted.

The equipment should be designed around the tube specifications given in this data and not around one particular tube since, due to normal production variations, the design parameters (V_a , R_{fo} , f , W_o etc.) will vary around the nominal values.

Anode supply

The magnetron may be operated from an L-C stabilized anode supply unit. Detailed information on power supply design available on request.

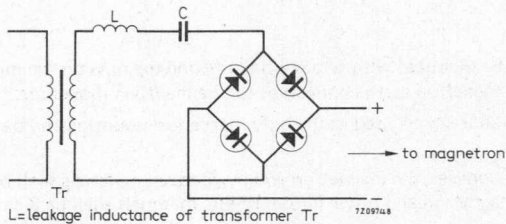


Fig. 1 Basic series resonant circuit of an L-C power supply.

Filament supply

The secondary of the filament transformer must be well insulated from the primary since during normal magnetron operation the anode is earthed and the cathode will be at high negative potential with respect to the anode.

The transformer should be so designed that the filament voltage and filament peak starting current limits are not exceeded.

Filament and filament/cathode connections

The magnetron has a high filament current and losses in filament voltage caused by bad connections, will result in poor operation. Therefore, it is important to ensure that the leads make good electrical contact with the tube terminals.

Load impedance, measured with measuring probe

The probe 55345 simulates the r.f. output system of the magnetron; it may be coupled to an R26 waveguide to replace the magnetron; in all cases the type 55344 gasket should be used. The termination of the probe matches a standard N-type connector.

The measuring probe enables the designer of the microwave heating equipment to determine the value of the load impedance (VSWR and phase of reflection), using standard cold measuring techniques, and to arrive at the correct coupling for the magnetron.

Tube cleanness

The ceramic parts of the input and output structure of the tube must be kept clean during installation and operation. The cooling air should be filtered to prevent deposits forming on the insulation during operation.

STORAGE, HANDLING AND MOUNTING

Storage and handling

The original pack should be used for transporting the tube. Shipment of the tube mounted in the equipment is permitted if specifically authorized by the manufacturer.

When the tubes have to be unpacked, e.g. at an assembly line or for measurement purposes, care should be taken that a minimum distance of 13 cm is maintained between tubes. As the thoriated tungsten filament is sensitive to shocks and vibration, care should be taken when handling and storing unpacked tubes that such shocks and vibration are avoided. High intensity magnetic fields associated with transformers and other magnetic equipment can demagnetize the magnets. They should not be present when the tube is stored or serviced. The best protection of the tube is its original pack.

The user should be aware of the strong magnetic fields around the tube. When handling and mounting the magnetron, he must use non-magnetic tools and be extremely careful not to have precision instruments nearby.

Mounting

The magnetron should be mounted with two M4 bolts fitting the nuts on the mounting bracket (see outline drawing). The magnetron earth connection can be made via these nuts.

The output coupling should not be used as the only means for mounting and be kept free from undue stress.

The minimum distance between the magnetron and magnetized materials shall be 13 cm. The minimum distance between the magnetron and other ferromagnetic materials shall be 3 cm.

The gasket 55344 essential to ensure good r.f. contact between the output of the magnetron and the waveguide to which it is connected.

All tools (screwdrivers, wrenches etc.) used close to or in contact with the magnetron must be of non-magnetic material to avoid unwanted attraction and possible mechanical damage to ceramic parts as well as short circuit of the magnetic flux.

MECHANICAL DATA

Mounting position: any

Net mass: approx. 2 kg

Accessories

Thermoswitch, mounted on tube type 55347

R.F. gasket, supplied with tube type 55344

Measuring probe (for measurements only, see Fig. 2) type 55345

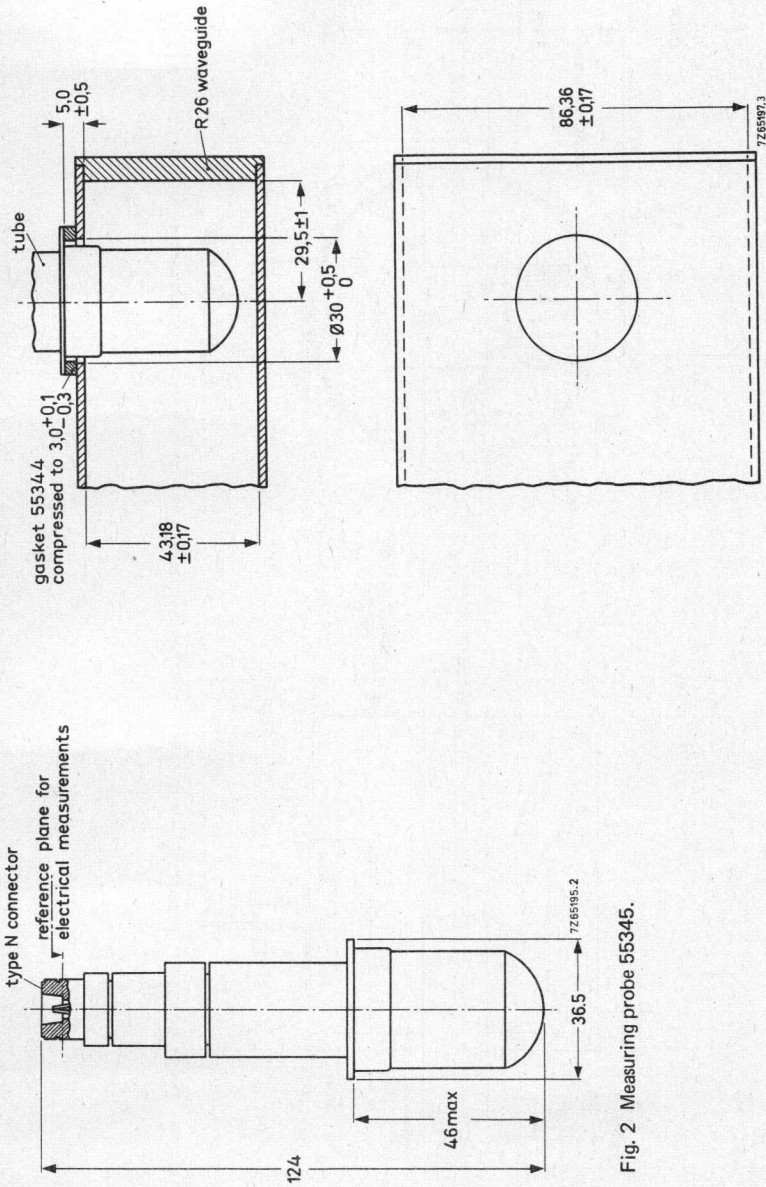


Fig. 2 Measuring probe 55345.

Fig. 3 Launching section.



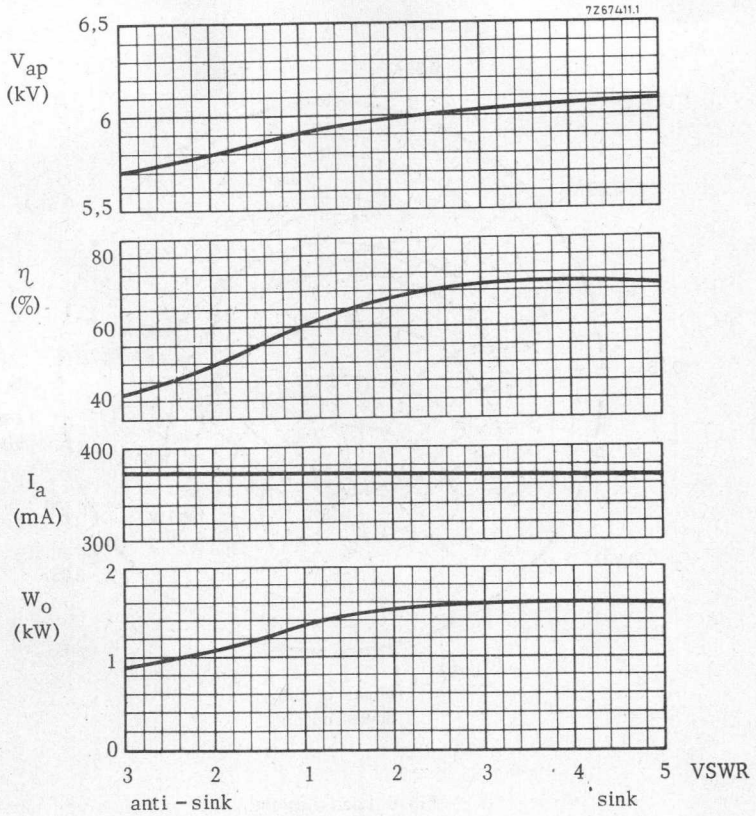
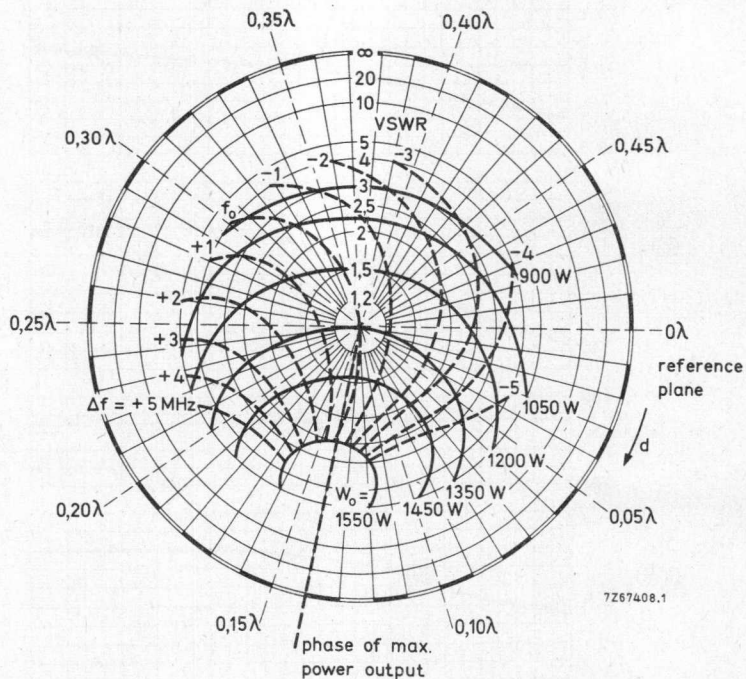


Fig. 5.



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Fig. 6 Load diagram.

Measured with an L-C stabilized power supply.
 Mean anode current $I_a = 370 \text{ mA}$ at matched load.
 Frequency $f_o = 2,450 \text{ GHz}$.
 Constant air cooling $q = 2 \text{ m}^3/\text{min}$.
 d = Distance of voltage standing wave minimum from the reference plane for electrical measurements (measuring probe 55345) towards load.

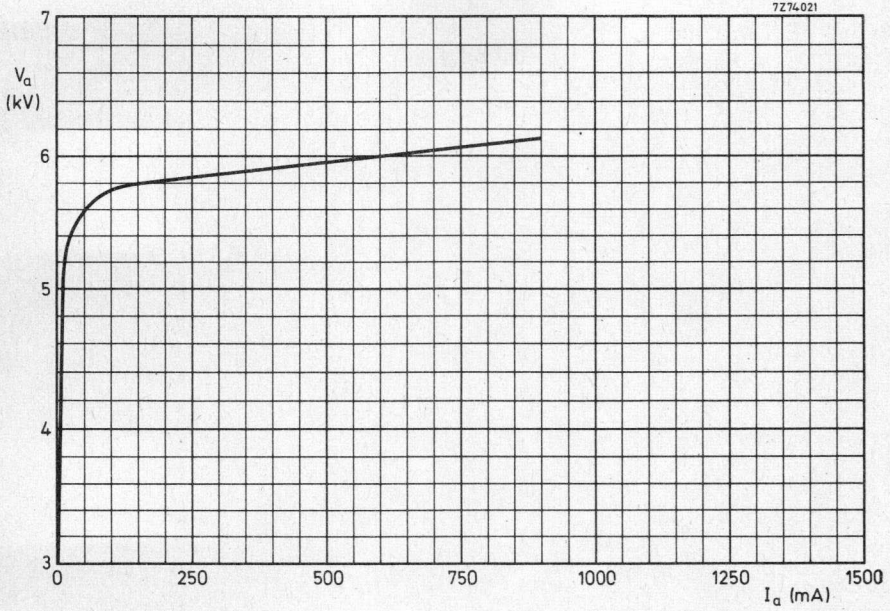


Fig. 7 Dynamic characteristic; anode voltage as a function of anode current at VSWR = 2,5 in direction of sink.

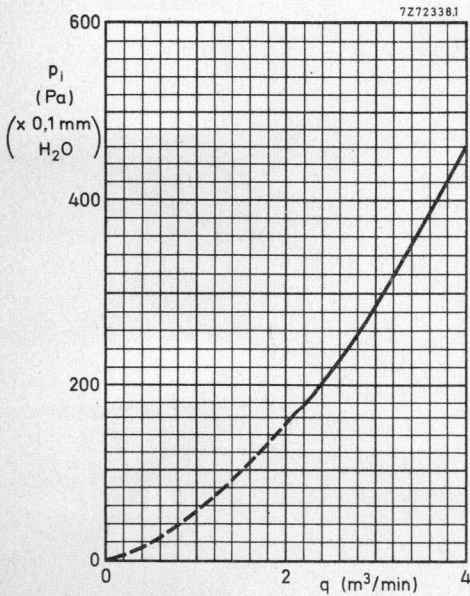
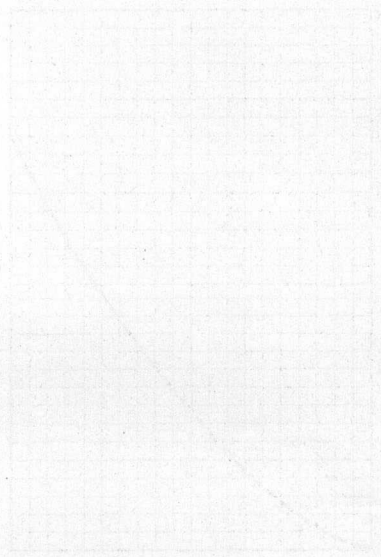
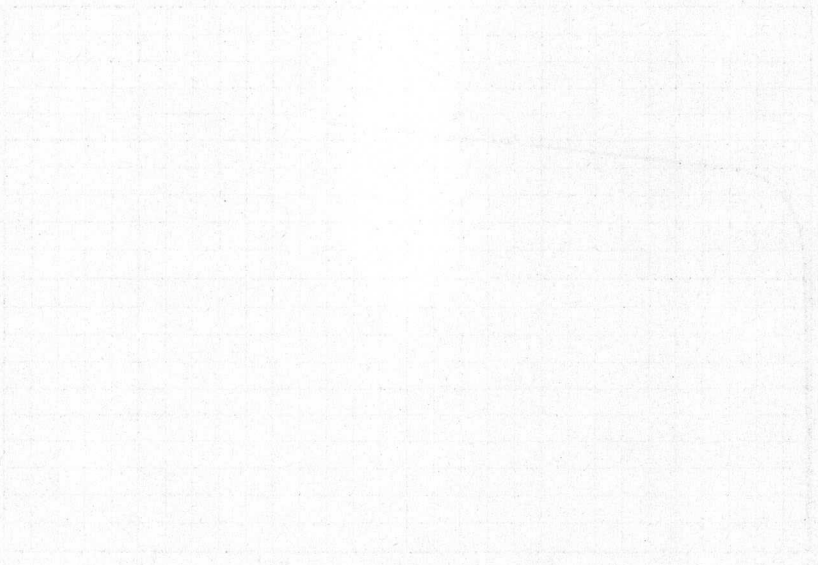


Fig. 8 Pressure drop as a function of rate of flow (air).



CONTINUOUS-WAVE MAGNETRON

Packaged, metal-ceramic, forced-air cooled, continuous-wave magnetron with integral r.f. cathode filter. The tube is primarily intended for use in domestic microwave ovens and features cold-start operation and high efficiency. Under typical operating conditions the output power is 1100 W. This lightweight tube may be mounted in any position.

QUICK REFERENCE DATA

Frequency, matched load	f	2,450 GHz
Output power	W_o	1100 W
Construction	packaged, metal-ceramic	
Cathode	thoriated tungsten, cold-start, quick heating	
R.F. cathode filter	integral	

TYPICAL OPERATION

Conditions

Filament voltage	V_f	3,2 V
Anode supply (see "Design and operating notes")	L-C stabilized half-wave doubler	
Anode current, mean	I_a	380 mA
Anode current, peak	I_{ap}	≈ 1250 mA
Cooling; rate of flow	q	1 m ³ /min

Performance (at matched load; for other load conditions see Fig. 5)

Filament current	I_f	14,5 A
Anode voltage, peak	V_{ap}	4 kV
Frequency	f	2,450 GHz
Output power	W_o	1100 W
	W_o	> 950 W
Efficiency	η	72 %

CATHODE: Thoriated tungsten, cold start, quick heating

HEATING

Filament voltage	V_f	3,2 V \pm 10%
Filament current at $V_f = 3,2$ V, $I_a = 0$	I_f	15,5 A
Cold filament resistance	R_{fo}	30 m Ω
Pre-heating time (waiting time)	t_w	0

TYPICAL CHARACTERISTICS

Frequency, fixed within the band	f	2,435 to 2,465 GHz
Phase of sink, measured with probe type 55371	d	0,11 λ

LIMITING VALUES (Absolute maximum rating system)

Filament voltage	V_f	max. 3,2 V +10%	min. 3,2 V -10%
Anode current, mean	I_a	max. 420 mA	*
Anode current, peak			
Anode voltage**	V_a	max. 12 kV	
Cooling; rate of flow	q	min. 1 m ³ /min	
Temperature at reference point (see outline drawing)	T	max. 180 °C	
Voltage standing-wave ratio, measured with probe 55371 during max. 0,02 s and max. 20% of the time	VSWR	max. 4	
	VSWR	max. 10	

Any period of time up to 0,02 s during which the VSWR is between 4 and 10 must be followed by a period four times as long during which the VSWR is ≤ 4 .

COOLING

Anode block	forced air
Required quantity of air, based on an air inlet temperature of 50 °C max. under typical operating conditions	q min. 1 m ³ /min
Pressure drop as a function of rate of flow	see Fig. 7
Direction of air flow through radiator	arbitrary

To protect the magnetron against overheating it is recommended that a thermostwitch be mounted in the position shown on the outline drawing. Thermostwitch switching-off temperature 100 °C.

* Under no circumstances should the magnetron be permitted to mode. Amongst other conditions, the moding stability of a magnetron depends on the r.f. loading conditions such as VSWR, phase of reflection, and coupling section. It also depends on peak anode current, mean anode current, and current waveform. For a magnetron operating from an L-C stabilized half-wave doubler anode supply, the peak to mean anode current ratio is approximately 3 to 3,5.

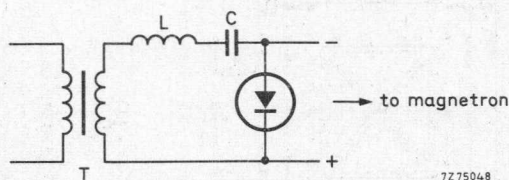
** For "cold-start" operation it is recommended that, for the anode voltage, a rectifier be used with a reverse breakdown voltage of 10 to 12 kV and having an avalanche energy rating of ≥ 2 J.

DESIGN AND OPERATING NOTES**General**

Whenever operation of the magnetron at conditions substantially different from those indicated under "Typical operation" is considered the tube supplier should be consulted.

Anode supply

The magnetron may be operated from an L-C stabilized half-wave doubler anode supply unit. Information on power supply design is available on request.



L = Leakage inductance of transformer T

Fig. 1 Basic circuit of an L-C stabilized half-wave doubler anode supply unit.

Filament supply

Simultaneous application of filament and anode voltage is permitted ("cold start"). The filament winding of the transformer must be well insulated from the primary winding since the anode is earthed and the cathode is at a high negative potential with respect to the anode and the primary winding.

When "variable power control" is used, please contact the tube supplier.

Load impedance, measured with measuring probe

The measuring probe type 55371 enables the designer of the microwave oven to determine the value of the load impedance (VSWR and phase of reflection), using standard cold measuring techniques, and to arrive at the correct coupling for the magnetron.

For the cold measurements the probe, with gasket type 55372, is coupled to the coupling section instead of the magnetron. The termination of the probe matches a standard N-type connector.

Assistance in the design of the h.f. part of the oven, including the magnetron coupling method, may be given by the tube manufacturer.

Tube cleanness

The ceramic parts of the input and output structure of the tube must be kept clean and dry during installation and operation.

Mounting

The magnetron should be mounted on a non-ferromagnetic coupling section by means of 4 screws through the holes in the air duct or by 4 mounting brackets catalogue number 4322 041 03832 which can be hooked into the slits in the air duct side-walls.

To ensure good r.f. contact between the magnetron and the coupling section the use of gasket type 55372 is essential.

MECHANICAL DATA

Mounting position: any

Net mass: approx. 1 kg

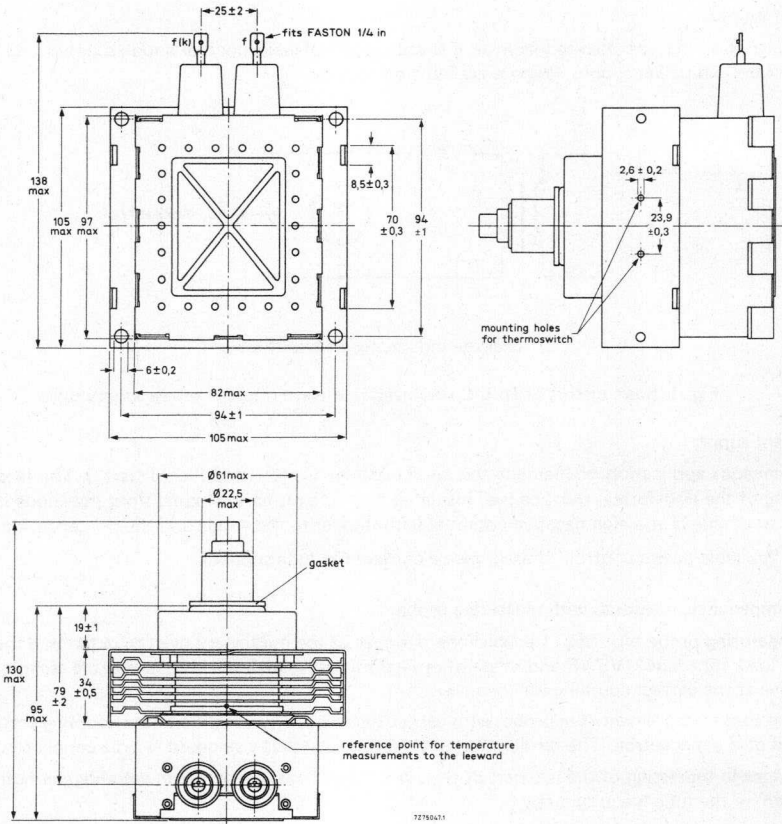


Fig. 2 Outline drawing.

ACCESSORIES

R.F. gasket, supplied with tube

type 55372

Measuring probe for oven design measurements

type 55371

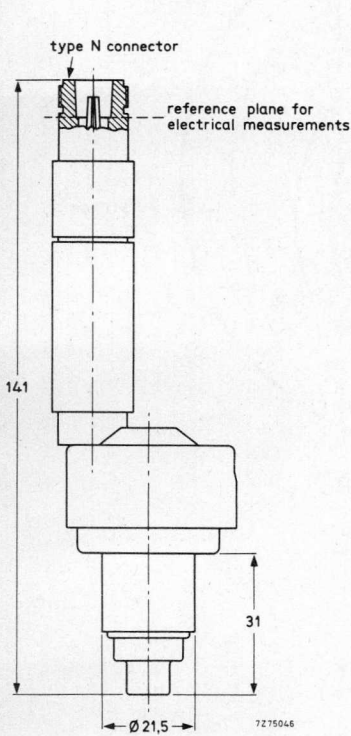


Fig. 3 Measuring probe type 55371.

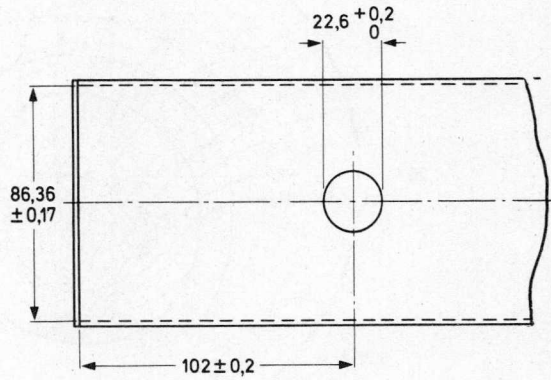


Fig. 4 Coupling section for YJ1500 into a waveguide R26 (used for measurements).

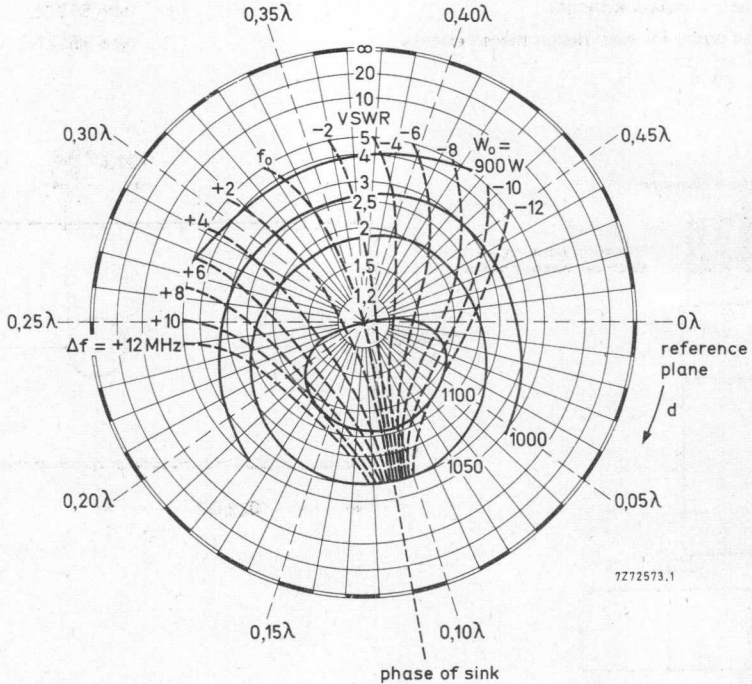


Fig. 5 Load diagram.

Measured with an L-C stabilized half-wave doubler anode supply.
 Mean anode current $I_a = 380 \text{ mA}$ at matched load.
 Frequency $f_0 = 2,450 \text{ GHz}$.
 Constant air cooling $q = 1 \text{ m}^3/\text{min}$.
 d = Distance of voltage standing wave minimum from the reference plane for electrical measurements (measuring probe type 55371) towards load.

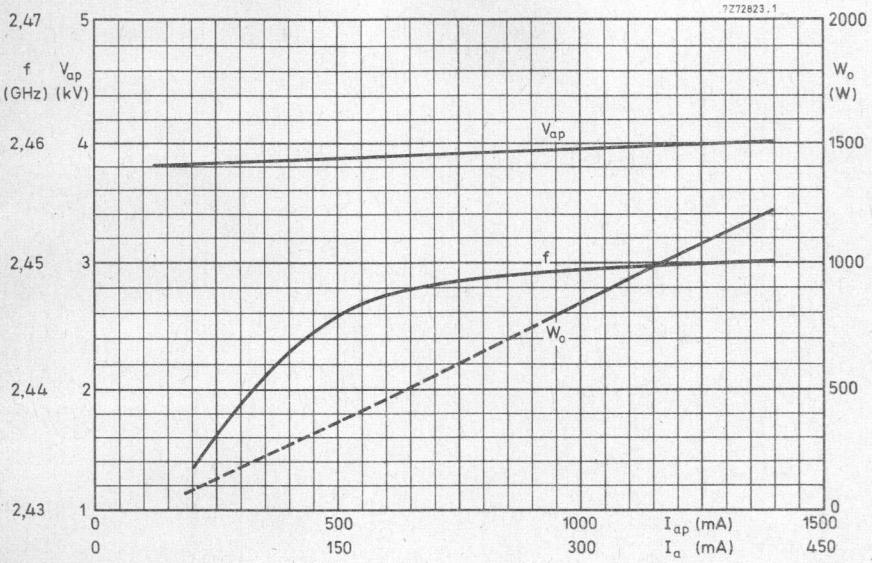


Fig. 6 Peak anode voltage, V_{ap} , as a function of peak anode current, I_{ap} . Frequency, f , as a function of peak anode current, I_{ap} . Output power, W_o , as a function of mean anode current, I_a , measured with an L-C stabilized half-wave doubler supply with $\frac{I_{ap}}{I_a} = \frac{10}{3}$. Load: matched.

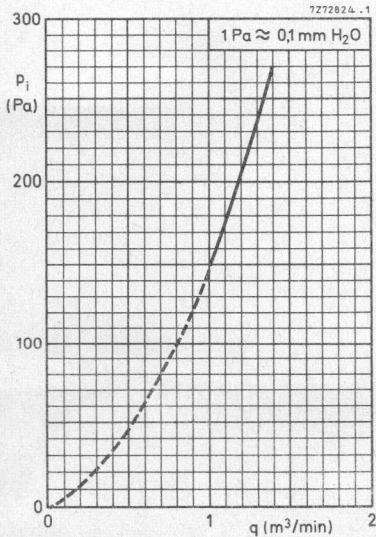


Fig. 7 Pressure drop, p_i , across radiator as a function of air flow, q .

CONTINUOUS-WAVE MAGNETRON

Packaged, metal-ceramic, forced-air cooled, continuous-wave magnetron with integral r.f. cathode filter. The tube is primarily intended for use in diathermy and other low-power heating applications. The tube features cold start operation and high efficiency.

QUICK REFERENCE DATA

Frequency, matched load	f	2,455 GHz
Output power	W_o	265 W
Construction		packaged, metal-ceramic
Cathode		thoriated tungsten cold start, quick heating
R.F. cathode filter		integral
Cooling		forced air

TYPICAL OPERATION

Tube coupled to waveguide section of Fig. 1.

At matched load in coaxial output line; for other load conditions see Fig. 3.

Anode supply

OPERATION A: Unsmoothed single-phase full-wave rectified voltage

OPERATION B: Pulsed

Conditions

		A	B
Filament voltage, a.c. 50 or 60 Hz	V_f	4	4 V
Anode current			
mean	I_a	150	150 mA
peak	I_{ap}	500	900 mA
Cooling rate of flow	q_{min}	500	500 l/min
Pressure drop	p_i	40	40 Pa

Performance

Filament current	I_f	17,5	17,5 A ←
Anode voltage, peak	V_{ap}	2,9	3,0 kV
Frequency	f	2,455	2,455 GHz
Output power, VSWR < 1,05	W_o	255	265 W
Efficiency	η	61	61 %

HEATING

Thoriated tungsten, cold start, quick-heating cathode

Filament voltage	V_f	$4 V \pm 10\%$
Filament current at $V_f = 4 V, I_a = 0$	I_f	17,5 A
Cold filament resistance	R_{f0}	30 m Ω
Pre-heating time (waiting time)	t_w	0

For "cold start" operation it is recommended that a rectifier be used with a reverse breakdown voltage of 10 kV and having an avalanche energy of 2 joule.

GENERAL DATA**Electrical**

Frequency, fixed within the band	f	2,445 to 2,465 GHz
Phase for maximum output power	d	0,09 λ

Mechanical

Mounting position	any	
Mass	\approx	1,0 kg

LIMITING VALUES (Absolute maximum rating system)

Filament voltage	V_f	max. 4,4 V min. 3,6 V
Anode current mean	I_a	max. 200 mA
peak		950 mA*
Anode voltage	V_a	max. 10 kV
Temperature at reference point (see outline drawing)	T	max. 180 °C
Voltage standing-wave ratio	VSWR	max. 5
Storage temperature		min. -30 °C

COOLING

Anode block	forced air	
Required quantity of air, based on an air inlet temperature of 50 °C max. under typical operating conditions	q	min. 300 l/min
Pressure drop as a function of rate of flow	see Fig. 6	
Direction of air flow through radiator	arbitrary	

To protect the magnetron against overheating it is recommended that a thermostwitch be mounted in the position shown on the outline drawing. Temperature at which the thermostwitch will switch off: see Fig. 4.

* Under no circumstances should the magnetron be permitted to mode. Amongst other conditions, the moding stability of a magnetron depends on the R.F. loading conditions such as VSWR, phase of reflection, and coupling section. It also depends on peak anode current, mean anode current, and current waveform.

DESIGN AND OPERATING NOTES**General**

Whenever operation of the magnetron at conditions substantially different from those indicated under *Typical operation* is considered the tube supplier should be consulted.

Filament supply

Simultaneous application of filament and anode voltage is permitted ('cold start'). The filament winding of the transformer must be well insulated from the primary winding since the anode is earthed and the cathode is at a high negative potential with respect to the anode and the primary winding.

Tube cleanliness

The ceramic part of the output structure of the tube must be kept clean and dry during installation and operation.

Mounting

The magnetron should be mounted on a coupling section by means of the 3 bolts M4 (see outline drawing). To ensure good r.f. contact between the magnetron and the coupling section, the nuts should be fastened evenly.

ACCESSORIES

R.F. gasket, supplied with the tube, type 55372.

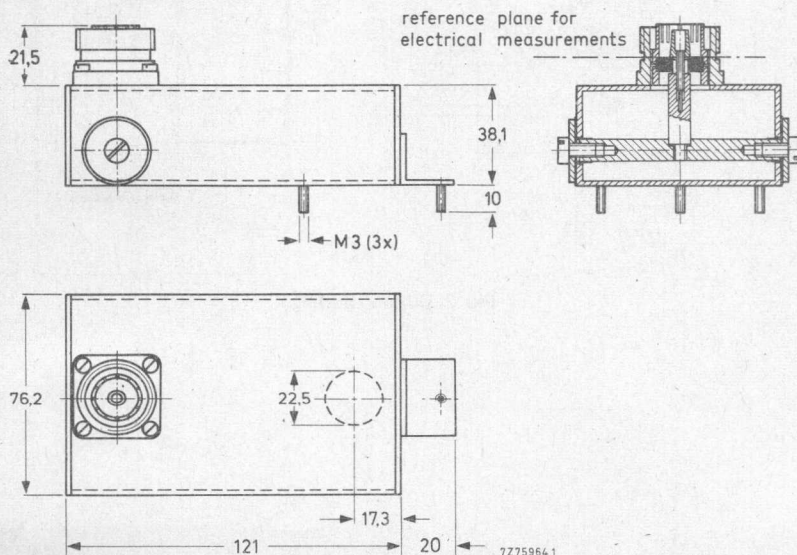


Fig. 1 Coupling section (detailed drawings available on request).

MECHANICAL DATA

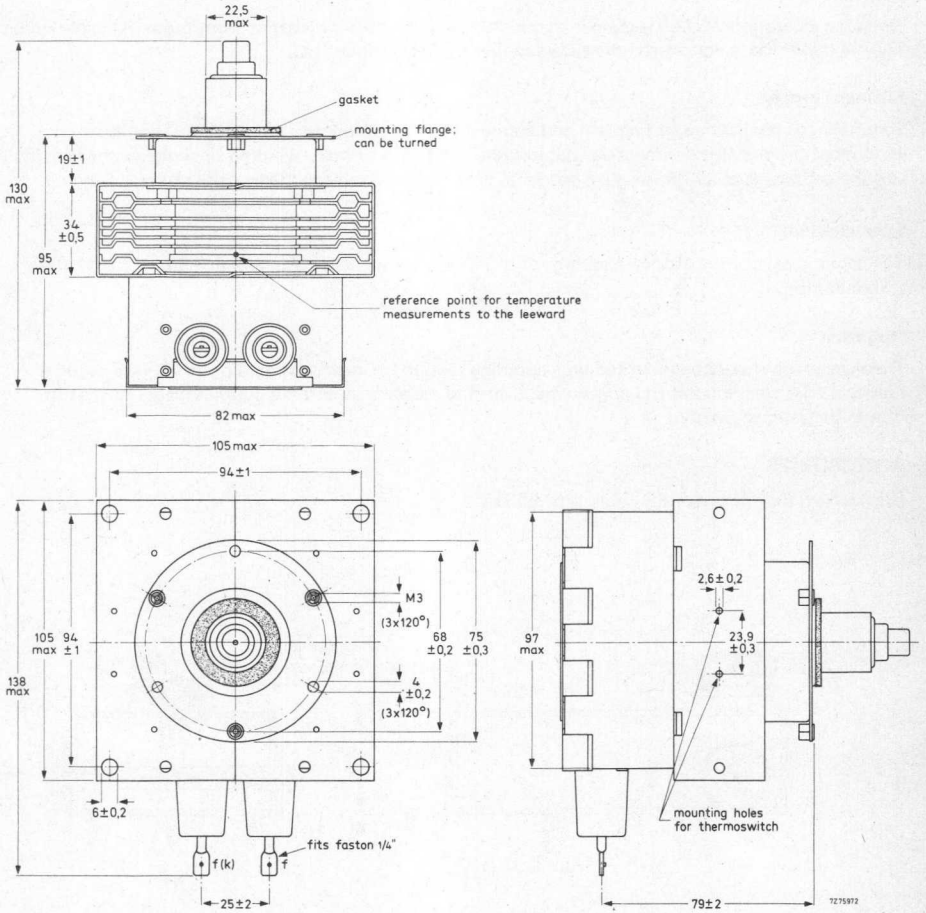


Fig. 2 Outline drawing.

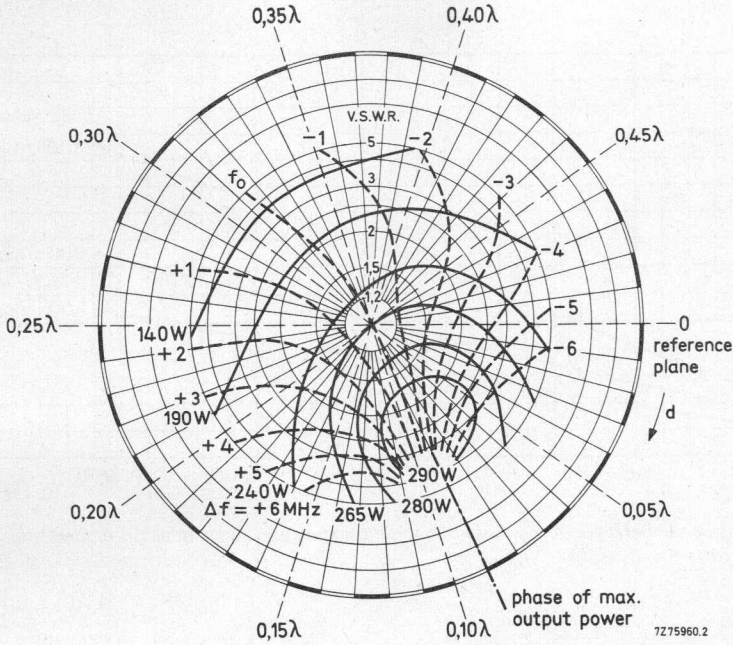


Fig. 3 Load diagram.

Reference plane	output of coupling section (see Fig. 1).
Anode supply	operation B: pulsed
Filament voltage	4 V
Average anode current	150 mA
Peak anode voltage	3 kV
Frequency at matched load	$f_0 = 2,455 \text{ GHz}$

d = distance of VSWR - minimum from reference plane towards load
 Diagram measured in cold condition.

Cooling characteristics

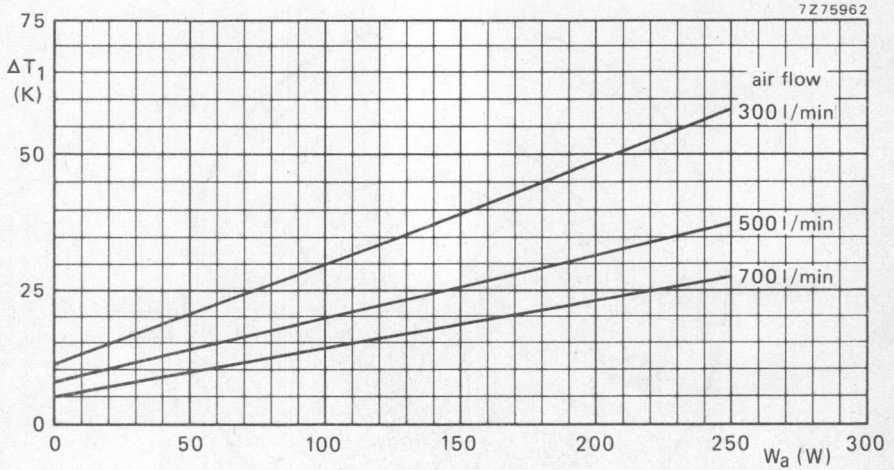


Fig. 4 Increase temperature of thermoswitch mounting position above inlet air temperature, ΔT_1 as a function of anode dissipation, W_a .

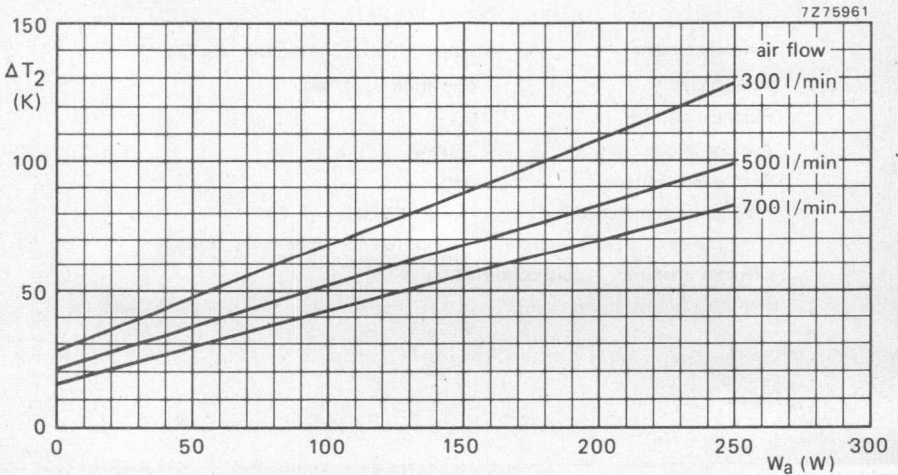


Fig. 5 Increase of anode temperature above inlet air temperature, ΔT_2 , as a function of anode dissipation, W_a . Anode dissipation = (peak anode voltage) \times (average anode current) - (output power). $V_f = 4$ V.

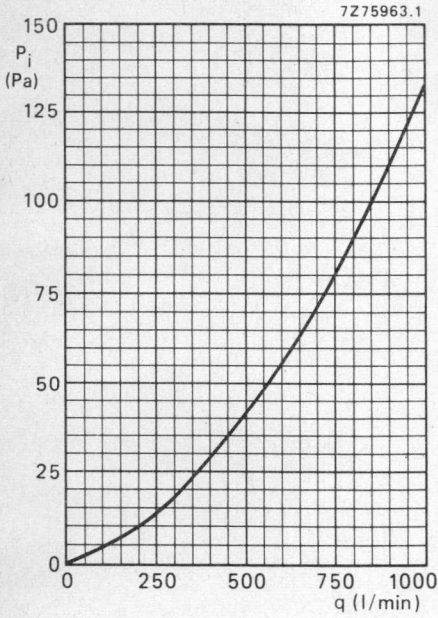


Fig. 6 Pressure drop, p_i , across radiator as a function of air flow, q .

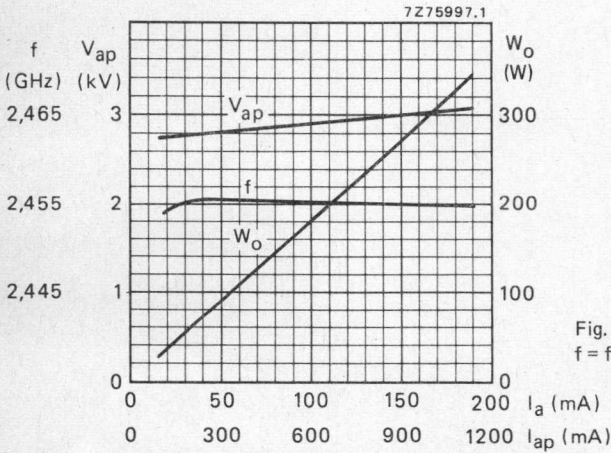


Fig. 7 Performance chart.
 $f = f(I_{ap})$; $V_{ap} = f(I_{ap})$; $W_o = f(I_a)$.

CONTINUOUS-WAVE MAGNETRON

Packaged, metal-ceramic, forced-air cooled, continuous-wave magnetron with integral r.f. cathode filter. The tube is primarily intended for use in domestic microwave ovens and features cold-start operation and high efficiency. Under typical operating conditions the output power is 875 W. This lightweight tube may be mounted in any position and is available in three mechanically different versions, YJ1520, YJ1521, YJ1522, having a different position of the filter box and different mounting.

QUICK REFERENCE DATA

Frequency, matched load	f	2,455 GHz
Output power	W_o	875 W
Construction	packaged, metal-ceramic	
Cathode	thoriated tungsten, cold start, quick heating	
R.F. cathode filter	integral	

TYPICAL OPERATION

Conditions

Filament voltage	V_f	3,15 V
Anode supply (see <i>Design and operating notes</i>)	LC stabilized half-wave doubler	
Anode current		
mean	I_a	300 mA
peak	I_{ap}	< 1000 mA
Cooling, rate of flow	q	800 l/min
Pressure drop	approximately 60 Pa or 6 mm H ₂ O	

Performance (at matched load; for other load conditions see Fig. 7)

Filament current	I_f	15 A
Anode voltage, peak	V_{ap}	4,15 kV
Frequency	f	2,455 GHz
Output power, VSWR < 1,05	W_o	875 W
Efficiency	η	71 %

YJ1520
YJ1521
YJ1522

HEATING

Thoriated tungsten, cold start, quick-heating cathode

Filament voltage	V_f	3,15 V \pm 10%
Filament current at $V_f = 3,15$ V, $I_a = 0$	I_f	15,5 A
Cold filament resistance	R_{f0}	27 m Ω
Pre-heating time (waiting time)	t_w	0

GENERAL DATA

Electrical

Frequency, fixed within the band	f	2,445 to 2,465 GHz
Phase for maximum output power measured with probe type 55374	d	0,245 λ

Mechanical

Mounting position	any	
Mass	\approx	1,1 kg

LIMITING VALUES (Absolute maximum rating system)

Filament voltage	V_f	max. 3,15 V + 10%	
		min. 3,15 V - 10%	
Anode current			
mean	I_a	max. 350 mA	
peak		1200 mA*	
Anode voltage	V_a	max. 10 kV	
Temperature at reference point (see outline drawing)	T	max. 200 °C	
Voltage standing-wave ratio, measured with probe type number 55374	VSWR	max. 4	
Any period of time up to 0,02 s during which the VSWR is between 4 and 10 must be followed by a period four times as long during which the VSWR is ≤ 4	VSWR	max. 10*	
Storage temperature		min. -30 °C	

* Under no circumstances should the magnetron be permitted to mode. Amongst other conditions, the moding stability of a magnetron depends on the r.f. loading conditions such as VSWR, phase of reflection, and coupling section. It also depends on peak anode current, mean anode current, and current waveform. For a magnetron operating from an LC stabilized half-wave doubler anode supply, the peak to mean anode current ratio is approximately 3,2.

COOLING

Anode block

forced air

Required quantity of air, based on an air inlet temperature of 50 °C max. under typical operating conditions

q min. 800 l/min

Pressure drop as a function of rate of flow

see Fig. 13

Direction of air flow through radiator

arbitrary

To protect the magnetron against overheating it is recommended that a thermostat be mounted in the position shown on the outline drawing. Temperature at which the thermostat will switch off: see Fig. 10.

ACCESSORIES

Measuring probe for oven design measurements

type 55374

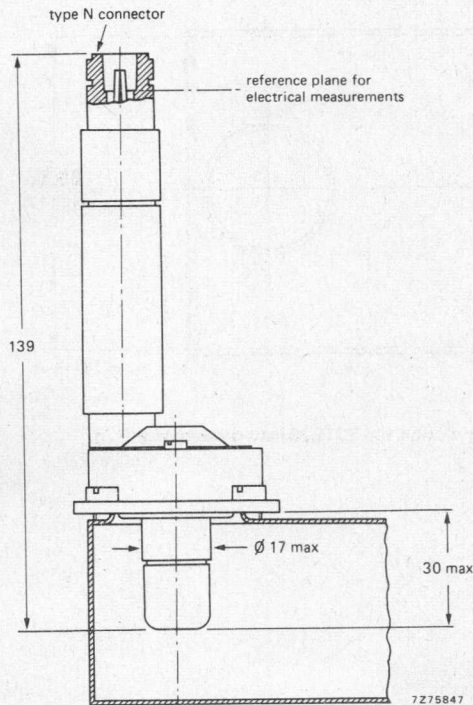


Fig. 1 Measuring probe type 55374 in coupling section R26.

YJ1520
YJ1521
YJ1522

Dimensions in mm

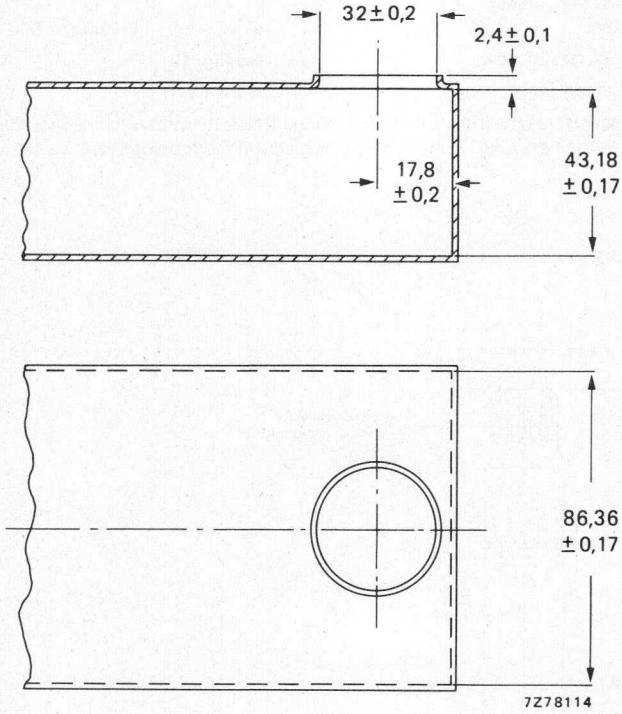


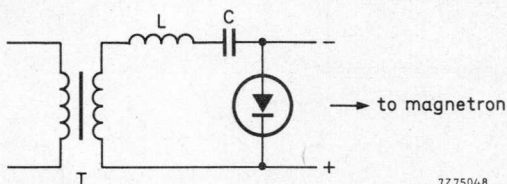
Fig. 2 Coupling section for YJ1520 into a waveguide R26.

DESIGN AND OPERATING NOTES**General**

Whenever operation of the magnetron at conditions substantially different from those indicated under *Typical operation* is considered the tube supplier should be consulted.

Anode supply

The magnetron may be operated from an LC stabilized half-wave doubler anode supply unit. Information on power supply design is available on request.



L = leakage inductance of transformer T.

Fig. 3 Basic circuit of an LC stabilized half-wave doubler anode supply unit.

Filament supply

Simultaneous application of filament and anode voltage is permitted ('cold start'). The filament winding of the transformer must be well insulated from the primary winding since the anode is earthed and the cathode is at a high negative potential with respect to the anode and the primary winding.

When 'variable power control' is used, please contact the tube supplier.

Load impedance, measured with measuring probe

The measuring probe type 55374 enables the designer of the microwave oven to determine the value of the load impedance (VSWR and phase of reflection), using standard cold measuring techniques, and to arrive at the correct coupling for the magnetron. For the cold measurements the probe is coupled to the coupling section instead of the magnetron. The termination of the probe matches a standard N-type connector.

Assistance in the design of the h.f. part of the oven, including the magnetron coupling method, may be given by the tube manufacturer.

Tube cleanness

The ceramic part of the output structure of the tube must be kept clean and dry during installation and operation.

Mounting

The magnetron should be mounted on a coupling section by means of the 4 bolts M5 (see outline drawing). To ensure good r.f. contact between the magnetron and the coupling section, the nuts should be fastened evenly.

YJ1520
YJ1521
YJ1522

MECHANICAL DATA

Mounting position: any

Net mass: approx. 1,1 kg

Dimensions in $\frac{\text{mm}}{\text{inches}}$

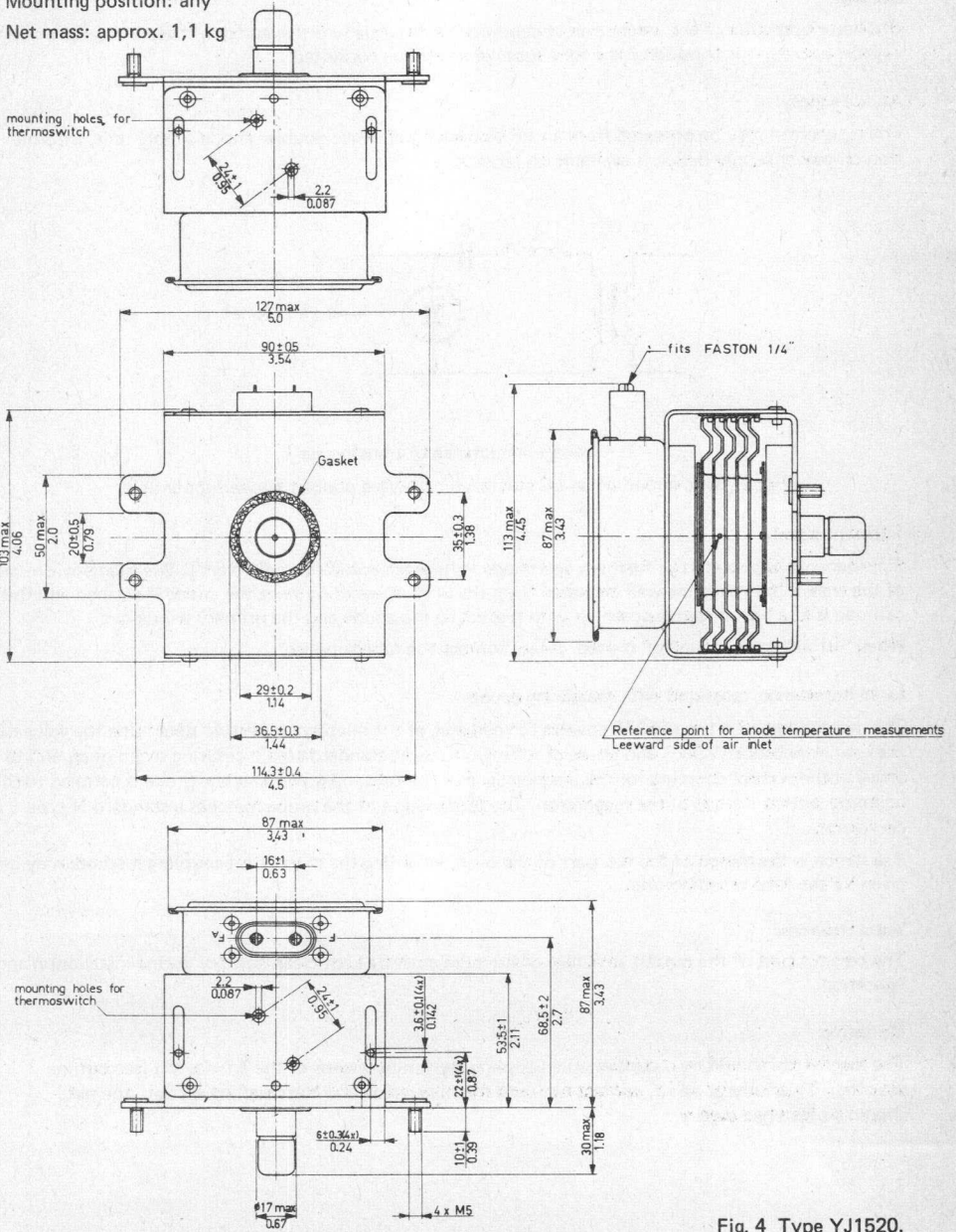


Fig. 4 Type YJ1520.

MECHANICAL DATA

Dimensions in $\frac{\text{mm}}{\text{inches}}$

Mounting position: any

Net mass: approx. 1,1 kg

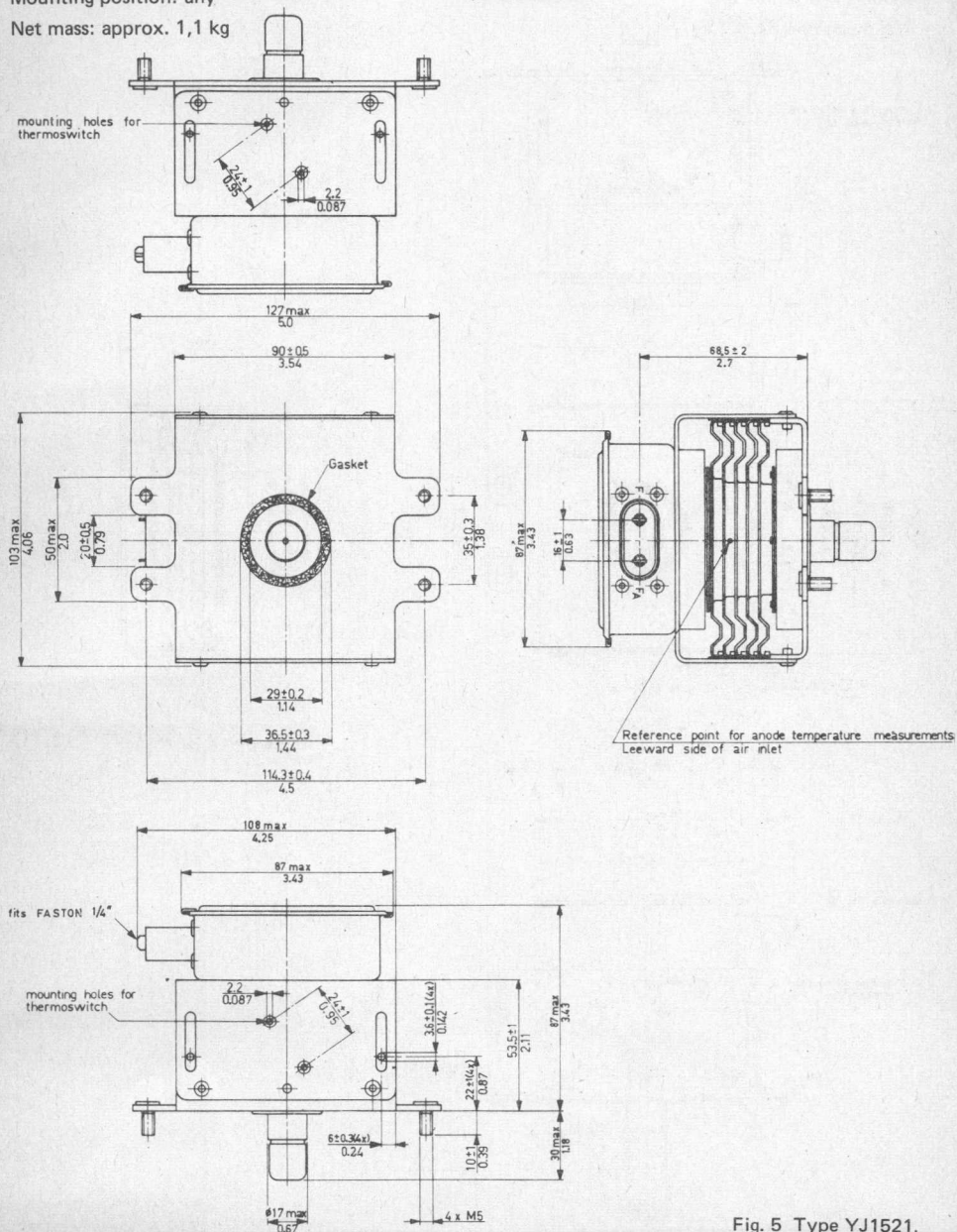


Fig. 5 Type YJ1521.

YJ1520
YJ1521
YJ1522

MECHANICAL DATA

Mounting position: any

Net mass: approx. 1,1 kg

Dimensions in $\frac{\text{mm}}{\text{inches}}$

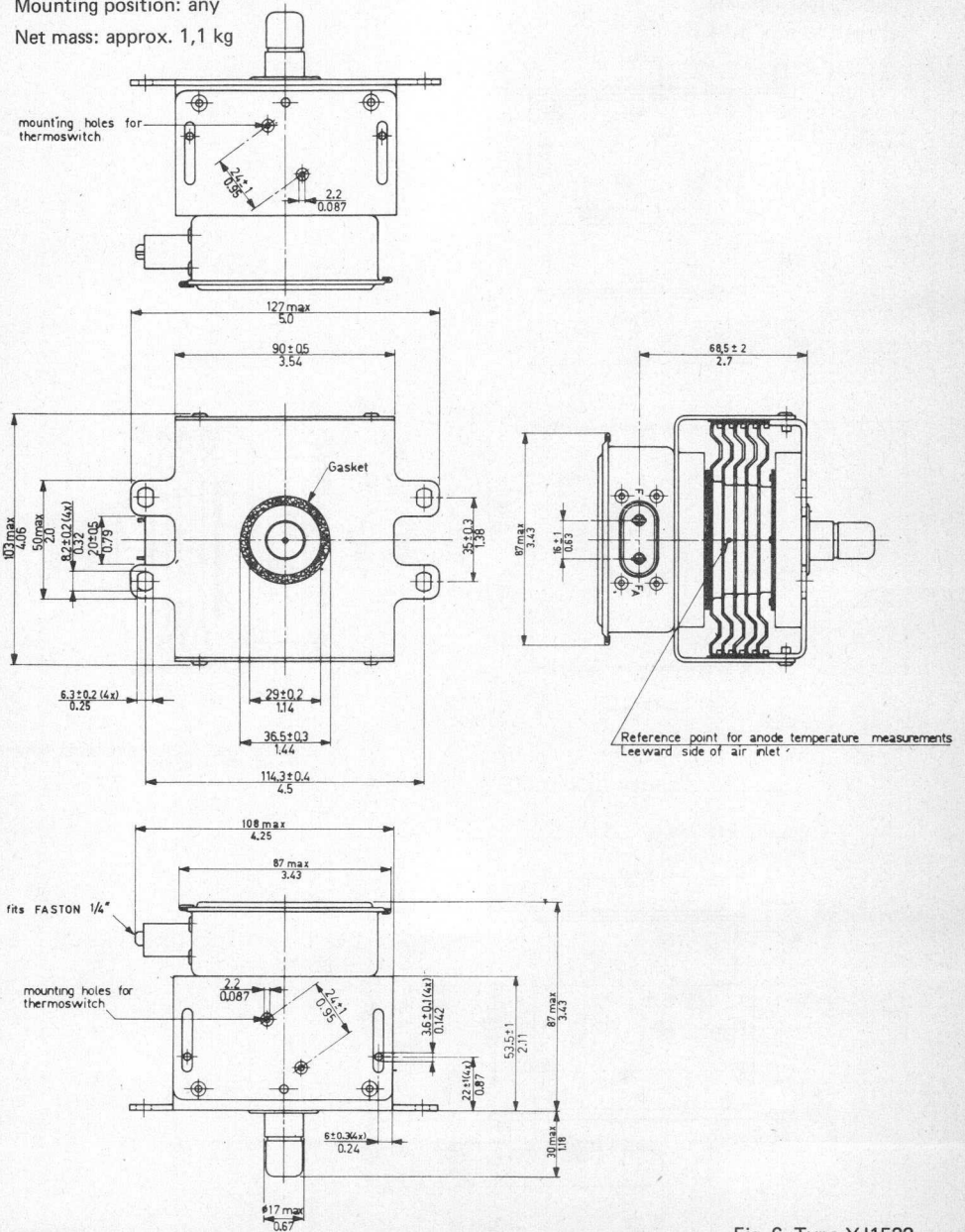


Fig. 6 Type YJ1522.

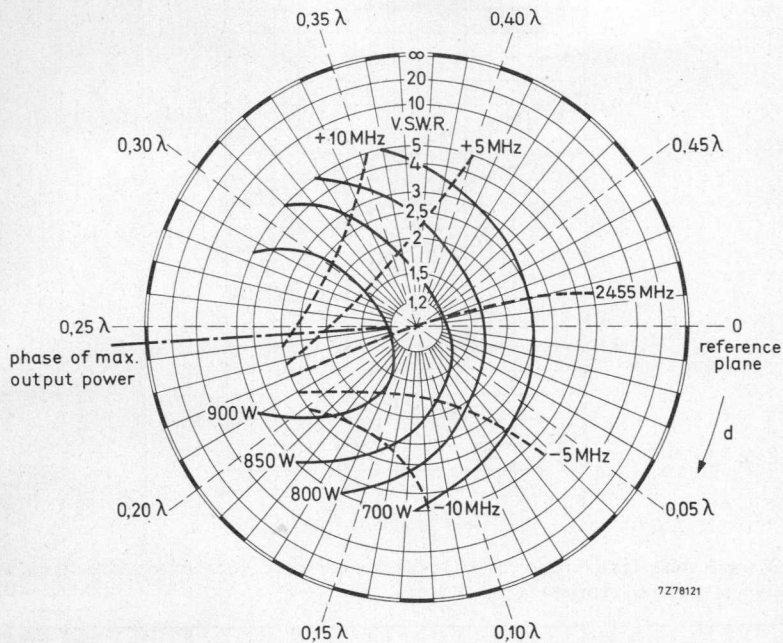


Fig. 7 Load diagram.

Reference plane: input of probe 55374 (see Fig. 1)

Anode supply half-wave doubler LC-type

Filament voltage 3,15 V

Average anode current 300 mA

Peak anode voltage 4,15 kV at matched load

Frequency at matched load 2,455 GHz

d = distance of VSWR - minimum from reference plane towards load

Diagram measured under cold condition.

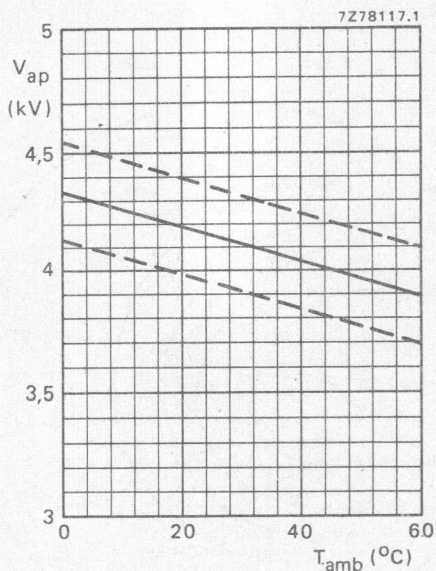


Fig. 8 Peak anode voltage as a function of the ambient temperature. Tube tested within 15 s after storage for 4 h at relevant temperature.

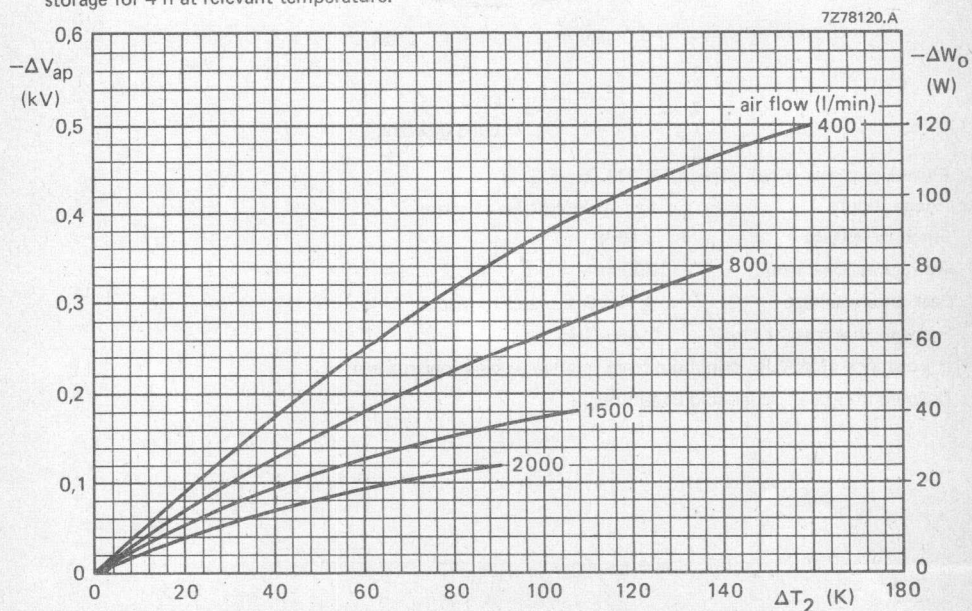


Fig. 9 Decrease of peak anode voltage, $-\Delta V_{ap}$, and output power, $-\Delta W_o$, as a function of anode temperature above inlet air temperature (after temperature stabilization), ΔT_2 .

Cooling characteristics

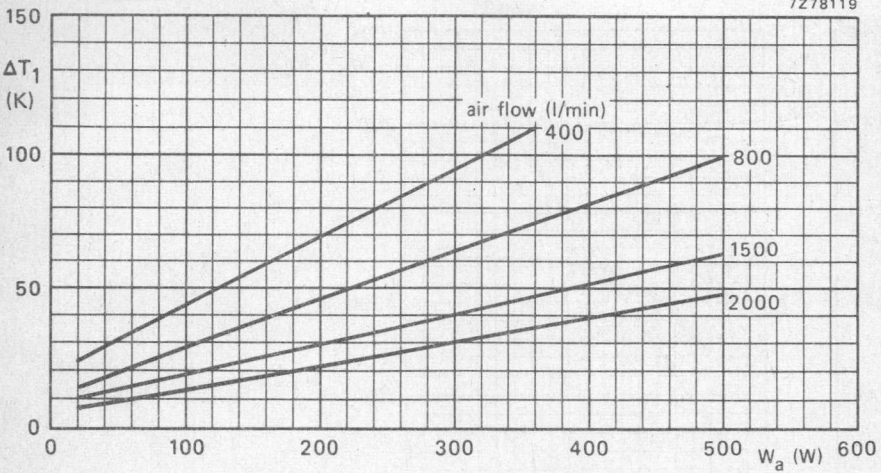


Fig. 10 Increase temperature of thermoswitch mounting position above inlet air temperature, ΔT_1 as a function of anode dissipation, W_a .

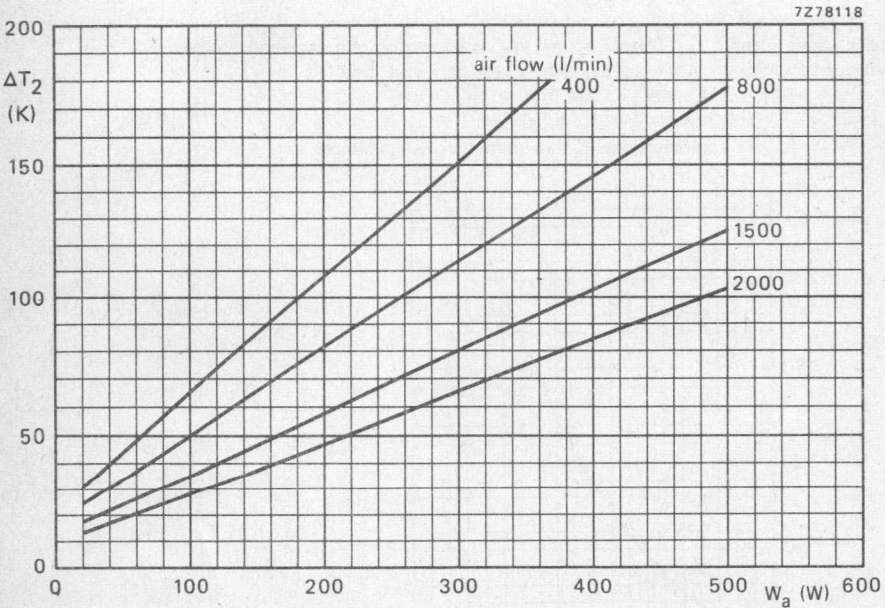


Fig. 11 Increase of anode temperature above inlet air temperature, ΔT_2 , as a function of anode dissipation, W_a . Anode dissipation = (peak anode voltage) x (average anode current) - (output power). $V_f = 3,15$ V.

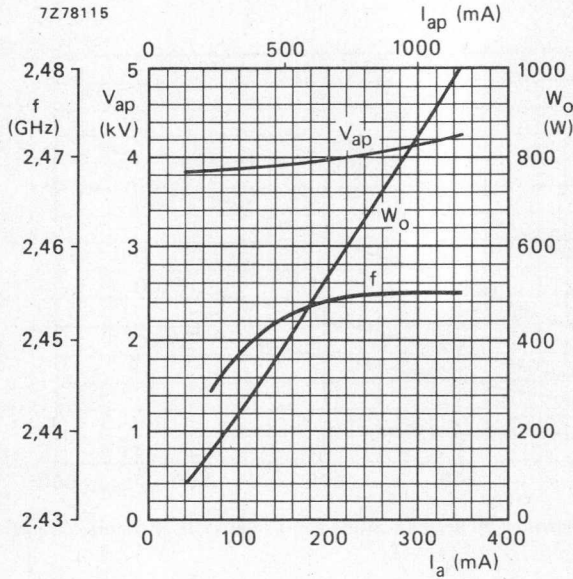


Fig. 12 Peak anode voltage, V_{ap} , as a function of peak anode current, I_{ap} . Frequency f , as a function of peak anode current, I_{ap} . Output power, W_o , as a function of mean anode current, I_a . Operating conditions: anode supply, single-phase half-wave doubler; filament voltage 3,15 V; load VSWR 1,1 maximum; measured within 15 s after applying voltages.

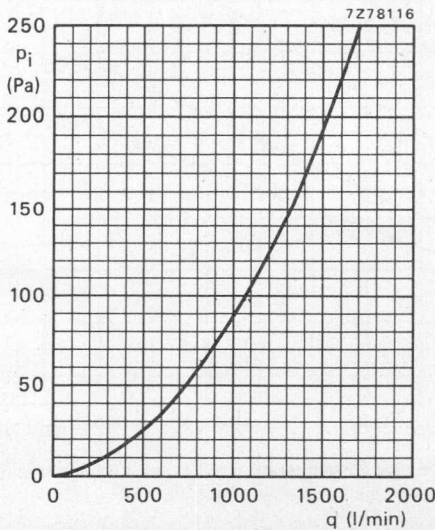


Fig. 13 Pressure drop, p_i , across radiator as a function of air flow, q .



CONTINUOUS-WAVE MAGNETRON

Integral-magnet, air-cooled or heatsink-cooled continuous-wave magnetron intended for diathermy and other low-power heating applications.

QUICK REFERENCE DATA

Frequency, fixed within the band	f	2,425 to 2,475 GHz
Output power	W_o	200 W
Construction		packaged
Cathode		nickel matrix type

CATHODE: nickel matrix type

HEATING: indirect by a.c. 50 Hz to 60 Hz, or d.c.

	Operation A, B, and D		Operation C
Heater voltage, starting and stand-by	V_f	5,3	4,8 V \pm 10%
Heater current at starting voltage	I_f	3,5	3,3 A
Heater current, peak starting	I_{fp}	max. 8,5	A
Cold heater resistance	R_{fo}	0,2	Ω
Waiting time	t_w min.	180	min. 240 s

TYPICAL CHARACTERISTICS

Measured under matched load conditions (VSWR < 1,05) and d.c. anode voltage.

Frequency, fixed within the band	f	2,425 to 2,475 GHz
Anode voltage, d.c.	V_a	1,55 to 1,70 kV
Anode current	I_a	200 mA

COOLING

a. Low velocity air flow with a rate of flow of 0,4 to 0,5 m³/min. Direction of air flow, see outline drawing. The air flow need not be ducted.

or

b. Heatsink. The tube does not require any extra cooling provided it is effectively mounted on a heat-conducting non-magnetic plate. A vertical position of this plate facilitates the heat transfer.

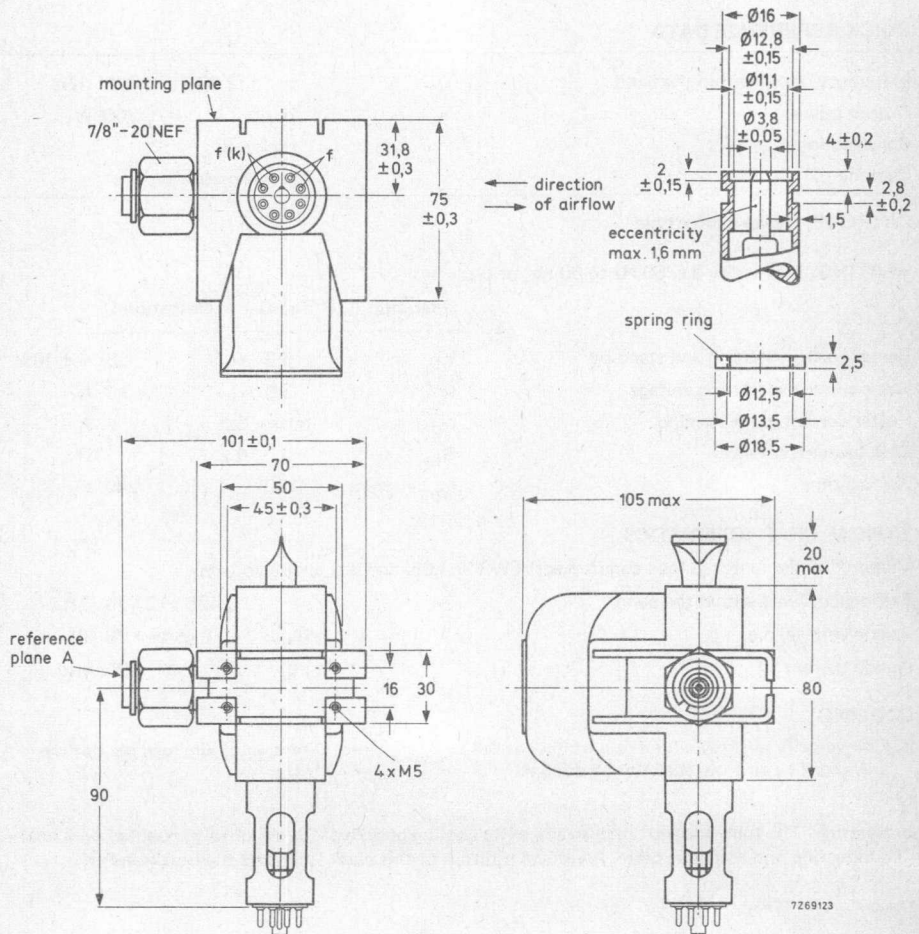
MECHANICAL DATA

Net mass: approx. 2,4 kg

Mounting position: any

Base: octal

The socket for this base should not be rigidly mounted, it should have flexible leads and be allowed to move freely.



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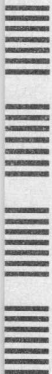
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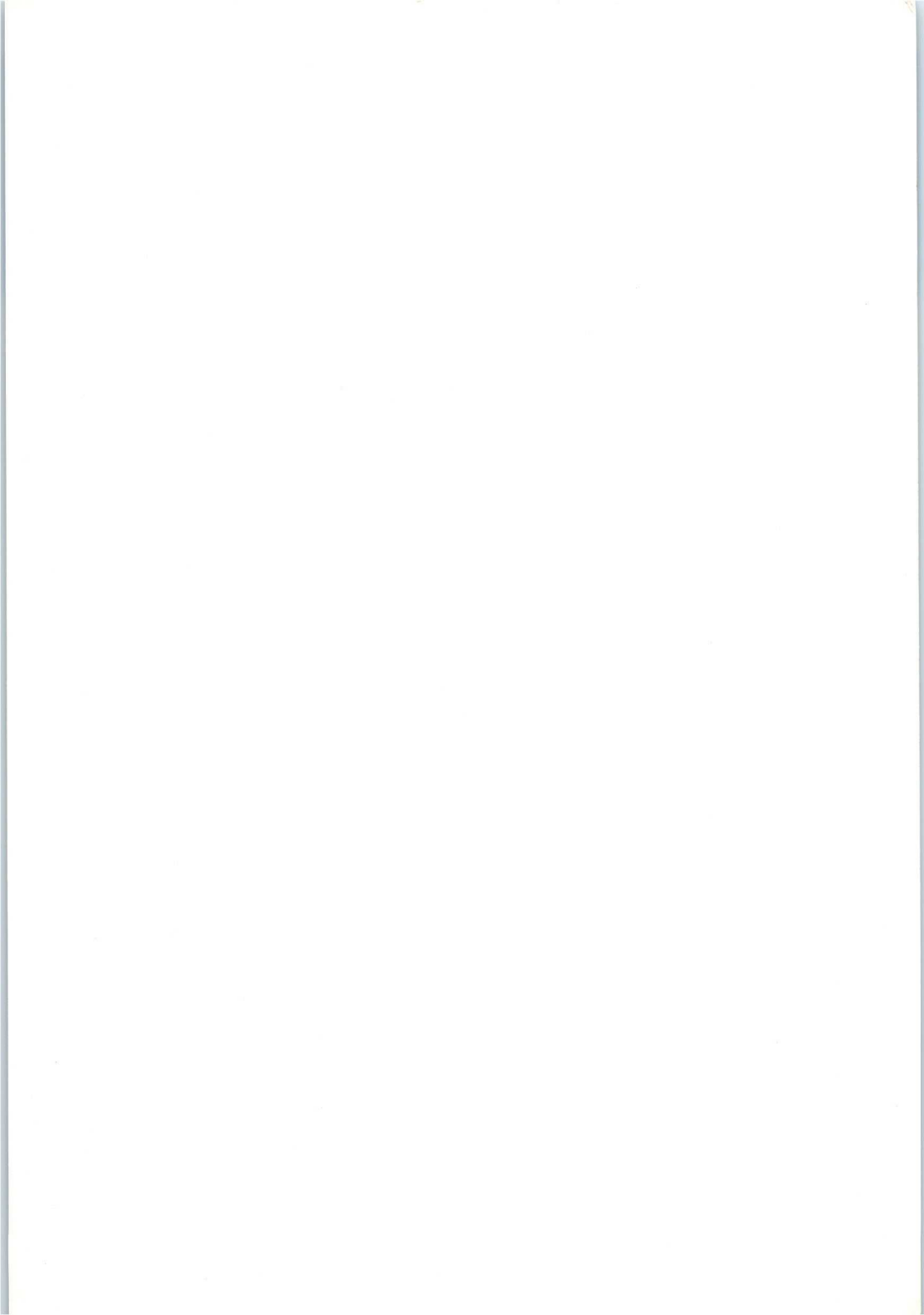
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- Uruguay:** LUZILETRON S.A., Avda Rondeau 1576, piso 5, MONTEVIDEO, Tel. 91 43 21.
- Venezuela:** IND. VENEZOLANAS PHILIPS S.A., Elcoma Dept., A. Ppal de los Ruices, Edif. Centro Colgate, CARACAS, Tel. 36 05 11.